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NAVAL POSTGRADUATE SCHOOL

Monterey, California



THESIS

DETERMINATION OF QUANTITATIVE RELATIONSHIPS BETWEEN SELECTED CRITICAL HELICOPTER DESIGN PARAMETERS

by

Ronald S. Petricka

September 1984

Thesis Advisor:

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Determination of Quantitative Relationships Between Selected Critical Helicopter Design Parameters

by

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Captain, United States Army
B.S., United States Military Academy, 1973

Submitted in partial fulfillment of the requirements for the degree of

MASTER OF SCIENCE IN AERONAUTICAL ENGINEERING

from the

NAVAL POSTGRADUATE SCHOOL September 1984

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A ESTRACT

This thesis determines the relationships of Helicopter design parameters by first depicting graphically all possible pairings of selected design parameter values and then, secondly, depicting graphically respective curve fits for the data point plcts which meet an acceptance criteria. In generating the curve plots, the specific constants of each curve equation are determined, thus allowing the designer the ability to derive quantitatively the values of many of the design parameters heretofore selected by trial and error methods.

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I. INTRODUCTION

The evolution of helicopter design has proceeded far beyond the starting point where design decisions were based on a 'trial and error' criteria. In major helicopter industry, the design process has evolved to a largely technical discipline where, with the noted exceptions of technological breakthroughs which cause a drastic departure from the norm (an example being the Hughes NOTAR, a helicopter without a tail rotor!), a new helicopter design is built by piecing together critical design parameters in a fashion dictated by past successful designs. Those critical design parameters, logically, are determined by the intended user's requirements (e.g., carrying capacity, and mission (scout vs. utility vs. attack)), performance requirements (e.g., speed, climb, and range), and the geometric requirements (e.g., length, and width).

Definite relationships between these critical design parameters (30 have been selected), are frequently unavailable, or unknown, and are not used during the preliminary design process. By examining all possible pairings, or permutations, across a large number of present helicopter designs (10 have been chosen), one could produce equations of curves which would consistently, accurately and quickly produce the quantitative value for the design parameter a designer seeks.

A. CEJECTIVES AND SCOPE

The objective of this thesis is to determine if quantitative relationships exist between the pairings of critical helicopter design parameters. If they do exist, specific

equations of curves, forming a curve fit of the lata, and specific constants, are to be determined.

II. AFPROACE TO THE PROBLEM

Thirty design parameters were selected and a data base was compiled of the values of these design parameters for 10 helicopters. The 10 helicopters chosen were selected purposely to represent a varied mix of single-mission aircraft (utility, heavy utility, scout or observation, and attack), and old and new technology, ranging from the 1950's to the late 1970's, to lend creditability to the resulting relationships for use in any future preliminary relicopter design process. Selected design parameters, and the respective values for each of the chosen helicopters are listed in Appendix A. A planform and abstract picture of each helicopter, for referencing, is contained in the same Appendix. Table 1 is a brief summary which illustrates the diversity of the helicopters chosen to compile the data base for this thesis.

Pairing each parameter singularly against each other yielded 435 permutations at the start of the evaluation. The pairings are referenced by 2 numbers. For example, the pairing number '1-30' pairs the first design parameter, Main Rotor Blade Radius, against the thirtieth design parameter, Maximum Gross Weight. Appendix B contains a complete listing of pairings. A simple data point graph (X vs. Y) was made of each pairing and, for the graphs that showed a clear relationship existed, data points are curve fitted yielding a curve equation with specific constants. Both the singular data points, and the curves, generated from the curve equations, are depicted graphically, reinforcing the closeness of the curve fits, and that a relationship does indeed exist.

TABLE 1
Summary Characteristics of Chosen Helicopters

Military	Weigat	Primary	Year of	Year of	Mission
Designator	Class	Service M	lanufacture	Technology	Purpose
AH653H 653H 6543	Medium Medium Medium Medium Medavy Heavy Headium Headium	USAA UUSSA UUSSA UUSSA UUSSA UUSSA UUSSA UUSSA	19 33 19 69 - 7 8 19 61 - 7 2 19 82 19 79 19 74 19 69 19 81 19 70 - 8 1 19 65 - 7 6		Attack cservation Utility Utility Utility Utility Utility Utility Attack Utility Attack Utility

In addition to original programs, two pre-existing computer programs were used to facilitate the accomplishment of the thesis objective. The data point plots were generated with 'Helicopter Data Display', written by Captain Gary Eishor, USA, [Ref 1], and the curve fit evaluation was accomplished with 'Crvfit', a Hewlett-Packard hand-held computer program, written by Commander Pat Sullivan, USN, [Ref 2]. The 'Helicopter Data Display' graphic output was re-sized to meet the requirements for thesis submission, and the pre-existing data base revised with additions of data from 3 more helicopters, a deletion of 1, and correction of some incorrect data. The 'Crvfit' program was used as is, with an acceptance criteria, called the correlation factor, of .8 cr greater.

III. SOLUTION TO THE PROBLEM

Of the first 435 pairings, 153 were cut from consideration following an initial consultation with Thesis Advisor Frof. Donald Layton based on his own expertise. Those pairings disregarded from further evaluation are indicated by a prefixed "XX" in Appendix B. An example of pairings which were disregarded outright were those involving 'Degree Twist of Blades'. By experience, and verified thru conversations with helicopter company representatives, 'Twist of the Elade' has in the past been decided on by a 'what's on the shelf' selection criteria, thus explaining why some companies produce helicopters predominantly with a -10 degree twist, while others produce helicopters predominantly with a -8 degree twist, or, a 0 degree twist. 282 simple X-Y plcts of the remaining pairings were then generated, with the first number of each pairing designated as the X-abcissa, or horizontal axis, and the second number, as the Y-ordinate, cr vertical axis. Plcts appear in Appendix C and are referenced with figure numbers consistent with the method used to reference the initial pairings (Example: Fig 1-30). The selection for further evaluation for determining curve fits was accomplished by empirically judging whether the data points tended to show that a relationship existed. figures referenced with a suffix 'a' indicate that a relationship does exist and a data point curve fit follows. The two examples are illustrated in Figures 3.1 and 3.2.

The data of the data points plots that were questionable were submitted to the Crvfit program which made the final decision as to whether there was an interrelationship with a resulting program correlation factor of .8 or greater.

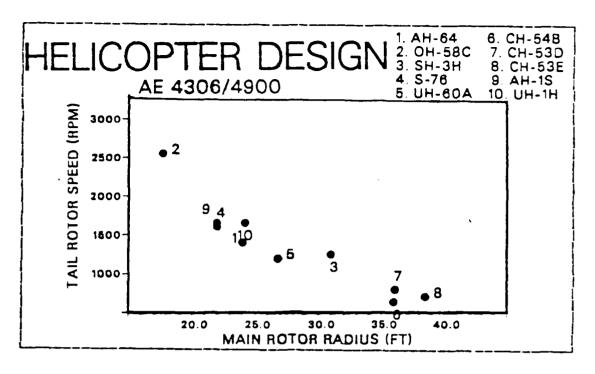


Figure 3.1 Data Fcint Plot Chosen to be Curve Fitted.

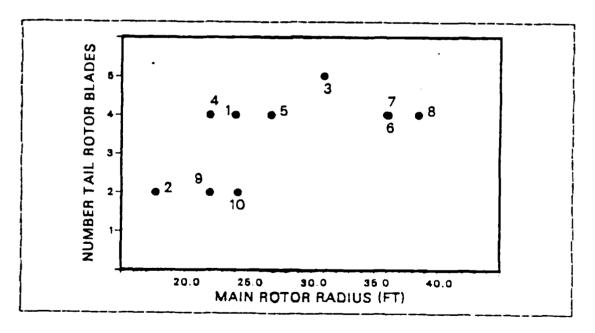


Figure 3.2 Data Point Plot Chosen Not to be Curve Fitted.

At the same time, the 'Crvfit' program determined which of 4 (four) curve types, linear (Type 1), exponential (Type 2), logarithmic (Type 3), or power (Type 4), best fit the data points plotted. An example of one of each of the 4 curves is illustrated in Figures 3.3 through 3.6. Curve fits for the respective pairings, referenced with a suffix 'b', indicating curve fit (Example: Fig 1-30b), and which includes the test curve fit equation, follow their respective data point plots in Appendix C.

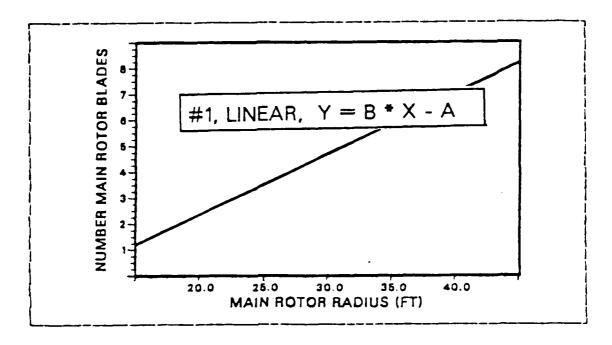


Figure 3.3 Example of Type 1 Curve Fit.

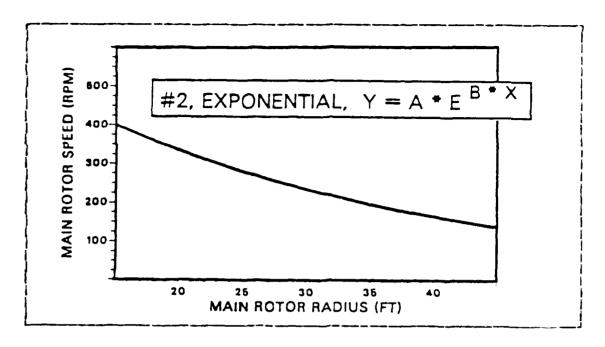


Figure 3.4 Example of Type 2 Curve Fit.

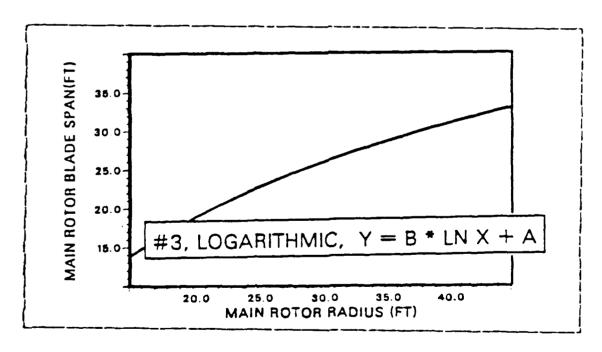


Figure 3.5 Example of Type 3 Curve Fit.

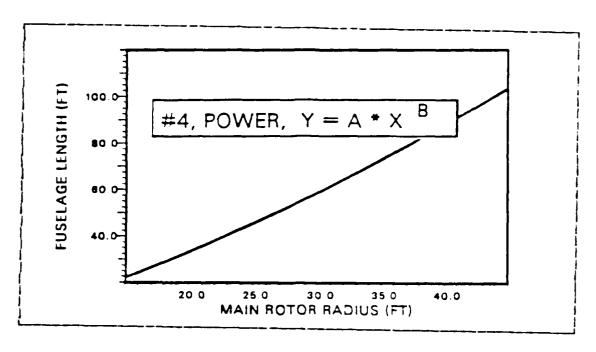


Figure 3.6 Example of Type 4 Curve Fit.

IV. RESULTS AND CONCLUSIONS

282 rairings were evaluated to determine whether an interrelationship existed between the selected design param-185 were determined to produce positive curve fit data which ret or exceeded the chosen correlation factor. Of the 30 design parameters selected for evaluation, the parameters Maximum Grcss Weight and Operating Weight were most interactive, resulting in positive quantitative relationships with 16 other parameters. This is understandable for both parameters are geometric parameters, driven by mission and performance requirements and both influence many of the others. 10 design parameters had no influence, resulting in no relationship with any other parameter. demonstration of the validity of the derived relationships is illustrated as follows where both the curve fit equation, and an alternate method (used in AE 4306 Helicopter Design Manual [Ref 3]), are used to generate specific design parameters of Gross Weight and Tail Rotor Radius. The results are compared to an existing, flying helicopter.

Required: Compute Gross Weight, MGW, as a function of Tail Rotor Radius, RTR, given as 2.6 feet.

Curve Fit - MGW = 324.88 x RTR 23829 = 3166 lbs Equation

AF 4306 - MGW = 591.716 x RTR 2.0 = 4000 lbs Design Manual (Alternate Method)

2.6 feet is the actual tail rotor radius of the OH58C Army Chservation/Scout Helicopter whose actual Gross Weight is 2550 lbs.

By comparison, the curve fit equation generates a value of Gross Weight 24% above actual lesign, whereas the alternate method generates a value 52% above actual design.

Table 2 lists the number of relationships, or the influence of each design parameter upon each other.

TABLE 2
Resultant Relationships of Design Parameters

10 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	H H H H H H H H H H H H H H H H H H H	, ,
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A. CCNCIUSIONS

The objective of this thesis has been achieved by establishing the clear relationships that exist between selected Helicopter design parameters. The curve fit equations that were derived, and the specific constants for each equation, provide the designer, be he professional, in the industry, or student, a means to quantitatively derive values of design parameters that are encountered during the preliminary design process.

Until technological breakthroughs force a drastic departure from the established design norms developed over the last 30 years, the curve fit equations can produce a quantitative, quicker, and more optimum solution than the methods employed to date.

APPENDIX A REFERENCES FOR DATA BASE AND HELICOPTERS

A. SELECTED DESIGN FARAMETERS AND NOMENCLATURE

TABLE 3
Selected Design Parameters and Nomenclature

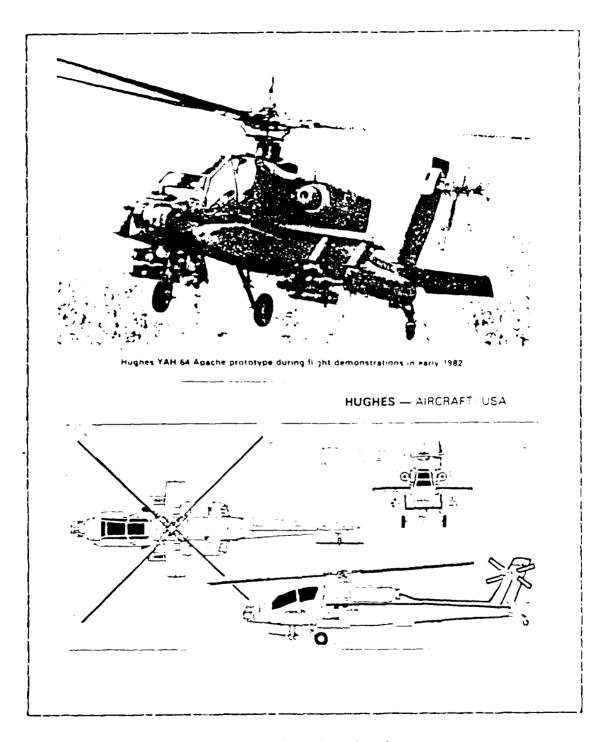
	Selected Design Parameters	Nomenclature
1. 2. 3. 4. 5.	Main Potor Radius (ft) Tail Rotor Radius (ft) Number of Main Rotor Blades Number of Fail Rotor Blades Height of Main Rotor System	E R R R R R R
67890123456	Main Potor Radius (ft) Tail Rotor Radius (ft) Number of Main Rotor Blades Number of Main Rotor System above Ground (ft) Speed of Main Rotor System (rrm) Chord of the Main Rotor (ftt) Span of the Main Rotor Blade (ftt) Span of the Main Rotor Blade (ftt) Span of the Main Rotor Blade (ftt) Twist of Main Rotor Blade (degrees) Twist of Main Rotor Blade (degrees) Profile Drag of Main Rotor Blade Profile Drag of Main Rotor Blade Profile Drag of Main Rotor System (lb/s; ft)	R TH RTH H PAR HOSSO PRECORREDOL PROCORREDOL
13.	Span of the Main Rotor Blade (ft) Span of the Main Rotor Blade (ft) Twist of Main Rotor Blade (degrees) Twist of Tail Rotor Blade (degrees) Profile Drag of Main Rotor Blade Profile Drag of Main Rotor Blade Disc Loading of Main Rotor System (lb/s; ft)	
18.	Length of the Fuselage (it) Length of the Fuselage (it) Frontal Horizontal Flat Plate Area	F D T E E E E E E E E E E E E E E E E E E
20.	Frontal Vertical Flat Plate Area (sq/ft) Takinum Forward Velocity (knots)	F V 7 M
21. 22. 23.	Frontal Vertical Flat Plate Area (sq/ft) Maximum Forward Velocity (knots) Maximum Pange (nm) Rate of Climb, Maximum Continuous Power (ftm)	a C
24.	Power (frm) Hover Ceiling (IGE, in ground effect)	HOVIGE
25.	Hover Ceiling (CGE, out of ground effect)	HOVIGE
26. 27. 22. 29. 30.	Length of Tail (ft) Cperating Weight (lb) Load Weight (lb) Fuel Weight (lb) Maximum Gross Weight (lb)	FOTTOR HERED JOHNS

E. SELECTED DESIGN FARAMETER VALUES

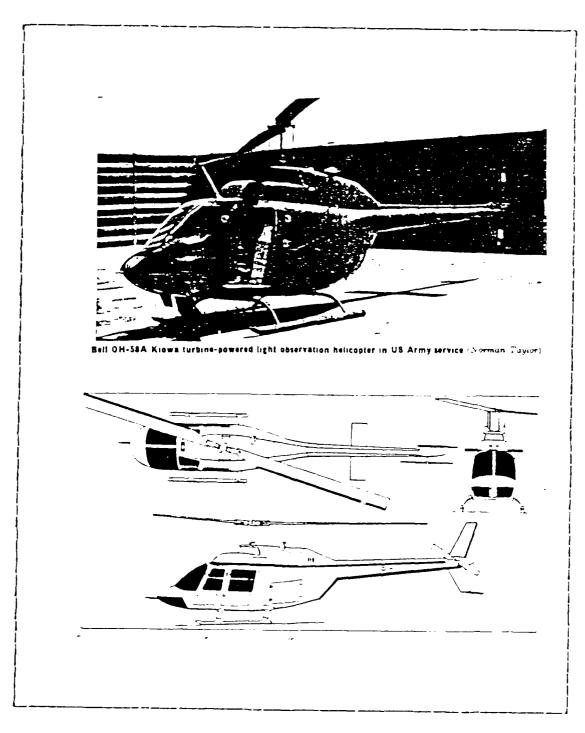
TABLE 4
Selected Design Parameter Values

នុក្ខ	Summary of	f Cesign	Pat	aneter	Values	2	i			
	AHÓ4	он5вс	SH3H	s 7 to	UHEOA	CH542	CH5 3 L	L 85 3c	A 11 1 5	J 11 1 H
Lain notor fadius (ft)	24.	17.71	31.	22.	B.a.	36.0	36.1	3.81	0.77	7.4.
2. Tail Rotor Radius (ft)	9-4	2.6	5.3	4.0	5.5	8.0	გ. ე	10.0	4.25	4.25
3. Number Main Potor Blades	7	7	5	7	3	9	9	7	~,	۲.
4. Number Tail Rotor Blades	7	2	5	3	3	7	37	-7	7	
L 2	12.6	3.6	14.3	0.01	11.2	17.6	15.8	10.0	12.2	13.1
11	583	354	203	293	258	185	185	179	7.1	324
7. Speel of Tail Rotor System	7.	2.55	1.24	1.01	1.19	.631	757	669.	50-	1.65
	1.75	1.38	1.52	1. 29	1.75	1.97	2.17	2.44	5.5	1.75
9.Chord of Tail Rotor (ft)	€8.	777	.61	₽6.	18.	1.28	1.28	1.28	. 6.	. 70
10. Span Hain Rotor Blade (ft)	13.8	16.2	29.3	25.3	23.3	3.67	6.85	38.c	18.9	22.0
11. Span Tail Botor Blade (ft)	3.1	2.3	0-4	3.3	4.25	5 h • a	54.0	6.53	3.9	3.8
of Main	6-	-10.6	R-	- 13	- 18	8-	9-	- 13. C	- 13	-10
25.	-8.8	0.0	0.0	- 8	- 18	- 8	e -	8-	င	0
14. Profile Drag of Main Rotor	600.	600.	600.	600.	.003	3500.	3600.	600.	b.6.	.008
15. Profile Drag of Tail Rotor	600-	9600.	.0105	. 015	. ឋិបិមិ	3010.	3 900.	3500.	110.	.011
To Disc Loading of Main Rotor	н Г.	4.c8	96.9	6.58	8.95	10.3	10.3	15.0	15.3	5. 25
17.Width of Fuselage (ft)	3.96	4.57	7.08	7.0	7.75	7.08	9.43	3. B.s	11.7	a 0
नेद्र :	1.64	23.0	55.2	43.4	50.1	70.2	01.2	95.0	T) 7	7
13. Frontal Horizontal Flat	8°5ħ	13.0	31.2	11.0	1.57	0.84	47.3	t 3.t	8.22	19.3
2). Frontal Vertical Flat	34.7	15.3	36.0	0.08	30.8	h . 66	90.0	153.	17.0	C
21. Maximum Forward Velocity	154	116	120	155	156	110	164	140	19.0	1:0
22. Hikiman Bange (nm)	246	3.30	505	434	275	007	245	4 13	017	997
23. Rate of Climb (1000 fpm)	3.88	1.42	1:31	1. 35	5#.	1.1	81	51	1.62	1.6
24. Hover Celling (IGE, 1000 ft)	14.2	7.1	3.7	6.2	8 · /	6.9	14.0	6.3	12.2	5.7
25.80ver Ceiling (0GP, 1000 ft)	11.02	4.2	4.3	2.8	3.9	2.4	р-я	7,	5.3	0.7
20. Length of Tail (ft)	29.7	15.2	30.0	30.5	5.11	5 " 5 15	5.44	48.1	7.15	6.65
-7. operating Weight (1000 1bs)	70-11	1.155	13.6	5.0	10.68	19.23	13.03	11.23	6.0.0	5.21
28.1543 Weight (1000 11s)	120.7	386.	1.759	2.517	1.220	14.19	14.33	24.79	1.04	5. 99 . 7
23.Fuel Worght (1000 lts)	1.624	7	5.041	1.833	2.345	р , я	4.338	15.48	1.76	14, 26
30. Max Gross Wellat (1900 lbs)	14.0	2.55	0.12	10.0	20.25	12.0	42.0	13.5	19.3	3.5

C. HELICOPTER PLANFORMS AND PICTURES



Pigure A. 1 AB64 Planform.



Pigure A.2 OH58C Planform.

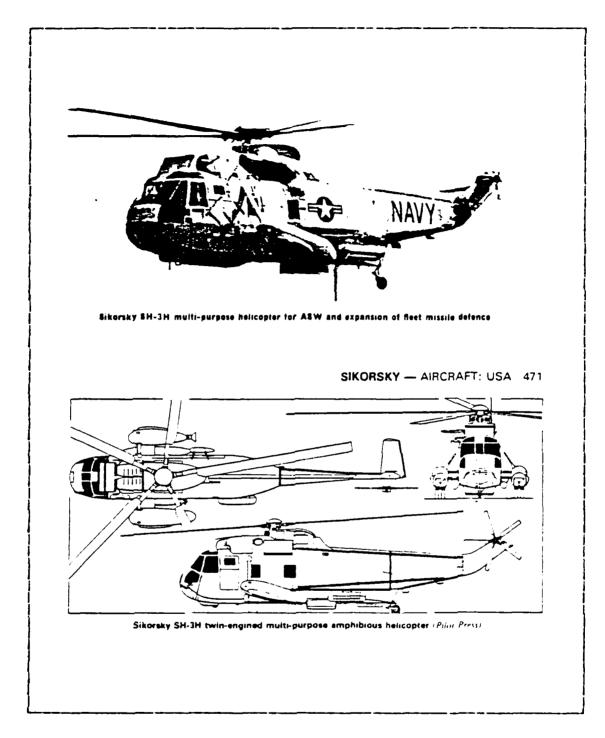


Figure A.3 SH-3H Planform.

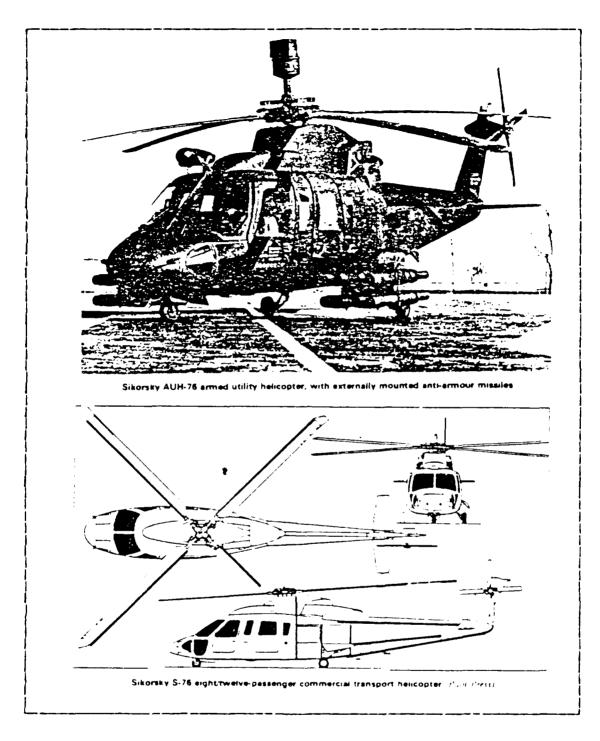


Figure A. 4 S-76 Planform.

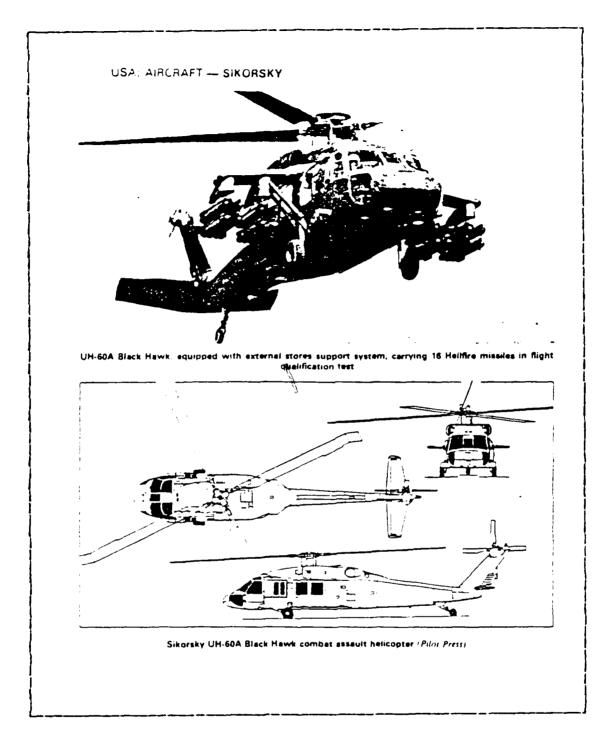
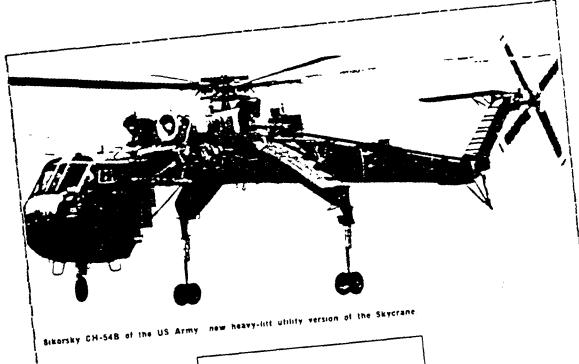
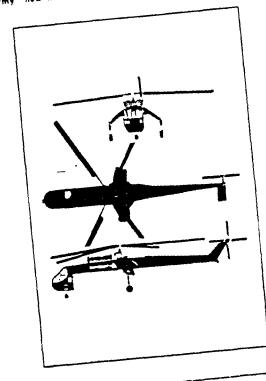
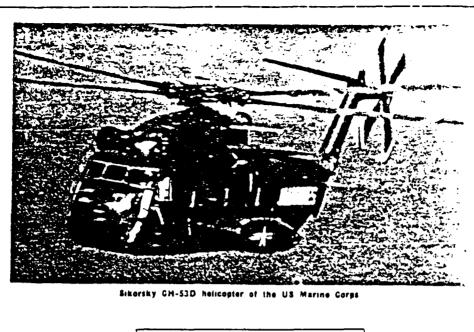


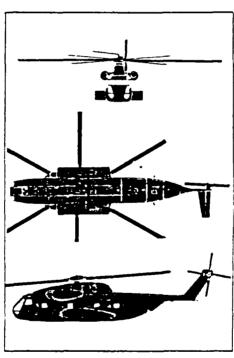
Figure A.5 UH-60A Planform.



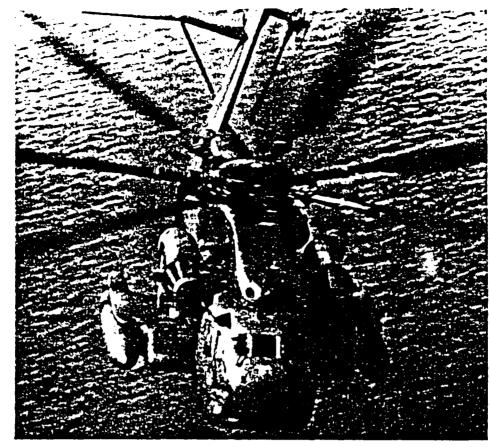


Pigure A.6 CH-54B Planfora.

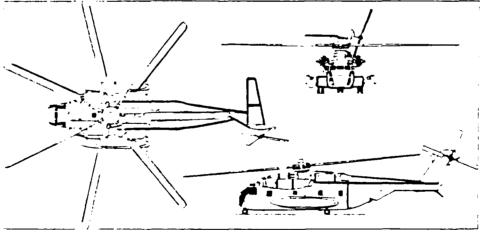




Pigure A.7 CH-53D Planform.



Sikorsky CH-53E Super Stallion heavy-lift helicopter (three General Electric T64-GE-416 turboshaft engines)



Sikorsky CH-53E Super Stallion heavy-lift helicopter (Pilor Press)

Pigure A.8 CH-53E Planform.

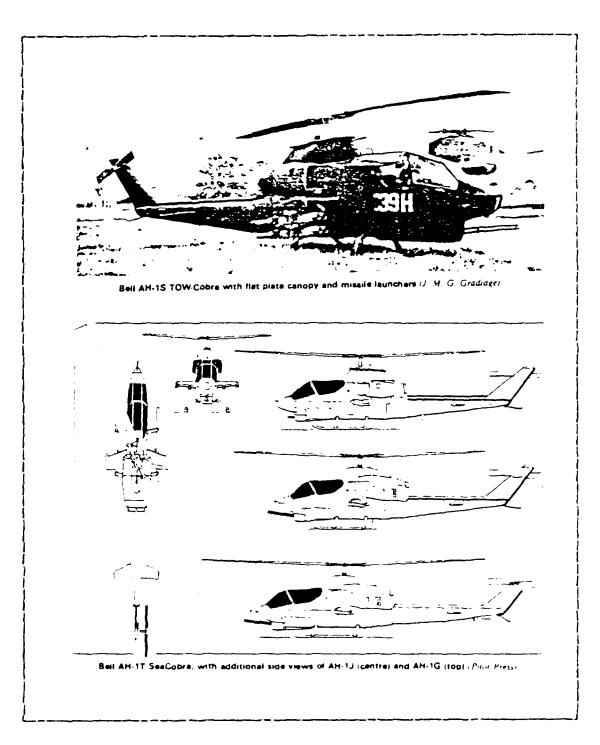
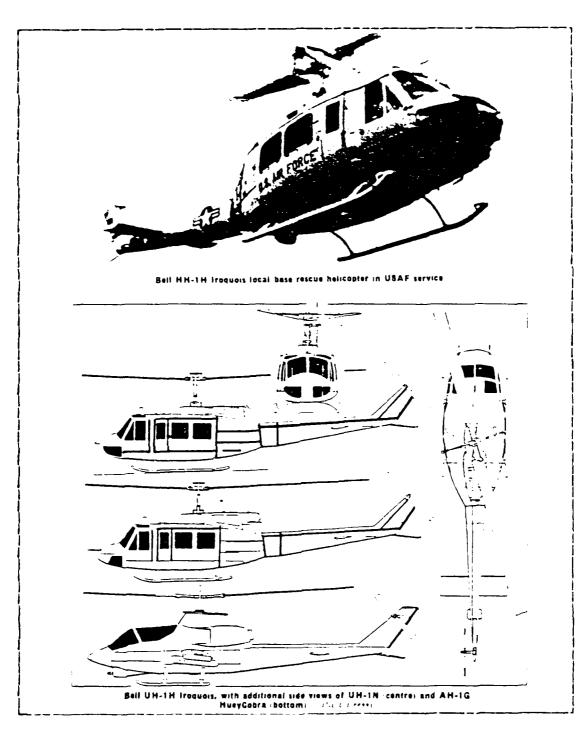


Figure A.9 AH-1S Planform.



Pigure A.10 UH-18 Planform.

APPENDIX 3

CRITICAL DESIGN PARAMETER PAIRINGS AND REFERENCE SYSTEM

TABLE 5

Main Rotor Radius Pairings

- 1 MAIN ROTOR ELADE RADIUS IN FEET 2 - TAIL FOTOR ELADE RADIUS IN FEET
- 1 MAIN ROTOR BLADE RADIUS IN FEET 3 - NUMBER OF MAIN ROTOR BLADES
- 1 MAIN ROTOR BLADE RADIUS IN FEET
- 1 MAIN ROTOR BLADE RADIUS IN FEET 5 - HEIGHT OF MAIN ROTOR SYSTEM ABOVE GROUND IN FEET
- 1 MAIN ROTOR BLADE RADIUS IN FEET 6 - SPEED OF MAIN ROTOR SYSTEM IN RPM
- 1 MAIN ROTOR BLADE RADIUS IN FEET 7 - SPEED OF TAIL FOTOR SYSTEM IN RPM
- 1 MAIN ROTOP BLADE RADIUS IN FEET 8 - CHORD OF MAIN FOTUR BLADE IN FEET
- 1 MAIN RCTOR BLADE RADIUS IN FEET 9 - CHOPD OF TAIL FOTOR BLADE IN FEET
- 1 MAIN ROTOF BLADE RADIUS IN FEET 10 - SPAN OF MAIN ROTOR BLADE IN FEET
- 1 ANTH DOTOR DIAGR CASTES IN FERT
- 1 MAIN BOTOR BLADE RADIUS IN FEET 11 - SPAN OF TAIL RUTOR BLADE IN FEET
- 1 MAIN FOTOR ELADE RADIUS IN FEET 12 - TWIST OF MAIN FOTOR BLADE IN DEGREES
- AX 1 MAIN ROTOR ELADE EADIUS IN FEET 13 - THIST OF TAIL ROTOR BLADE IN DEGREES
 - 1 MAIN ROTOR BLADE RADIUS IN FEET 14 - PEDFILE DRAG OF MAIN ROTOR BLADE
- XX 1 MAIN FOTOR ELADE FADIUS IN FEET 15 - PROFILE DRAG OF TAIL FOTOR ELADE
- (C) 1 MAIN ECTOR BLADE RADIUS IN FEET 16 - DISC LOADING OF THE MAIN ECTOR SYSTEM
- XX 1 MAIN ECTOR BLADE FADIUS IN FEET 17 WIDTH OF THE FUSEIAGE IN FEET

- 1 MAIN ROTOF BLADE RADIUS IN FEET 18 - LENGTH OF THE FUSELAGE IN FEET
- 1 MAIN ROTOR BLADE RADIUS IN FEET 19 - FRONTAL FLAT PLATE AREA IN SQUARE FEET
- 1 MAIN ROTOR BLADE RADIUS IN FEET 20 - VERTICAL FLAT PLATE AREA IN SQUARE FEET
- 1 MAIN ROTOR BLADE RADIUS IN FEET 11 - MAIN MUNICIPOLITY IN ANOTS
- 1 MAIN ROTOR BLADE HADIUS IN FEET 22 - MAXIMUM RANGE IN NAUTICAL MILES
- 1 MAIN ROTOR BLADE RADIUS IN FRET 23 - RATE OF CLIMB IN FRET PER MINUTE, MAKIMUM CONTINUOUS POWER
- 1 MAIN ROTOR BLADE RADIUS IN FEET 24 - HOVER CEILING (IN GROUND FIFECT) IN FEET
- 1 MAIN ROTOR ELADE RADIUS IN FEET 25 - HOVER CEILING (CUT OF GROUND EFFECT) IN FEET
- 1 MAIN ROTOR BLADE RADIUS IN FEET 26 - LENGTH OF THE TAILBOOM IN FEET
- 1 MAIN ECTOR BLADE PADIUS IN FEET 27 - OPERATING WEIGHT IN POUNDS
- 1 MAIN ROTOR BLADE RADIUS IN FEET 28 - LOAD WEIGHT IN POUNDS
- 1 MAIN ROTOR BLADE FADIUS IN FEET 29 - FUEL WEIGHT IN POUNDS
- 1 MAIN FOTOR BLADE BADIUS IN FEET BU - MAXIMUM GROSS WEIGHT IN POUNDS

TABLE 6
Tail Rotor Radius Pairings

- XX 2 TAIL ROTOR BLADE RADIUS IN FEET 3 - NUMBER OF MAIN ROTOR BLADES
 - 2 TAIL ROTOR BLADE BADIUS IN FEET 4 - NUMBER OF TAIL FOTOR BLADES
- XX 2 TAIL ROTOR BLADE RADIUS IN FEET 5 HEIGHT OF MAIN ROTOR SYSTEM ABOVE GROUND IN FEET
- XX 2 TAIL ROTOR BLADE BADIUS IN FEET 6 - SPEED OF MAIN FOTOR SYSTEM IN REM
 - 2 TAIL ROTOR BLADE RADIUS IN FEET 7 - SPEED OF TAIL ROTOR SYSTEM IN RPM
- XX 2 TAIL ROTOR BLADE RADIUS IN FEET
 8 CHORD OF MAIN ROTOR BLADE IN FEET
 - 2 TAIL ROTOR BLADE FADIUS IN FEET 9 - CHORD OF TAIL ROTOR BLADE IN FEET
- XX 2 TAIL ECTOR ELADE RADIUS IN FEET 10 SPAN OF MAIN ROTOR BLADE IN FEET
 - 2 TAIL ECTOR BLADE FADIUS IN FEET 11 - SPAN OF TAIL ECTOR BLADE IN FEET
- XX 2 TAIL ROTOR BLADE RADIUS IN FEET 12 TWIST OF MAIN POTOR BLADE IN DEGREES
 - 2 TAIL ROTOR BLADE PADIUS IN FEET 13 - TVIST OF TAIL FOTOR BLADE IN DEGREES
- XX 2 TAIL FOTOR BLADE RADIUS IN FELL 1 14 - PROFILE DRAG OF MAIN ROTOR ELADE
 - 2 TAIL BOTOR BLADE RADIUS IN FEET 15 - PROFILE DRAG OF TAIL ROTOR BLADE
 - 2 TAIL ROTOR BLADE HADIUS IN FEET 16 - DISC LOADING OF THE MAIN ROTOR SYSTEM
- KK 2 TAIL BOTOR BLADE RADIUS IN FEET 17 WIDTH OF THE FUSELAGE IN FEET
- XC 2 TAIL ROTOR BLADE RADIUS IN FEET 18 LENGTH OF THE FUSELAGE IN FEET

- AX 2 TAIL ECTOR BLADE PADIUS IN FEIT 19 FRONTAL FLAT PLATE AREA IN SQUARE FEET
- XX 2 TAIL ROTOR BLADE RADIUS IN FEET 20 VERTICAL FLAT PLATE AREA IN SQUARE FEET
 - 2 TAIL ECTOR BLADE RADIUS IN FEET 21 MAXIMUM VELOCITY IN KNOTS
- XX 2 TAIL BOTOK BLADE RADIUS IN FEET 22 MAKIMUM RANGE IN NAUTICAL MILES
 - 2 TAIL ROTOR BLADE RADIUS IN FEET 23 RATE OF CLIMB IN FEET PER MINUTE, MAXIMUM CONTINUOUS POWER
 - 2 TAIL FOTOR ELADE FADIUS IN EEET 24 HOVER CEILING (IN GROUND EFFECT) IN FEET
 - 2 TAIL ROTOR BLADE RADIUS IN FEET 25 - HOVER CEILING (CUT OF GROUND EFFECT) IN FEET
 - 2 TAIL ROTOR BLADE RADIUS IN FEET 20 - LENGTH OF THE TAILBOOM IN FEET
 - 2 TAIL ROTOR ELADE RADIUS IN FEET 27 OPERATING WEIGHT IN POUNDS
 - 2 TAIL ROTOR BLADE RADIUS IN FEET 28 LOAD WEIGHT IN POUNDS
- XX 2 TAIL ROTOR ELADE RADIUS IN FEET 29 FUEL WEIGHT IN POUNDS
 - 2 TAIL ROTOR BLADE HADIUS IN FEET 30 - MAXIMUM GROSS WEIGHT IN POUNDS

TABLE 7 Number of Main Botor Blades Pairings

- NUMBER OF MAIN FOTOR BLADES
 NUMBER OF TAIL BOTOR BLADES
- 3 NUMBER OF MAIN ROTOR BLADES 5 - HEIGHT OF MAIN ROTOR SYSTEM ABOVE GROUND IN FEET
- 3 NUMBER OF MAIN RCTOR BLADES 6 - SPEED OF MAIN FOTOR SYSTEM IN RPM
- 3 NUMBER OF MAIN ROTOR BLADES 7 - SPEED OF TAIL ROTOR SYSTEM IN RPM
- 3 NUMBER OF MAIN FOTOR BLADES 8 - CHORD OF MAIN FOTOR BLADE IN FEET
- XX 3 NUMBER OF MAIN ROTOR BLADES 9 - CHORD OF TAIL ROTOR BLADE IN FEET
 - 3 NUMBER OF MAIN BOTOR BLADES 10 - SPAN OF MAIN BOTOR BLADE IN FEET
- AK 3 NUMBER OF MAIN ROTCH BLADES
 11 SPAN OF TAIL BOTCH BLADE IN FRET
 - 3 NUMBER OF MAIN ROTOR BLADES 12 - TWIST OF MAIN ROTOR BLADE IN DEGREES
- XX 3 NUMBER OF MAIN SCTOR BLADES
 13 TWIST OF TAIL BOTOR BLADE IN LEGREES
 - 3 NUMBER OF MAIN ROTOR BLADES 14 - PROFILE DRAG OF MAIN ROTOR ELADE
- XX 3 NUMBER OF MAIN ROTOR BLADES
 15 PROFILE DRAG OF TAIL ROTOR BLADE
 - 3 NUMBER OF MAIN FOTOR BLADES 16 - DISC LOADING OF THE MAIN ROTOR SYSTEM
 - 3 NUMBER OF MAIN ROTOR BLADES 17 - WIDTH OF THE FUSELAGE IN FEET
 - 3 NUMBER OF MAIN ROTOR BLADES 18 - LENGTH OF THE FUSELAGE IN FEET
 - 3 NUMBER OF MAIN ROTOR BLADES 19 - FROMTAL FLAT PLATE AREA IN SQUARE FEET

- XX 3 MUMBER OF MAIN BOTCE BLADES 20 - VERTICAL FLAT BLATE AREA IN SQUAR E FEET
 - 3 JUMBER OF MAIN ROTOR BLADES 21 - MAXIAUM VELOCITY IN KNOTS
 - 3 NUMBER OF MAIN BOTOR BLADES 22 - MAXIMUM RANGE IN MAUTICAL MILES
 - NUMBER OF MAIN FOTOR BLADES - BATE OF CLIMB IN FEET PER MINUTE, MAXIMUM CONTINUOUS POWER
 - 3 NUMBER OF MAIN FOTOR ELADES 24 - HOVER CEILING (IN GROUND EFFECT) IN FEET
 - 3 NUMBER OF MAIN ROTOR BLADES 25 - HOVER CEILING (CUT OF GROUND EFFECT) IN FEET
 - 3 NUMBER OF MAIN ROTOR BLADES 26 - LENGTH OF THE TAILBOOM IN FEET
 - 3 NUMBER OF MAIN FOTOR BLADES 27 - OPERATING WEIGHT IN POUNDS
 - 3 NUMBER OF MAIN SOTOR BLADES 28 - LOAD WEIGHT IN POUNDS
 - 3 NUMBER OF MAIN FOTOR BLADES 29 - FUEL WEIGHT IN POUNDS
 - 3 NUMBER OF MAIN ROTOR BLADES 30 - MAYIMUM GROSS WEIGHT IN POUNDS

TABLE 8 Number of Tail Rotor Blades Pairings

NUMBER OF TAIL ROTOR BLADES HEIGHT OF MAIN ROTOR SYSTEM ABOVE GROUND IN FEET XX- NUMBER OF TAIL ROTOR BLADES - SPEED OF MAIN FOTOR SYSTEM IN RPM NUMBER OF TAIL ROTOR BLADES SPEED OF TAIL ROTOR SYSTEM IN RPM NUMBER OF TAIL FOTOR BLADES CHORD OF MAIN FOTOR BLADE IN FEET XXNUMBER OF TAIL ROTOR BLADES
CHORD OF TAIL ROTOR BLADE IN FEET 4 - NUMBER OF TAIL FOTOR BLADES 10 - SPAN OF MAIN ROTOR BLADE IN FEET 4 - NUMBER OF TAIL ROTOR BLADES 11 - SPAN OF TAIL ROTOR BLADE IN FEET 4 - NUMBER OF TAIL FOTOR BLADES 12 - TWIST OF MAIN ROTOP BLADE IN DEGREES NUMBER OF TAIL FOTOR BLADES
TWIST OF TAIL FOTOR BLADE IN DEGREES 4 - NUMBER OF TAIL FOTOR BLADES 15 - PROFILE DRAG OF TAIL ROTOR FLADE 4 - NUMBER OF TAIL ROTOR BLADES 16 - DISC LOADING OF THE MAIN ROTOR SYSTEM 4 - NUMBER OF TAIL ROTOR BLADES 17 - WIDTH OF THE FUSELAGE IN FEET 4 - NUMBER OF TAIL ROTOR BLADES 18 - LENGIH OF THE FUSILAGE IN FEET 4 - NUMBER OF TAIL ROTOR BLADES 19 - FRONTAL FLAT PLATE AREA IN SQUARE FEET 4 - NUMBER OF TAIL BOTOR BLADES 20 - VERTICAL FLAT PLATE AREA IN SQUARE FEET

- 4 NUMBER OF TAIL ROTOR BLADES 21 MAKIMUM VEICCITY IN KNOTS
- 4 NUMBER OF TAIL ROTOR BLADES 22 MAKIMUM RANGE IN NAUTICAL MILES
- 4 WUMBER OF TAIL ECTOR BLADES 23 RATE OF CLIMB IN FEET PER MINUTE, MAKIMUM CONTINUOUS POWER
 - 4 NUMBER OF TAIL ROTOR BLADES 24 HOVER CEILING (IN GROUND EFFECT) IN FEET
 - NUMBER OF TAIL ROTOR BLADES
 HOVER CEILING (CUT OF GROUND EFFECT)
 IN FEET
 - 4 NUMBER OF TAIL ROTOR BLADES 26 LENGTH OF THE TAILBOOM IN FEET
 - NUMBER OF TAIL ROTOR BLADES OPERATING WEIGHT IN POUNDS
 - NUMBER OF TAIL ROTOR BLADES LOAD WEIGHT IN POUNDS

 - NUMBER OF TAIL ROTOR BLADES FUEL WEIGHT IN POUNDS
 - 4 NUMBER OF TAIL ROTOR BLADES 30 MAXIMUM GROSS WEIGHT IN POUNDS

Height of Main Rotor System Pairings

- HEIGHT OF MAIN ROIOR SYSTEM ABOVE GROUND IN FEET SPEED OF MAIN ROTOR SYSTEM IN RPM
- HELSHT OF MAIN FOTOR SYSTEM ABOVE SROUND IN FEET SPEED OF TAIL ROTOR SYSTEM IN RPM

 - HEIGHT OF MAIN ROTOR SYSTEM ABOVE GROUND IN FEET CHORD OF MAIN FOTOR BLADE IN FEET
- HEIGHT OF MAIN ROTOR SYSTEM ABOVE GROUND IN FEET CHORD OF TAIL ROTOR BLADE IN FEET XX
- 5 HEIGHT OF MAIN BOTOR SYSTEM ABOVE GROUND IN FEET
 10 SPAN OF MAIN BOTOR BLADE IN FEET
- 5 HEIGHT OF MAIN FOTOR SYSTEM ABOVE SKOUND IN FEET
 11 SPAN OF TAIL ECTOR BLADE IN FEET
- 5 HEIGHT OF MAIN ROTOR SYSTEM ABOVE GROUND IN FEET
 12 TWIST OF MAIN ROTOR BLADE IN DEGREES
- XX
- 5 HEIGHT OF MAIN ROTOR SYSTEM ABOVE GROUND IN FEET
 13 TWIST OF TAIL ROTOR BLADE IN DEGREES
 - HEIGHT OF MAIN ROTOR SYSTEM ABOVE GROUND IN FEET
 PROFILE DRAG OF MAIN ROTOR BLADE
- 5 HEIGHT OF MAIN ROTOR SYSTEM ABOVE GROUND IN FEET 15 PROFILE DRAG OF TAIL ROTOR ELADE ΣX
 - - HEIGHT OF MAIN ROTOR SYSTEM ABOVE GROUND IN FEET DISC LCADING OF THE MAIN BOTOR SYSTEM

 - HEIGHT OF MAIN ROTOR SYSTEM ABOVE GROUND IN FEET
 WIDTH OF THE FUSELAGE IN FEET

 - HEIGHT OF MAIN ROTOR SYSTEM ABOVE GROUND IN FEET
 LENGTH OF THE FUSELAGE IN FEET
 - HEIGHT OF MAIN SOTOR SYSTEM ABOVE GROUND IN FEET FRONTAL FLAT PLATE AREA IN SQUARE FEET

 - HEIGHT OF MAIN ROTOR SYSTEM ABOVE FROUND IN FEET VERTICAL FLAT PLATE AREA IN SQUARE FEET
 - HEIGHT OF MAIN ROTOR SYSTEM ABOVE GROUND IN FEET MAXIMUM VELOCITY IN KNOTS

- HEIGHT OF MAIN FOICE SYSTEM ABOVE GROUND IN FEET MAXIMUM RANGE IN NAUTICAL MILES X X

 - HEIGHT OF MAIN ROTOR SYSTEM ABOVE GROUND IN FEET RATE OF CLIMB IN FEET PER MINUTE, MAKIMUM CONTINUOUS POWER 23
 - 5
 - HEIGHT OF MAIN ROTOR SYSTEM ABOVE GROUND IN FEET HOVER CEILING (IN GROUND EFFECT) IN FEET
 - 5
 - HEIGHT OF MAIN ROTOR SYSTEM ABOVE GROUND IN FEET HOVER CEILING (CUT OF GROUND EFFECT) IN FEET
 - HEIGHT OF GROUND IN LENGTH OF MAIN ROTOR SYSTEM ABOVE FEET THE TAILBOOM IN FEET

 - HEIGHT OF GROUND IN OPERATING MAIN SCTOR SYSTEM ABOVE FEET WEIGHT IN POUNDS

 - HEIGHT OF MAIN ROTOR SYSTEM ABOVE GROUND IN FEET LOAD WEIGHT IN POUNDS
 - 28
- HEIGHT OF MAIN HOTOR SYSTEM ABOVE GROUND IN FEET FUEL WEIGHT IN POUNDS

 - HEIGHT OF MAIN ROTOR SYSTEM ABOVE GROUND IN FEET MAXIMUM GROSS WEIGHT IN POUNDS
 - 30

TABLE 10
Speed of Main Rotor Pairings

- 6 SPEED OF MAIN BOTOR SYSTEM IN RPM 7 - SPEED OF TAIL ROTOR SYSTEM IN RPM
- 6 SPEED OF MAIN FOTOR SYSTEM IN RPM 8 - CHORD OF MAIN ROTOR BLADE IN FEET
- XX 6 SPEED OF MAIN ROTOR SYSTEM IN RPM 9 - CHORD OF TAIL ROTOR BLADE IN FEET
 - 6 SPEED OF MAIN FOTCH SYSTEM IN RPM 10 - SPAN OF MAIN ROTOR BLADE IN FEET
- XX 6 SPEED OF MAIN ROTOR SYSTEM IN RPM 11 - SPAN OF TAIL ROTOR BLADE IN FEET
 - 6 SPEED OF MAIN FOTOR SYSTEM IN RPM 12 - TWIST OF MAIN FOTOR BLADE IN DEGREES
- XX 6 SPRED OF MAIN ROTOR SYSTEM IN RPM 13 - TWIST OF TAIL FOTOR BLADE IN DEGREES
 - 6 SPEED OF MAIN ROTOR SYSTEM IN ROM 14 - PROFILE DRAG OF MAIN ROTOR ELADE
- XX 6 SPEED OF MAIN ROTOR SYSTEM IN RPM 15 - PROFILE DRAG OF TAIL ROTOR ELADE
 - 6 SPEED OF MAIN ROTOR SYSTEM IN RPM 16 - DISC LOADING OF THE MAIN ROTOR SYSTEM
- XX 6 SPEED OF MAIN FOTOR SYSTEM IN REM
 - 6 SPEED OF MAIN ROTOR SYSTEM IN RPM 18 - LENGTH OF THE FUSELAGE IN FERT
 - 6 SPEED CF MAIN FOTCR SYSTEM IN RPM 19 - FRONTAL FLAT PLATE AREA IN SQUARE FEET
 - 6 SPEED OF MAIN FOTOR SYSTEM IN RPM 20 - VERTICAL FLAT PLATE AREA IN SOUARE FEET
 - 6 SPEED OF MAIN ROTOR SYSTEM IN RPM 21 - MAXIMUM VELOCITY IN KNOTS
- XX 6 SPEED OF MAIN BOTCE SYSTEM IN RPM 22 - MAXIMUM RANGE IN NAUTICAL MILES

- SPEED OF MAIN ROTOR SYSTEM IN RPM 23 - RAID OF CLIMB IN FEET PER MINUTE, MAKIMUM CONTINUOUS POWER
- 0 SPEED OF MAIN ROTOR SYSTEM IN RPM 24 - HOVER CEILING (IN GROUND EFFECT) IN FEET
- 6 SPEED OF MAIN BOTCH SYSTEM IN RPM 25 - HOVER CEILING (CUT OF GROUNT EFFECT) IN FEET
- XY 6 SPEED OF MAIN ROTOR SYSTEM IN RPM 26 - LENGTH OF THE TAILBOOM IN FEET
 - 6 SPEED OF MAIN ROTOR SYSTEM IN RPM 27 OPERATING WEIGHT IN POUNDS
 - 6 SPEED OF MAIN FOTOR SYSTEM IN RPM 28 - LOAD WEIGHT IN POUNDS
- XX 6 SPEED OF MAIN ROTOR SYSTEM IN RPM 29 - FUEL WEIGHT IN POUNDS
 - 6 SPEED OF MAIN FOTOR SYSTEM IN RPM 30 - MAXIMUM GROSS WEIGHT IN POUNDS

TABLE 11 Speed of Tail Rotor Radius Pairings

- XX 7 SPEED OF TAIL POTOR SYSTEM IN RPM 8 - CHORD OF MAIN FOTOR BLADE IN FEET
 - 7 SPEED OF TAIL POTOR SYSTEM IN REM 9 - CHORD OF TAIL BOTOR BLADE IN FEET
- XX 7 SPEED OF TAIL BOTOR SYSTEM IN RPM 10 - SPAN OF MAIN ROTOR BLADE IN FEET
 - 7 SPEED OF TAIL ROTOR SYSTEM IN RPM 11 - SPAN OF TAIL ROTOR BLADE IN FEET
- XX 7 SPEED OF TAIL FOTOR SYSTEM IN REM 12 - TWIST OF MAIN FOTOR BLADE IN DEGREES
 - 7 SPEED OF TAIL ROTOR SYSTEM IN RPM 13 - TWIST OF TAIL ROTOR BLADE IN DEGREES
- XX 7 SPEED OF TAIL ROTOR SYSTEM IN EPM
 14 PROFILE DEAG OF MAIN ROTOR ELADE
 - 7 SPEED CF TAIL FOTCR SYSTEM IN RPM 15 - PROFILE DRAG OF TAIL ROTOR ELADE
 - 7 SPEED OF TAIL ROTOR SYSTEM IN RPM 16 - DISC LOADING OF THE MAIN ROTOR SYSTEM
- XX 7 SPEED OF TAIL ROTCE SYSTEM IN EPM 17 - WIDTH OF THE FUSELAGE IN FEET
- XX 7 SPEED OF TAIL ROTOR SYSTEM IN RPM 18 - LENGTH OF THE FUSELAGE IN FEET
 - 7 SPEED OF TAIL FOTOR SYSTEM IN REM 19 - FRONTAL FLAT PLATE AREA IN SQUARE FEET
- XX 7 SPEED OF TAIL ROTOR SYSTEM IN RPM 20 VERTICAL FLAT PLATE AREA IN SQUARE FEET
 - 7 SPEED OF TAIL FOTOR SYSTEM IN RPM 21 - MAXIMUM VELOCITY IN KNOTS
- XX 7 SPAED OF TAIL ROTOR SYSTEM IN RPM 22 MAXIMUM RANGE IN NAUTICAL MILES
- XX 7 SPEED OF TAIL ROTOR SYSTEM IN RPM 23 - RATE OF CLIMB IN FEET PER MINUTE, MAXIMUM CONTINUOUS POWER

- 7 SPEED OF TAIL ROTOR SYSTEM IN REM 24 - HOVER CEILING (IN GROUND EFFECT) IN FEET
- 7 SPEED OF TAIL FOICE SYSTEM IN RPM 25 - HOVER CEILING (CUT OF GROUNE EFFECT) IN FEET
- 7 SPEED OF TAIL BOTOR SYSTEM IN RPM 26 - LENGTH OF THE TAILBOOM IN FEET
- 7 SPEED OF TAIL ROTOR SYSTEM IN RPM 27 - OPERATING WEIGHT IN POUNDS
- 7 SPEED OF TAIL FOTOR SYSTEM IN EPM 28 LOAD WEIGHT IN POUNDS
- XX 7 SPEED OF TAIL FOTOR SYSTEM IN RPM 29 FUEL WEIGHT IN POUNDS
 - 7 SPEED OF TAIL FOTOR SYSTEM IN RPM 30 - MAXIMUM GROSS WEIGHT IN POUNDS

TABLE 12 Chord of Main Botor Blade Pairings

- 8 CHORD OF MAIN FOTOR BLADE IN FEET 9 - CHORD OF TAIL ROTOR BLADE IN FEET
- 8 CHORD OF MAIN BOTCE BLADE IN FEET 10 - SPAN OF MAIN FOTOF BLADE IN FEET
- XX 8 CHORD OF MAIN BUTCH BLADE IN FEET 11 SPAN OF TAIL BUTCH BLADE IN FEET
 - 8 CHORD OF MAIN ROTOR BLADE IN FEET 12 - TWIST OF MAIN FOTOR BLADE IN DEGREES
- XX 8 CHORD OF MAIN ROTOR BLADE IN FEET 13 - TWIST OF TAIL FOTOR BLADE IN DEGREES
 - 8 CHORD OF MAIN ROTOR BLADE IN FEET 14 - PROFILE DRAG OF MAIN ROTOR BLADE
- XX 8 CHORD OF MAIN FOTOR BLADE IN FEET 15 - PROFILE DRAG OF TAIL ROTOR BLADE
 - 8 CHORD OF MAIN BOTOR BLADE IN FEET 46 - DISC LOADING OF THE MAIN POTOR SYSTEM
- XX 8 CHORD OF MAIN FOTOR BLADE IN FEET 17 WIDTH OF THE FUSELAGE IN FEET
 - 8 CHORD OF MAIN FOTOR BLADE IN FEET 18 - LENGTH OF THE FUSIFIED IN FEET
 - 8 CHORD OF MAIN ROTOR BLADE IN FIET 19 - FRUNTAL FLAT PLATE AREA IN SCUARE FEET
 - -8 CHORD OF MAIN FOTOR BLADE IN FEET 20 - VERTICAL FLAT PLATE AREA IN SUJARE FEET
 - 8 CHORD OF MAIN ROTOR BLADE IN FEET 21 MAXIMUM VELOCITY IN KNOTS
- XX 8 CHORD OF MAIN BOTOR BLADE IN FEET 22 MAXIMUM RANGE IN NAUTICAL MILES
- XX 8 CHORD OF MAIN FOTOR BLADE IN FEET 23 FAIE OF CLIMB IN FEET PER MINUTE, MAXIMUM CONTINUOUS POWER
 - 8 CHORD OF MAIN ROTOR BLADE IN FEET 24 - HOVER CEILING (IN GROUND EFFECT) IN FEET

- 8 CHORD OF MAIN BOTTE BLADE IN FEET 25 - HOVER CEILING (COT OF BROUND EFFECT) IN FEET
- 8 CHORD OF MAIN ROTCE BLADE IN FEET 26 LENGTH OF THE TAILBOOM IN FEET
- 3 CHORD OF MAIN FOTOR BLADE IN FEET 27 OPERATING WEIGHT IN POUNDS
- 3 CHURD OF MAIN ROTCR BLADE IN FEET 28 LOAD WEIGHT IN POUNDS
- AA 3 CHORD OF MAIN FOTOR BLADE IN FEET 29 FUEL WEIGHT IN POUNDS

Ç

8 - CHORD OF MAIN FOTOR BLADE IN FEET 30 - MAXIMUM GROSS WEIGHT IN POUNDS

Chord of Tail Rotor Blade Pairings

- XX 9 CHORD OF TAIL FOTOR BLADE IN FEET 10 - SPAN OF MAIN ROTOR BLADE IN FEET
 - 9 CHORD OF TAIL FOTOR BLADE IN FEET 11 - SPAN OF TAIL POTOR BLADE IN FEET
- XX 9 CHORD OF TAIL BOTOR BLADE IN FEET 12 TWIST OF MAIN BOTOR BLADE IN DESKEES
 - 9 CHORD OF TAIL ROTOR BLADE IN FEET 13 - TWIST OF TAIL ROTOR BLADE IN DEGREES
- XX 9 CHORD OF TAIL SOTOR BLADE IN FEET 14 - PROFILE DRAG OF MAIN ROTOR ELADE
 - 9 CHORD OF TAIL ROTOR BLADE IN FEET 15 - PROFILE DRAG OF TAIL ROTOR BLADE
- XX 9 CHORD OF TAIL FOTOR BLADE IN FEET 16 DISC LOADING OF THE MAIN ROTOR SYSTEM
- XX 9 CHORD OF TAIL BOTCE BLADE IN FEET 17 WIDTH OF THE FUSELAGE IN FEET
- XX 9 CHORD OF TAIL SOTOR BLADE IN FEET 18 LENGTH OF THE FUSELAGE IN FEET
- XX 9 CHORD OF TAIL FOTOR BLADE IN FEET 19 - FRONTAL FLAT PLATE AREA IN SQUARE FEET
- XX 9 CHORD OF TAIL ROTOR BLADE IN FEET 20 - VERTICAL FLAT PLATE AREA IN SQUARE FEET
 - 9 CHORD OF TAIL FOTOR BLADE IN FEET 21 MAXIMUM VELOCITY IN KNOTS
 - 9 CHOED OF TAIL ROTOR BLADE IN FEET 22 MAXIMUM RANGE IN NAUTICAL MILES
- YX 9 CHORD OF TAIL ROTOR BLADE IN FEET 23 - RATE OF CLIMB IN FEET PER MINUTE, MAXIMUM CONTINUOUS POWER
 - 9 CHORD OF TAIL BOTOR BLADE IN FEET 24 - HOVER CEILING (IN GROUND EFFECT) IN FEET
 - 9 CHORD OF TAIL ROTOR BLADE IN FEET 25 HOVER CEILING (CUT OF GROUND EFFECT) IN FEET

- 9 CHIED OF TAIL BOTOR BLADE IN SEET 26 LENGTH OF THE TAILBOOM IN FEET
- 9 CHORD OF TAIL ROTOF BLADE IN FEET 27 OPERATING WEIGHT IN POUNDS
- 9 CHOAD OF TAIL FOTOR BLADE IN FEET 28 LOAD WEIGHT IN POUNDS
- XX 9 CHORD OF TAIL ROTOR BLADE IN FEET 29 FUEL WEIGHT IN POUNDS
 - 9 CHORD OF TAIL FOTOR BLADE IN FEET 30 - MAXIMUM GROSS WEIGHT IN POUNDS

TABLE 14 Span of Main Rotor Pairings

- 10 SPAN OF MAIN ROTOR BLADE IN FEET 11 - SPAN OF TAIL ROTOR BLADE IN FEET
- 10 SPAN OF MAIN ROTOR BLADE IN FEET 12 - IMIST OF MAIN BOTOR BLADE IN DEGREES
- XK 10 SEAN OF MAIN BOTCH BLADE IN FEET 13 - IWIST OF TAIL BOTCH BLADE IN DEGREES
 - 10 SPAN OF MAIN BOTOR BLADE IN FEET 14 - PROFILE DRAG OF MAIN BOTOR BLADE
- XX 13 SPAN OF MAIN FOTOR BLADE IN FEET 15 PROFILE DRAG OF TAIL ROTOR BLADE
 - 10 SPAN OF MAIN ACTOR BLADE IN FEET 16 - DISC LOADING OF THE MAIN ROTOR SYSTEM
 - 10 SPAN OF MAIN ROTOR BLADE IN FEET 17 WIDTH OF THE FUSELAGE IN FEET
 - 10 SPAN OF MAIN ROTOR BLADE IN FEET 18 - LENGTH OF THE FUSELAGE IN FEET
 - 10 SPAN OF MAIN ROTOR BLADE IN FEET 19 - FRONTAL FLAT PLATE AREA IN SQUARE FEET
 - 10 SPAN OF MAIN ROTOR BLADE IN FEET
 - 20 VERTICAL FLAI FLAIE AREA IN SQUARE FEET
 - 10 SPAN OF MAIN FOTOR BLADE IN FEET 21 MAKIMUM VELOCITY IN KNOTS
- XX 10 SPAN OF MAIN ROTOR BLADE IN FEET 22 MAXIMUM RANGE IN MAUTICAL MILES
 - 10 SPAN OF MAIN ROTOR BLADE IN FEET 23 RATE OF CLIMB IN FEET PER MINUTE, MAXIMUM CONTINUOUS POWER
 - 10 SPAN OF MAIN ROTOR BLADE IN FEET 24 - HOVER CEILING (IN GROUND EFFECT) IN FEET
 - 10 SPAN OF MAIN ECTOR BLADE IN FEET 25 HOVER CEILING (CUT OF GROUND EFFECT) IN FEET
 - 10 SPAN OF MAIN ROTOR BLADE IN FEET 26 LENGTH OF THE TAILBOOM IN FEET

- 10 SPAN OF MAIN FOTOE BLADE IN FEET 27 OPERATING WEIGHT IN POUNDS
- 10 SPAN OF MAIN ECTOR BLADE IN FEET 28 LOAD WEIGHT IN POUNDS
- XX 10 + SPAN OF MAIN ROTOR BLADE IN FEET 29 FUEL WEIGHT IN POUNDS

O

10 - SPAN OF MAIN ROTOR BLADE IN FEET 30 - MAXIMUM GROSS WEIGHT IN POUNDS

TABLE 15 Span of Tail Rotor Pairings

- 11 SPAN OF TAIL ROTOR BLADE IN FEET 12 - INIST OF MAIN ROTOR BLADE IN DEGREES
- 11 SPAN OF TAIL ROTOR BLADE IN FEET 13 - THIST OF TAIL ROTOR BLADE IN DEGREES
- XX 11 SPAN OF TAIL ROTOR BLADE IN FEET 14 - PROFILE DRAG OF MAIN ROTOR ELADE
 - 11 SPAN OF TAIL ROTOR BLADE IN FEET 15 - PROFILE DRAG OF TAIL ROTOR BLADE
- AX 11 SPAN OF TAIL ROTOR BLACE IN FEET 16 DISC LOADING OF THE MAIN ROTOR SYSTEM
- KK 11 SPAN OF TAIL ROTOR BLADE IN FEET 17 - WIDTH OF THE FUSELAGE IN FEET
- XX 11 SPAN OF TAIL ROTOL BLADE IN FEET 18 LENGTH OF THE FUSELAGE IN FEET
 - 11 SPAN OF TAIL BOTOR BLADE IN FEET 19 - FRONTAL FLAT PLATE AREA IN SQUARE FEET
 - 11 SPAN OF TAIL ROTOR BLADE IN FEET 20 - VERTICAL FLAT PLATE AREA IN SQUARE FEET
 - 11 SPAN OF TAIL BOTCA BLADE IN FEET 21 MAXIMUM VELOCITY IN KNOTS
- XX 11 SEAN OF TAIL ROTOR BLADE IN FEET 22 MAXIMUM RANGE IN NAUTICAL MILES
- XX 11 SPAN OF TAIL SCTOR BLADE IN FEET 23 RATE OF CLIMB IN FEET PER MINUTE, MAXIMUM CONTINUOUS POWER
 - 11 SPAN OF TAIL ROTOR BLADE IN FEET 24 HOVER CEILING (IN GROUND EFFECT)
 - 11 SPAN OF TAIL ROTOR BLADE IN FEET 25 - HOVER CEILING (CUT OF GROUND EFFECT) IN FEET
 - 11 SPAN OF TAIL ROTOR BLADE IN FEET 26 LENGTH OF THE TAILBOOM IN FEET

- 11 SPAN CY TAIL RCTOR BLADE IN FEET 27 OPERATING WEIGHT IN POUNDS
- 11 SPAN OF TAIL SCTOR BLADE IN FEET 28 LOAD WEIGHT IN POUNDS
- XX 11 SPAN OF TAIL ROTOR BLADE IN FEET 29 FUEL WEIGHT IN POUNDS
 - 11 SPAN OF TAIL ECTOR BLADE IN FEET 30 MAKIMUM GROSS WEIGHT IN POUNDS

Twist of Hain Rotor Blade Pairings

- 12 TWIST OF MAIN FOTOR BLADE IN DEGREES 13 TWIST OF TAIL ROTOR BLADE IN DEGREES
- 12 TWIST OF MAIN ROTOR BLADE IN DEGREES 14 - PROFILE DRAG OF MAIN ROTOR ELADE
- XX 12 TWIST OF MAIN BOTOR BLADE IN DEGREES 15 PROFILE DRAG OF TAIL ROTOR BLADE
 - 12 TWIST OF MAIN FOTOR BLADE IN DEGREES 16 - DISC LOADING OF THE MAIN ROTOR SYSTEM
- XX 12 TWIST OF MAIN ROTOR BLADE IN DEGREES 17 WIDTH OF THE FUSELAGE IN FEET
- XX 12 TWIST OF MAIN BOTCR BLADE IN DEGREES 18 LENGTH OF THE FUSELAGE IN FEET
- XX 12 TWIST OF MAIN FOTOR BLADE IN DEGREES 19 FRONTAL FLAT PLATE AREA IN SQUARE FEET
- XX 12 TWIST OF MAIN ROTOF BLADE IN DEGREES 20 VERTICAL FLAT PLATE AREA IN SQUARE FEET
 - 12 TWIST OF MAIN FOTOR BLADE IN DEGREES 21 MAXIMUM VELOCITY IN KNOTS
- XX 12 TWIST OF MAIN ROTOR BLADE IN DEGREES 22 MAXIMUM RANGE IN NAUTICAL MILES
- XX 12 TWIST OF MAIN ROTOR BLADE IN DEGREES 23 RATE OF CLIMB IN FEET PER MINUTE, MAXIMUM CONTINUOUS POWER
- XX 12 TWIST OF MAIN ROTOR BLADE IN DEGREES 24 HOVER CEILING (IN GROUND EFFECT) IN FEET
- XX 12 TWIST OF MAIN ROTOR BLADE IN DEGREES 25 HOVER CEILING (CUT OF GROUND EFFECT)
- XX 12 TWIST OF MAIN ROTOR BLADE IN DEGREES 26 LENGTH OF THE TAILBOOM IN FEET
- AX 12 TWIST OF MAIN FOTOR BLADE IN DEGREES 27 OPERATING WEIGHT IN FOUNDS
- XX 12 TWIST OF MAIN ROTCE BLADE IN DEGREES 28 LOAD WEIGHT IN POUNDS
- XX 12 TWIST OF MAIN FOTOR BLADE IN DEGREES 29 FUEL WEIGHT IN POUNDS
- XX 12 TWIST OF MAIN FOTOR BLADE IN DEGREES 30 MAKIMUM GROSS WEIGHT IN POUNDS

Twist of Tail Botor Blade Pairings

- XX 13 TWIST OF TAIL FOTOR BLADE IN DEGREES 14 PROFILE DRAG OF MAIN ROTOR BLADE
 - 13 TWIST OF TAIL FOTOR BLADE IN DEGREES 15 - PROFILE DRAG OF TAIL ROTOR ELADE
- XX 13 TWIST OF TAIL ROTCE BLADE IN DEGREES 16 DISC LOADING OF THE MAIN ROTOR SYSIEM
- XX 13 TWIST OF TAIL FOTOR BLADE IN DEGREES 17 WIDTH OF THE FUSELAGE IN FEET
- XX 13 TWIST OF TAIL ROTCR BLADE IN DEGREES 18 LENGTH OF THE FUSELAGE IN FEET
- AX 13 TWIST OF TAIL ROTCR BLADE IN DEGREES
 19 FRONTAL FLAT PLATE AREA IN SQUARE FEET
- XX 13 TWIST OF TAIL ROTCR BLADE IN DEGREES 20 VERTICAL FLAT FLATE AREA IN SQUARE FEET
- XX 13 TWIST OF TAIL ROTOR BLADE IN DEGREES 21 MAXIMUM VELOCITY IN KNOTS
- AA 13 TWIST OF TAIL BOTOR BLADE IN DEGREES 22 MAXIMUM RANGE IN NAUTICAL MILES
- XX 13 TWIST OF TAIL POTOR BLADE IN DEGREES 23 RATE OF CLIMB IN FEET PER MINUTE, MAXIMUM CONTINUOUS POWER
- XX 13 TWIST OF TAIL ROTOR BLADE IN DEGREES 24 HOVER CEILING (IN GROUND EFFECT) IN FEET
- XX 13 TWIST OF TAIL ROTOR BLADE IN DEGREES 25 HOVER CEILING (CUT OF GROUND EFFECT) IN FEET
- XX 13 TWIST OF TAIL ROTOR BLADE IN DEGREES 26 LENGTH OF THE TAILBOOM IN FEET
- XA 13 TWIST OF TAIL FOTOR BLADE IN DEGREES 27 OPERATING WEIGHT IN POUNDS
- XX 13 TWIST OF TAIL ROTOR BLADE IN DEGREES 28 LOAD WEIGHT IN POUNDS
- XX 13 TWIST OF TAIL BOTCE BLADE IN DEGREES 29 FUEL WEIGHT IN FOUNDS
 - 13 TWIST OF TAIL ROTOR BLADE IN DEGREES 30 MAKIMUM GROSS WEIGHT IN POUNDS

Profile Drag of Main Rotor Blade Pairings

- 14 PROFILE DRAG OF MAIN ROTOR ELADE 15 - PROFILE DRAG OF TAIL ROTOR ELADE
- 14 PROFILE DRAG OF MAIN FOTOR ELADE 16 - DISC LOADING OF THE MAIN ROTOR SYSTEM
- XX 14 PEDFILE DRAG OF MAIN ROTOR BLADE 17 WIDTH OF THE FUSELAGE IN FEET
- XX 14 PROFILE DRAG OF MAIN ROTOR FLADE 18 - LENGTH OF THE FUSELAGE IN FEET
- XX 14 PROFILE DRAG OF MAIN ROTOR ELADE 19 - FRONTAL FLAT PLATE AREA IN SQUARE FEET
- XX 14 PROFILE DRAG OF MAIN ROTOR ELADE 20 - VERTICAL FLAT PLATE AREA IN SQUARE FEET
 - 14 PROFILE DRAG OF MAIN ROTOR ELADE 21 - MAXIMUM VELOCITY IN KNOTS
- XX 14 PROFILE DRAG OF MAIN ROTOR ELADE 22 - MAXIMUM RANGE IN MAUTICAL MILES
 - 14 PROFILE DRAG OF MAIN ROTOR ELADE 23 - RATE OF CLIMB IN FEET PER MINUTE, MAXIMUM CONTINUCUS POWER
 - 14 PROFILE DRAG OF MAIN ROTOR ELADE 24 - HOVER CEILING (IN GROUND EFFECT) IN FEET
 - 14 PEOFILE DRAG OF MAIN ROTOR ELADE 25 - HOVER CEILING (CUT OF GROUND EFFECT) IN FEET
- XK 14 PROFILE DRAG OF MAIN FOTOR ELADE 26 LENGTH OF THE TAILBOOM IN FEET
 - 14 PROFILE DRAG OF MAIN ROTOR ELADE 27 OPERATING WEIGHT IN POUNDS
 - 14 PROFILE DRAG OF MAIN ROTOR ELADE 28 - LOAD WEIGHT IN POUNDS
- XX 14 PROFILE DRAG OF MAIN ROTOR BLADE 29 FUEL WEIGHT IN POUNDS
 - 14 PROFILE DRAG OF MAIN ROTOR FLADE 30 - MAXIMUM GROSS WEIGHT IN POUNDS

TABLE 19 Profile Drag of Tail Rotor 3lade Pairings

- KK 15 PECFILE DRAG OF TAIL FOTOR BLADE 16 - DISC LOADING OF THE MAIN ROTOR SYSTEM
- XX 15 PROFILE DRAG OF TAIL ROTOR ELADE 17 - WIDTH OF THE FUSELAGE IN FEET
 - 15 PROFILE DRAG OF TAIL ECTOR BLADE 18 - LENGTH OF THE FUSELAGE IN FEET
- XX 15 PROFILE DRAG OF TAIL ROTOR ELADE 19 - FRONTAL FLAT PLATE AREA IN SQUARE FEET
- XX 15 PROFILE DRAG OF TAIL ROTOR ELADE 20 - VERTICAL FLAT PLATE AREA IN SQUARE FEET
 - 15 PROFILE DRAG OF TAIL ROTOR ELADE 21 - MAXIMUM VELOCITY IN KNOTS
- XX 15 PROFILE DRAG OF TAIL ROTOR ELADE 22 MAXIMUM RANGE IN NAUTICAL MILES
 - 15 PROFILE DRAG OF TAIL ROTOR BLADE 23 - RATE OF CLIMB IN FEET PER MINUTE, MAXIMUM CONTINUOUS POWER
 - 15 PROFILE DRAG OF TAIL ROTOR ELADE 24 - HOVER CEILING (IN GROUND EFFECT) IN FEET
 - 15 PROFILE DRAG OF TAIL ROTOR ELADE 25 - MOVER CEILING (CUT OF GROUND EFFECT) IN FEET
 - 15 PROFILE DRAG OF TAIL ROTOR ELADE 26 - LENGTH OF THE TAILBOOM IN FEET
 - 15 PROFILE DRAG OF TAIL ROTOR ELADE 27 - OPERATING WEIGHT IN POUNDS
 - 15 PROFILE DRAG OF TAIL ROTOR BLADE 28 LOAD WEIGHT IN POUNDS
- XX 15 PROFILE DRAG OF TAIL ROTOR ELADE 29 FUEL WEIGHT IN POUNDS
 - 15 PECFILE DRAG OF TAIL ROTOR ELADE 30 - MAXIMUM GROSS WEIGHT IN POUNDS

Disc Loading of the Main Rotor System Pairings

- 16 DISC LCADING OF THE MAIN RCTOR SYSTEM 17 WIDTH OF THE FUSELAGE IN FEET
- DISC LOADING OF THE MAIN ROTOR SYSTEM LENGTH OF THE FUSELAGE IN FEET
- DISC LCADING OF THE MAIN ROTOR SYSTEM FRONTAL FLAT PLATE AREA IN SQUARE FEET
- DISC LOADING OF THE MAIN ROTOR SYSTEM VERTICAL FLAT PLATE AREA IN SQUARE FEET
- DISC LCADING OF THE MAIN ROTOR SYSTEM MAXIMUM VELOCITY IN KNOTS
- DISC LOADING OF THE MAIN ROTOR SYSTEM MAXIMUM RANGE IN NAUTICAL MILES
- DISC LOADING OF THE MAIN ECTOR SYSTEM RATE OF CLIMB IN FEET PER MINUTE, MAXIMUM CONTINUOUS POWER
- 16 DISC LCADING OF THE MAIN RCTOR SYSTEM 24 HOVER CEILING (IN GROUND EFFECT) IN FEET
- 16 DISC LOADING OF THE MAIN ROTOR SYSTEM 25 HOVER CEILING (CUT OF GROUND EFFECT) IN FEET
- XX 16 DISC LOADING OF THE MAIN ROTOR SYSTEM 26 LENGTH OF THE TAILBOOM IN FEET
- XX 16 DISC LCADING OF THE MAIN ROTOR SYSTEM 27 OPERATING WEIGHT IN POUNDS
- XX 16 DISC LOADING OF THE MAIN ROTOR SYSTEM 28 LOAD WEIGHT IN POUNDS
- XX 16 DISC LCADING OF THE MAIN ECTOR SYSTEM 29 FUEL WEIGHT IN POUNDS
 - 16 DISC LOADING OF THE MAIN RCTOR SYSTEM 30 MAXIMUM GROSS WEIGHT IN POUNDS

TABLE 21 Width of the Fuselage Pairings

- 17 WIDTH OF THE FUSELAGE IN FEET 18 - LENGTH OF THE FUSELAGE IN FEET
- 17 WIDTH OF THE FUSELAGE IN FEET 19 - FRONTAL PLAT PLATE AREA IN SQUARE FEET
- 17 WIDTH OF THE FUSELAGE IN FEET 20 - VERTICAL FLAT PLATE AREA IN SQUARE FEET
- 17 WIDTH OF THE FUSELAGE IN FEET 21 MAXIMUM VELOCITY IN KNOTS
- XX 17 WIDTH OF THE FUSELAGE IN FEET 22 MAXIMUM RANGE IN NAUTICAL MILES
 - 17 WIDTH OF THE FUSELAGE IN FEET 23 - RATE OF CLIMB IN FEET PER MINUTE, MAXIMUM CONTINUOUS POWER
 - 17 WIDTH OF THE FUSELAGE IN FEET 24 HOVER CEILING (IN GROUND EFFECT)
 - 17 WIDTH OF THE FUSELAGE IN FEET 25 - HOVER CEILING (CUT OF GROUND EFFECT) IN FEET
 - 17 MIDTH OF THE FUSELAGE IN FEET 26 LENGTH OF THE TAILBOOM IN FEET
 - 17 WIDTH OF THE FUSELAGE IN FEET
 - 17 WIDTH OF THE FUSELAGE IN FEET
 - 17 WIDTH OF THE FUSELAGE IN FEET 29 FUEL WEIGHT IN POUNDS
 - 17 WIDTH OF THE FUSEIAGE IN FEET 30 - MAXIMUM GROSS WEIGHT IN POUNDS

TABLE 22 Length of Fuselage Pairings

- 18 LENGTH OF THE FUSILAGE IN FEET 19 - FRONTAL FLAT PLATE AREA IN SQUARE FEET
- 18 LENGTH OF THE FUSELAGE IN FIET 20 - VERTICAL FLAT FLATE AREA IN SUUARE FEET
- 18 LENGTH OF THE FUSELAGE IN FEET 21 MAXIMUM VELOCITY IN KNOTS
- 18 LENGTH OF THE FUSELAGE IN FEET 22 MAXIMUM RANGE IN NAUTICAL MILES
- 18 LENGTH OF THE FUSELAGE IN FEET 23 - RATE OF CLIMB IN FEET PER MINUTE, MAXIMUM CONTINUOUS POWER
- 18 LENGTH OF THE FUSELAGE IN FEET 24 HOVER CEILING (IN GROUND EFFECT) IN FEET
- 19 LENGTH OF THE FUSELAGE IN FEET 25 - HOVER CEILING (CUT OF GROUND EFFECT) IN FEET
- 18 LENGTH OF THE FUSELAGE IN FEET 26 LENGTH OF THE TAILBOOM IN FEET
- 18 LENGTH OF THE FUSELAGE IN FEET 27 OPERATING WEIGHT IN POUNDS
- 18 LENGTH OF THE FUSELAGE IN FEET 29 LOAD WEIGHT IN POUNDS
- XX 18 LENGTH OF THE FUSELAGE IN FEET 29 FUEL WEIGHT IN POUNDS
 - 18 LENGTH OF THE FUSELAGE IN FEET 30 - MAXIMUM GROSS WEIGHT IN POUNDS

TABLE 23 Frontal Horizontal Flat Plate Area Pairings

- 19 FRONTAL FLAT PLATE AREA IN SQUARE FEET 20 VERTICAL FLAT PLATE AREA IN SQUARE FEET
- 19 FFONTAL FLAT PLATE AREA IN SQUARE FEET 21 - MAXIMUM VELCCITY IN KNOTS
- 19 FRONTAL FLAT PLATE AREA IN SQUARE FEET 22 MAXIMUM RANGE IN NAUTICAL MILES
- XX 19 FRONTAL FLAT PLATE AREA IN SQUARE FEET
 23 RATE OF CLIMB IN FEET PER MINUTE,
 MAXIMUM CONTINUOUS POWER
- XX 19 FRONTAL FLAT PLATE AREA IN SQUARE FEET 24 HOVER CEILING (IN GROUND EFFECT)
- AA 19 FRONTAL FLAT PLATE AREA IN SQUARE FEET 25 HOVER CEILING (CUT OF GROUND EFFECT) IN FEET
- XX 19 FRONTAL FLAT PLATE AREA IN SQUARE FEET 26 LENGTH OF THE TAILBOOM IN FEET
 - 19 FRONTAL FLAT PLATE AREA IN SQUARE FEET 27 OPERATING WEIGHT IN POUNDS
 - 19 FRONTAL FLAT PLATE AREA IN SQUARE FEET 28 LOAD WEIGHT IN POUNDS
- XX 19 FRONTAL FLAT PLATE AREA IN SQUARE FEET 29 - FUEL WEIGHT IN POUNDS
 - 19 FRONTAL FLAT PLATE AREA IN SQUARE FEET 30 MAKIMUM GROSS WEIGHT IN POUNDS

TABLE 24 Prontal Vertical Plat Plate Area Pairings

- (A 1) VERTICAL FLAT PLATE AFFA IN SQUARE FEIT IN MAXIMUM VELCCITY IN KNOTS
- XX U) VESTICAL FLAT BLATE AREA IN SQUARE FEET 12 + MAKIMUM RANGE IN DAUTICAL MILES
 - 3 VESTICAL FLAT FLATE AREA IN SQUARE FEET BE RATE OF CLIMB IN FEET BER MINUTE, MAXIMUM CONTINUOUS POWER
 - 2) VERTICAL FLAT FLATE AREA IN SQUARE FEET 2+ - HOVER CEILING (IN GROUND EFFECT) IN FEET
 - 2) VERTICAL FLAT ELATE AREA IN SQUARE FEET 25 - HOVER CEILING (CUT OF GROUND EFFECT) IN FEET
- XX 20 + VERTICAL FLAT FLATE AREA IN SIUAR E FEET 26 LENGTH OF THE TAILBOOM IN FEET
 - 2) VORTICAL FLAT PLATE AREA IN SQUARE FEET 27 OPERATING WEIGHT IN POUNDS
 - 20 VERTICAL FLAT PLATE AREA IN SQUARE FEET 28 LOAD WEIGHT IN FOUNDS
- XX 20 VERTICAL FLAT PLATE AREA IN SQUARE FEET 29 - FUEL WEIGHT IN POUNDS
 - 20 VERTICAL FLAT PLATE AREA IN SUAR E FEET 30 MAKIMUM GROSS WEIGHT IN POUNDS

Maximum Forward Telocity Pairings

- 21 MAKIMUM VELOCITY IN KNOTS 22 MAKIMUM RANGE IN NAUTICAL MILES
- 21 MAXIMUM VELOCITY IN KNOTS 23 RATE OF CLIMB IN FEET PER MINUTE, MAXIMUM CONTINUOUS POWER
- 21 MAXIMUM VILOCITY IN KNOTS 24 HOVER CEILING (IN GROUND EFFECT) IN FEFT
- 21 MAKINUM VELOCITY IN KNOTS 25 HOVER CEILING (CUI OF GROUND EFFECT) IN FEET
- XX 21 MAXIMUM VELOCITY IN KNOTS 26 LENGTH OF THE TAILBOOM IN FEET

 - 21 MAILMUM VELOCITY IN KNOTS 28 LOAD WEIGHT IN POUNDS
- XX 21 MAXIMUM VELOCITY IN KNOTS 29 FUEL WEIGHT IN POUNDS
 - 21 MAXIMUM VELOCITY IN KNOTS 30 MAXIMUM GROSS WEIGHT IN POUNDS

TABLE 26

Maximum Range Pairings

- 22 MAXIMUM RANGE IN MAUTICAL MILES 23 RATE OF CLIMB IN FEET PER MINUTE, MAXIMUM CONTINUOUS POWER
- XX 22 MAXIMUM RANGE IN NAUTICAL MILES 24 HOVER CEILING (IN GROUND EFFECT) IN FEFT
- XX 22 MAXIMUM RANGE IN NAUTICAL MILES 25 HOVER CEILING (CUT OF BROUND EFFECT) IN FEET
- XX 22 MAXIMUM RANGE IN NAUTICAL MILES 26 LENGTH OF THE TAILBOOM IN FEET
 - 22 MAKIMUM RANGE IN NAUTICAL MILES 27 OPERATING WEIGHT IN POUNDS
 - 22 MAKIMUM RANGE IN NAUTICAL MILES 28 LOAD WEIGHT IN POUNDS
 - 22 MAXIMUM BANGE IN JAUTICAL MILES 29 FUEL WEIGHT IN POUNDS
 - 22 MAKIMUM RANGE IN NAUTICAL MILES 30 MAKIMUM GROSS WEIGHT IN POUNDS

Rate of Climb Pairings

- RATE OF CLIME IN FEET PER MINUTE MAXIMUM CONTINUOUS POWER HOVER CEILING (IN GROUND EFFECT) IN FEET
- BATE OF CLIMB IN FEET PER MINUTE MAKIMUM CONTINUOUS POWER HOVER CEILING (CUT OF GROUND EFFECT) IN FEET
- 23 RATE OF CLIMB IN FEET PER MINUTE MAKIMUM CONTINUCUS POWER
 26 LENGTH OF THE TAILBOOM IN FEET
- 23 RAIE OF CLIMB IN FEET PER MINUTE MAXIMUM CONTINUOUS FOWER
 27 CPERATING WEIGHT IN POUNDS
- 23 RATE OF CLIMB IN FEET PER MINUTE MAXIMUM CONTINUOUS POWER
 28 LOAD WEIGHT IN POUNDS
- 23 RAIE OF CLIMB IN FEET PER MINUTE MAXIMUM CONTINUOUS POWER
 29 FUEL WEIGHT IN POUNDS
- 23 RATE OF CLIMB IN FEET PER MINUTE MAXIMUM CONTINUOUS POWER
 30 MAXIMUM GROSS WEIGHT IN POUNDS

TABLE 28

Hover Ceiling (IGE) Pairings

- HOVER CEILING (IN GROUND EFFECT)
 IN FEET
 HOVER CEILING (CUT OF GROUND EFFECT)
 IN FEET
- XX 24 HOVER CEILING (IN GROUND EFFECT)
 10 FEET
 26 LENGTH OF THE TAILBOOM IN FEET

 - HOVER CEILING (IN GROUND EFFECT)
 IN FEET
 OPERATING FEIGHT IN POUNDS

 - 24 HOVER CEILING (IN GROUND EFFECT) IN FEET 28 LOAD WEIGHT IN POUNDS
- XX 24 HOVER CEILING (IN GROUND EFFECT) IN FEET 29 FUEL WEIGHT IN POUNDS

 - 24 HOVER CEILING (IN GROUND EFFECT) IN FEET
 - MÄYİMÜM GROSS WEIGHT IJ POUNDS

TABLE 29 Hover Ceiling (OGE) Pairings

- YX 25 HOVER CEILING (CUT OF GROUND EFFECT) IN FEET 26 LENGTH OF THE TAILBOOM IN FEET

 - 25 HCVER CEILING (CUT OF GROUND EFFECT)
 - 27 ÖPERÄTING WEIGHT IN POUNDS
 - 25 HOVER CEILING (CUT OF BROUND EFFECT)
 - IN YEST 28 LOAD WEIGHT IN POUNDS
- XX 25 HOVER CEILING (CUT OF GROUND EFFECT)

 10 FEET
 29 FUEL WEIGHT IN POUNDS

 - 25 HOVER CEILING (CUT OF GROUND EFFECT)
 30 MAXIMUM GROSS WEIGHT IN POUNDS

TABLE 30 Length of Tail Pairings

- 26 LENGTH OF THE TAILBOOM IN FEET 27 OPERATING WEIGHT IN POUNDS
- 26 LENGTH OF THE TAILEDOM IN FEET 28 LOAD WEIGHT IN POUNDS
- XX 26 LENGTH OF THE TAILBOOM IN FEET 29 FUEL WEIGHT IN POUNDS
 - 26 LENGIH OF THE TAILBOOM IN FEET 30 MAKIMUM GROSS WEIGHT IN POUNDS

TABLE 31 Operating Weight Pairings

- 27 OPERATING WEIGHT IN POUNDS 30 MAXIMUM GROSS WEIGHT IN POUNDS

TABLE 32 Load Weight Pairings

- 28 LOAD WEIGHT IN POUNDS 29 FUEL WEIGHT IN POUNDS
- 28 LOAD WEIGHT IN POUNDS 30 MAXIMUM GRCSS WEIGHT IN POUNDS

TABLE 33 Fuel Weight Pairings

29 - FUEL WEIGHT IN POUNDS 30 - MAXIMUM GROSS WEIGHT IN POUNDS

APPENDIX C

DATA POINT PLOTS, CURVE FITS, AND CURVE FIT EQUATIONS

Main Rotor Radius Pairings.

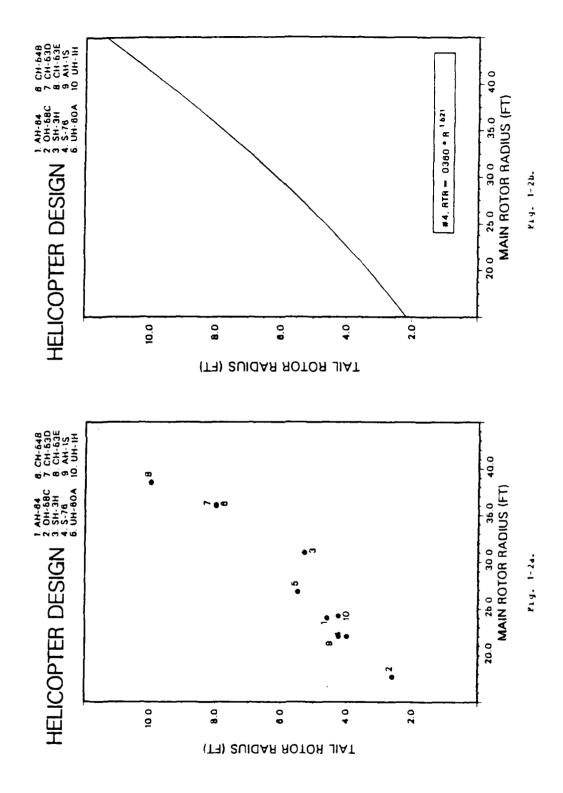


Fig. 1-2a and 1-2b.

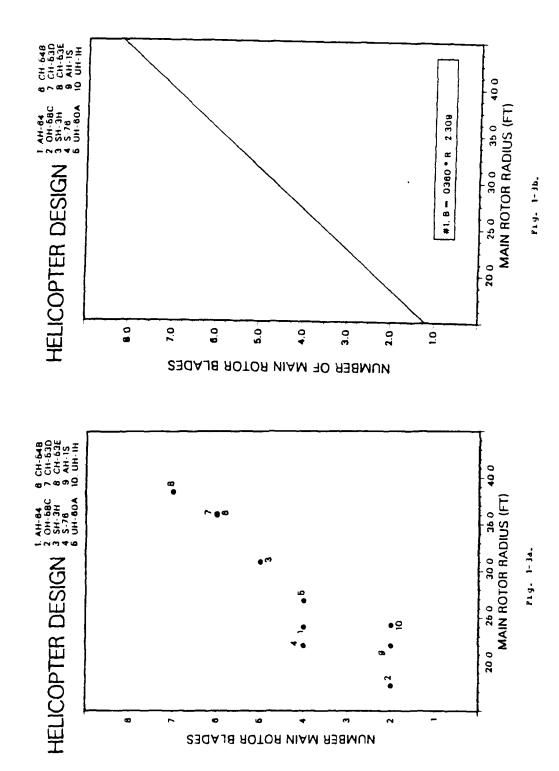
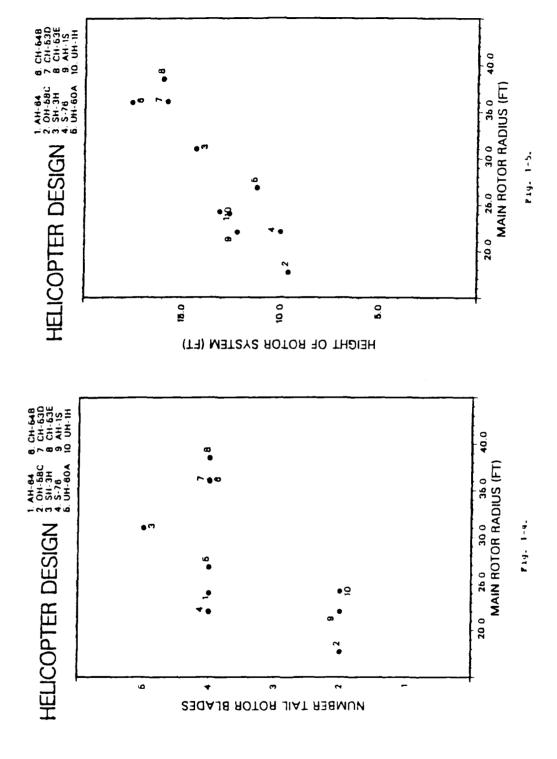


Fig. 1-3a and 1-3b.

Fig.



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7 3

1-4 and 1-5.

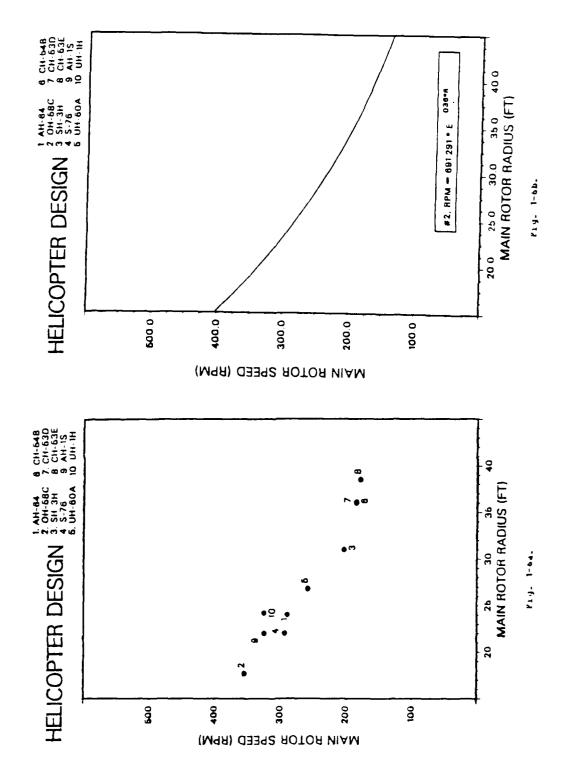


Fig. 1-ba and 1-bb.

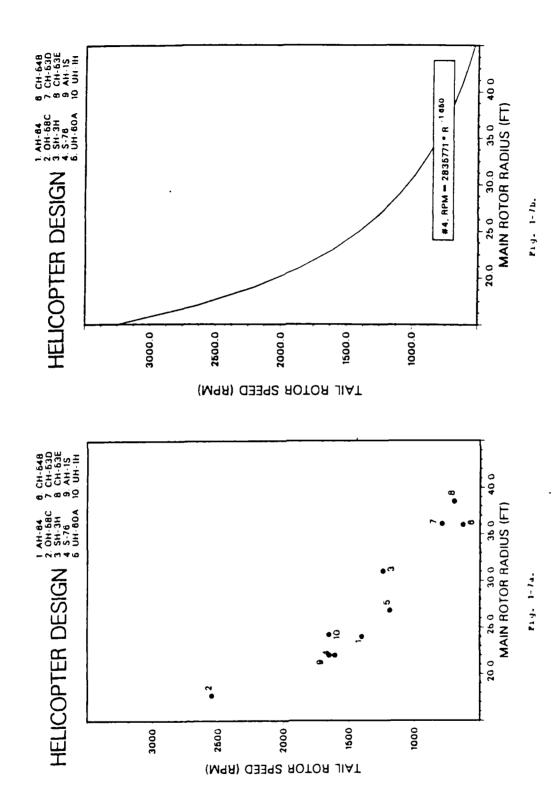


Fig. 1-7a and 1-7b.

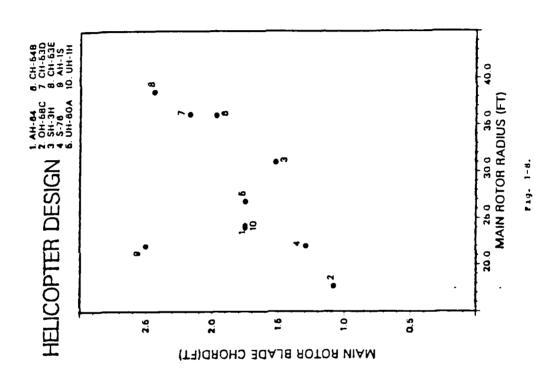


Fig. 1-8.

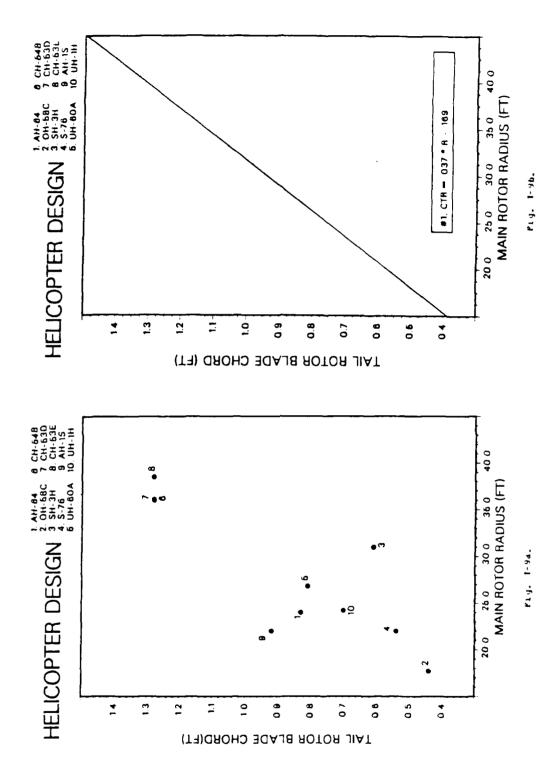


Fig. 1-9a and 1-9b.

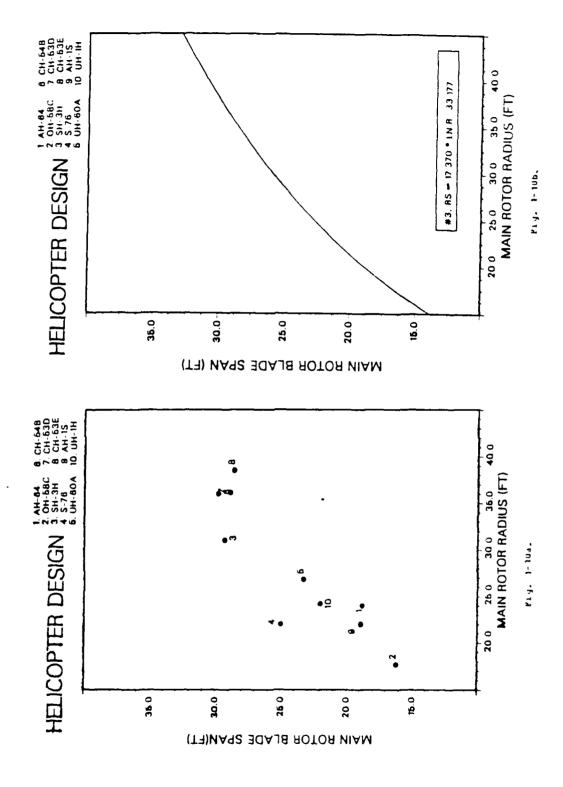


Fig. 1-10a and 1-10b.

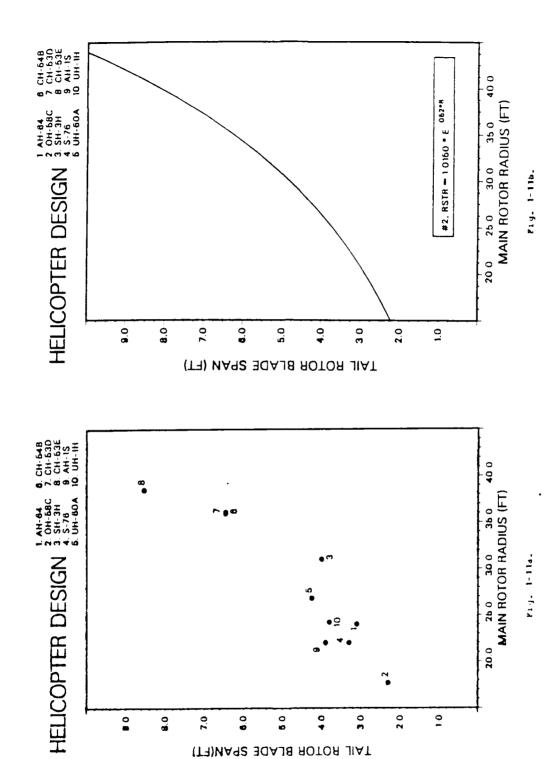
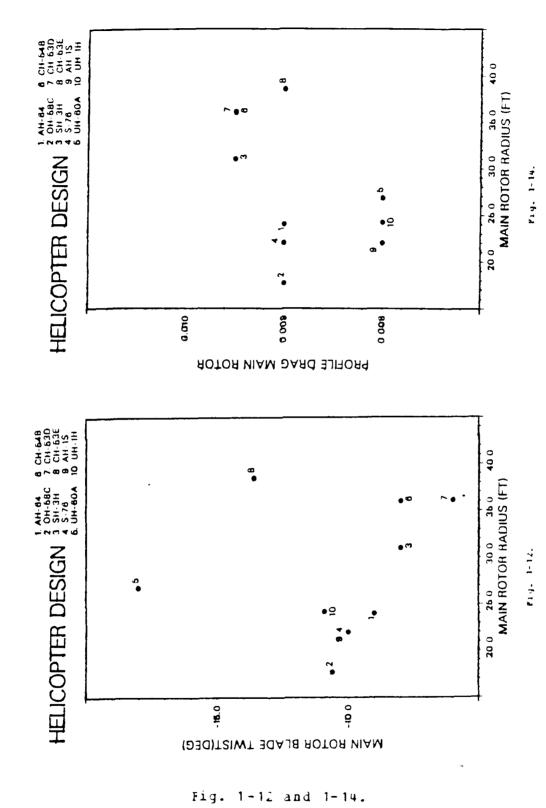
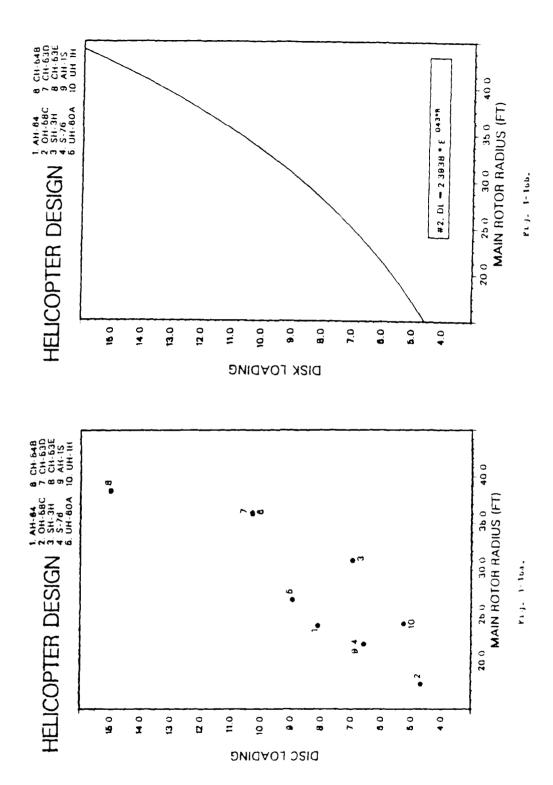


Fig. 1-11a and 1-11b.



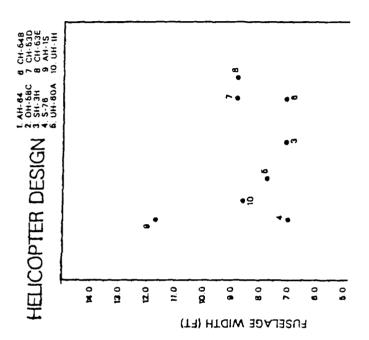
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Fig. 1-16a and 1-16b.



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Fig. 1-17.

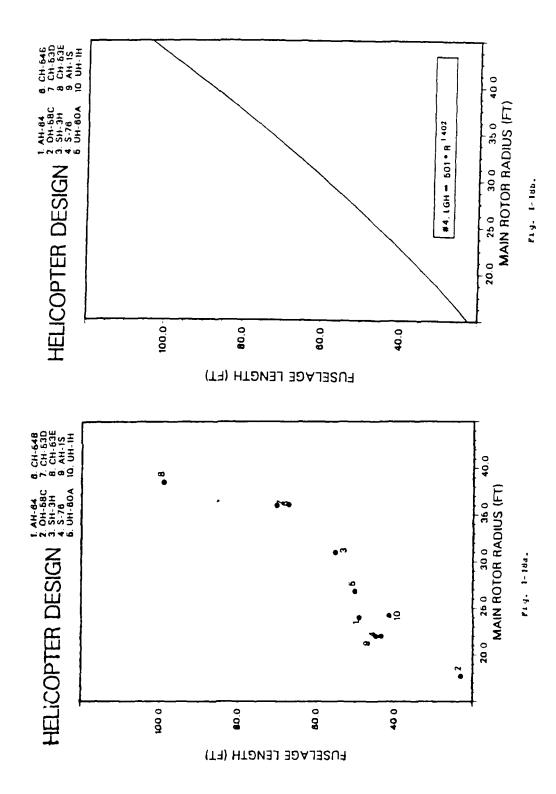
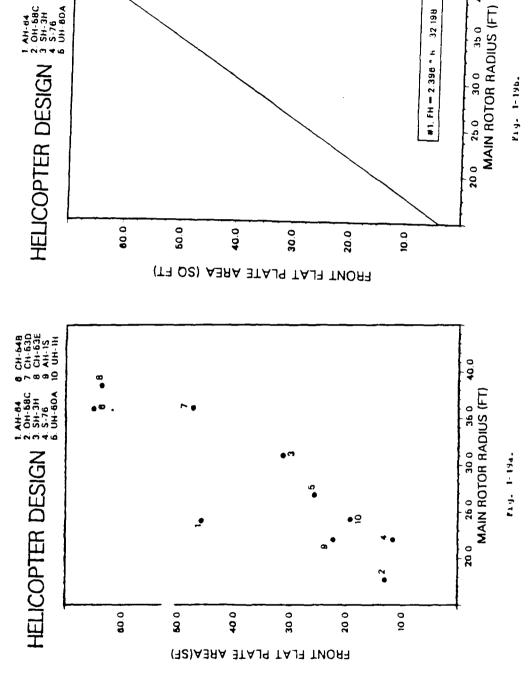


Fig. 1-18a and 1-13b.

Fig. 1-19a and 1-19b.



8 CH-648 7 CH-63D 8 CH-63E 9 AH-1S 10 UH-1H

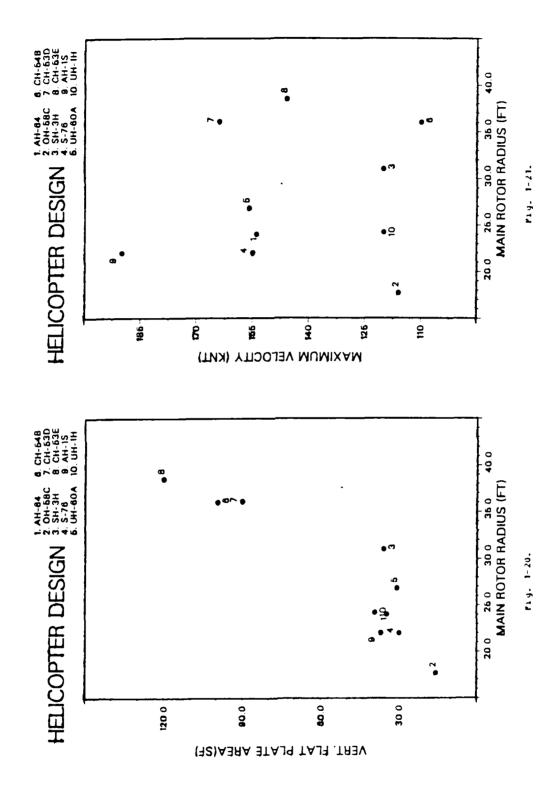


Fig. 1-20 and 1-21.

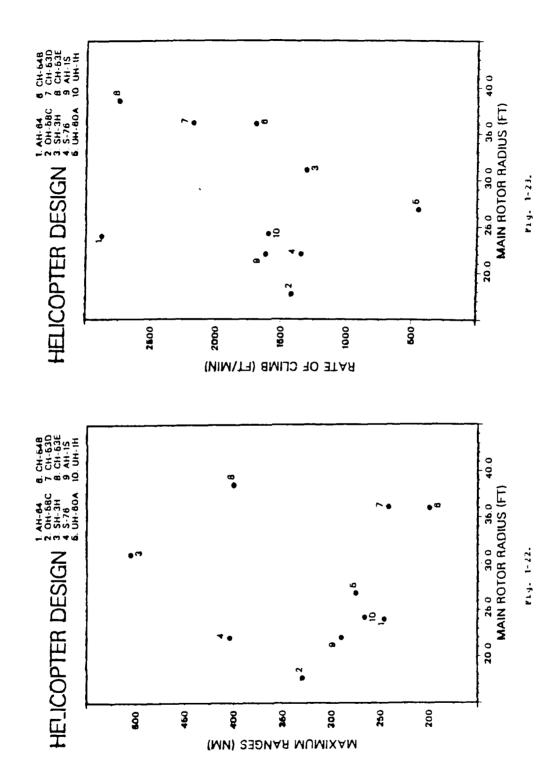


Fig. 1-22 and 1-23.

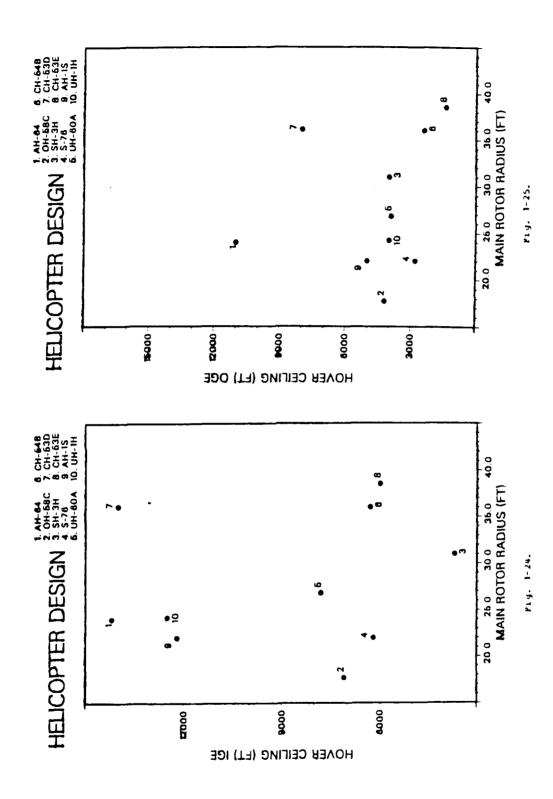


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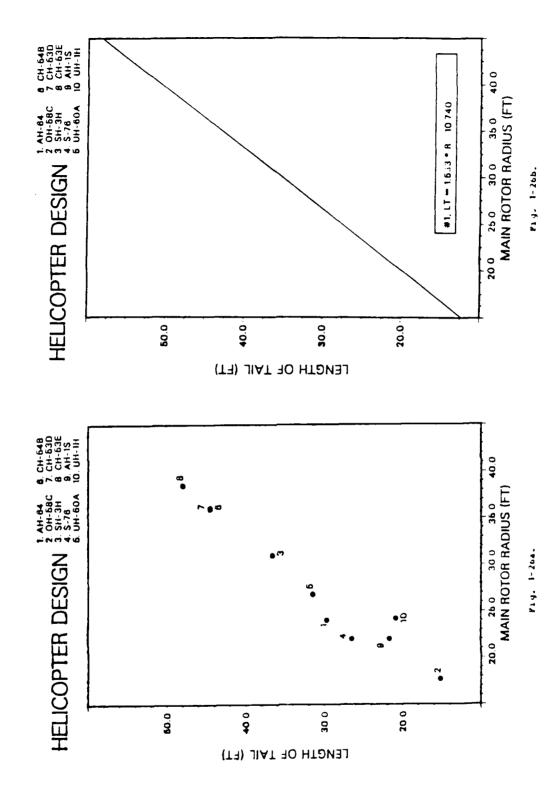


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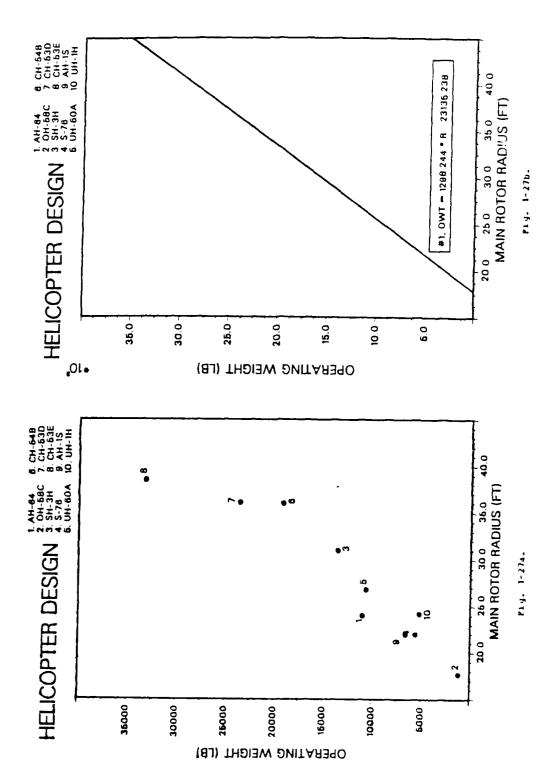


Fig. 1-27a and 1-27b.

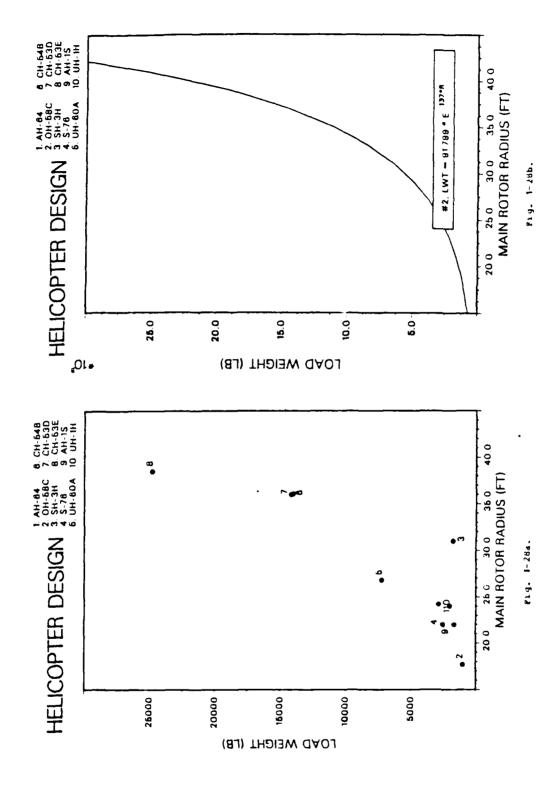
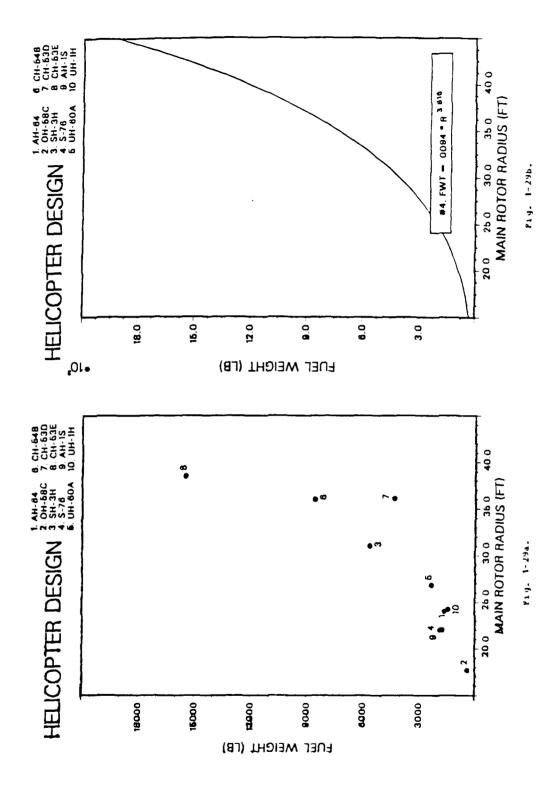
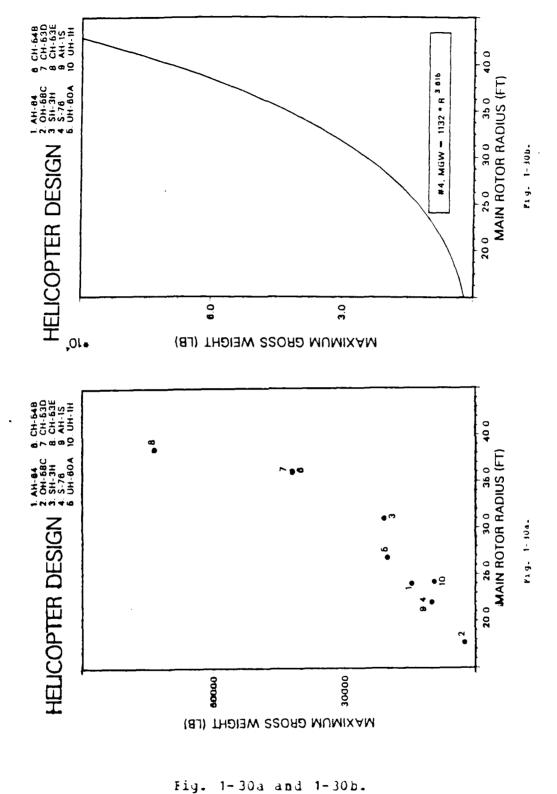


Fig. 1-28a and 1-23b.



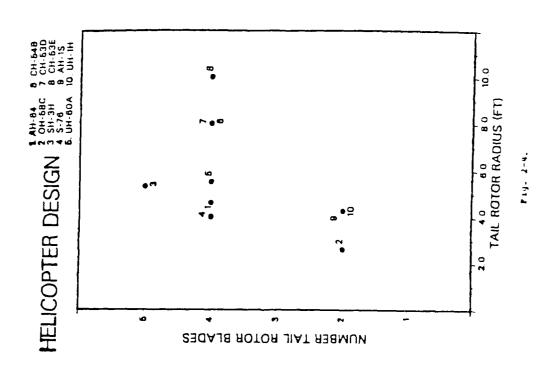
E

Fig. 1-29a and 1-23b.

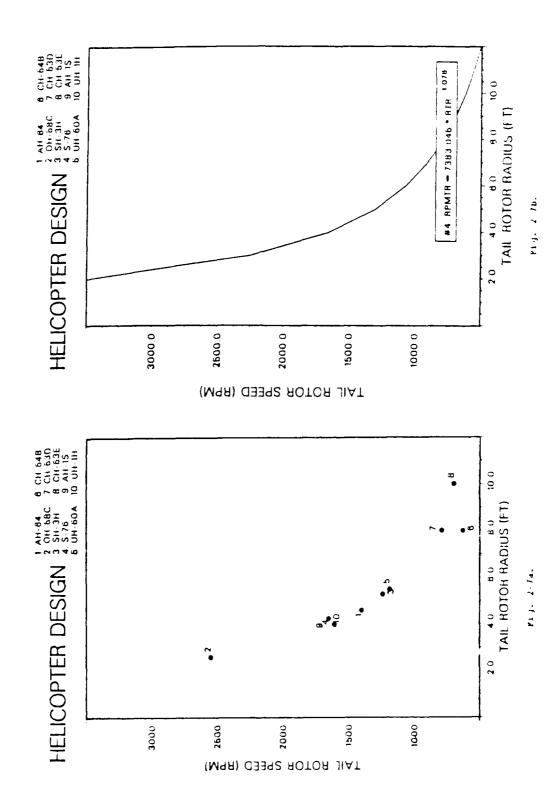


9 Î

Tail Rotor Radius Pairings.

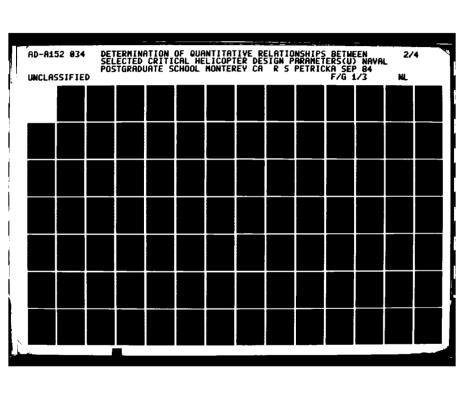


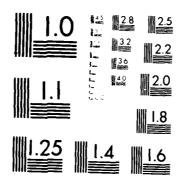
Pig. 2-4.



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Fig. 2-7a and 2-7b.





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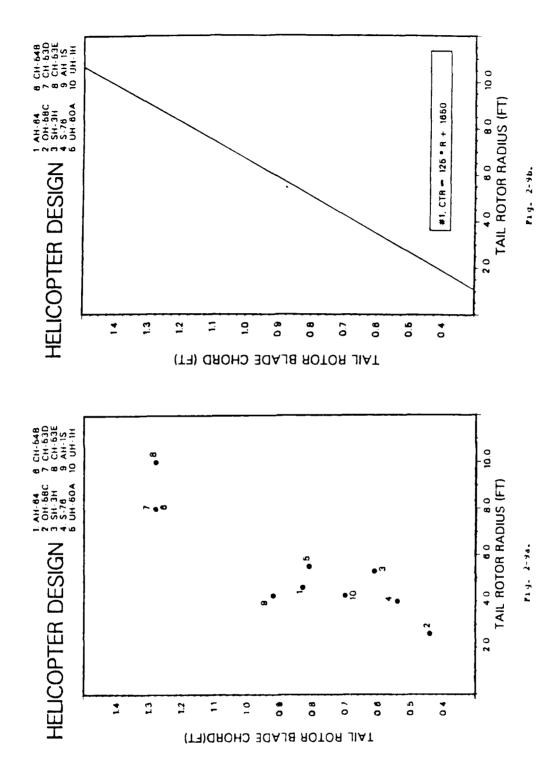


Fig. 2-9a and 2-9b.

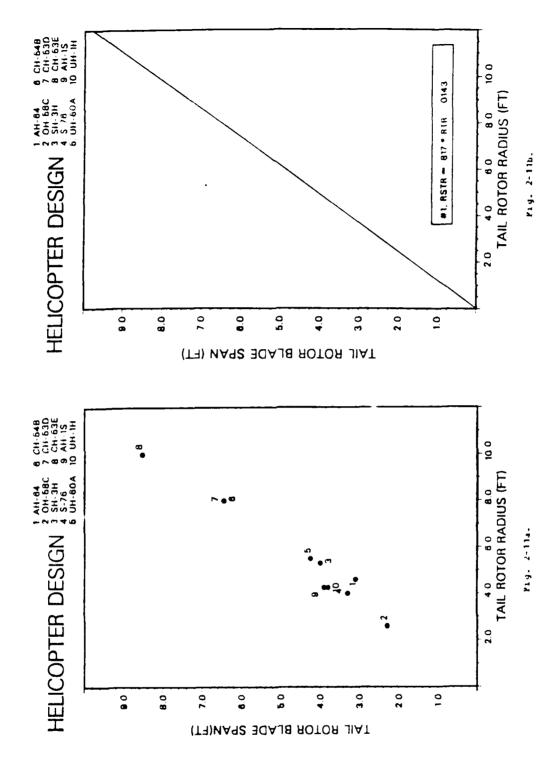


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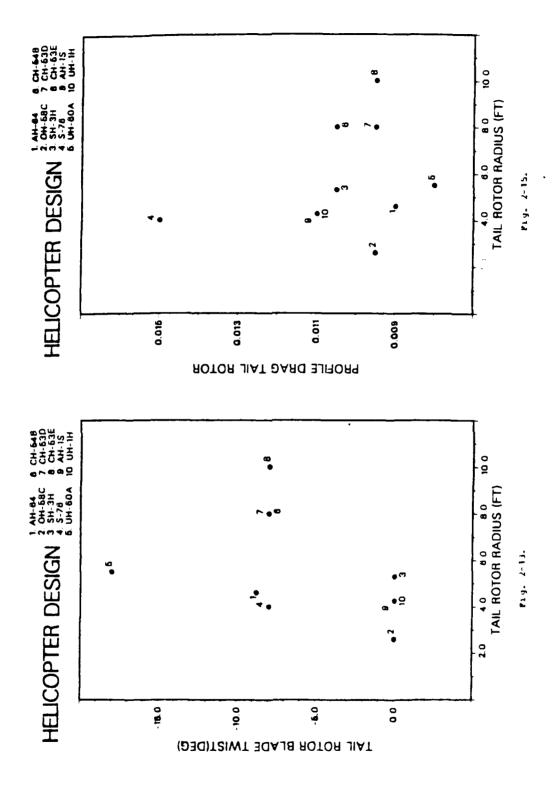


Fig. 2-13 and 2-15.

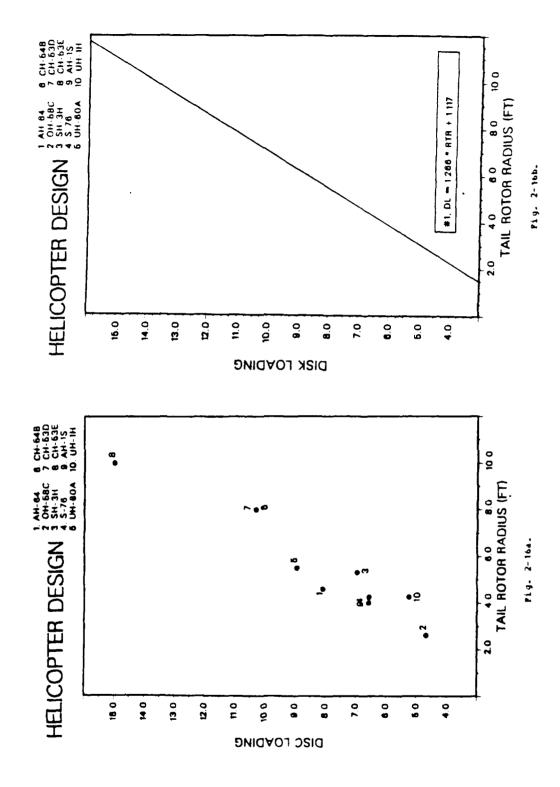


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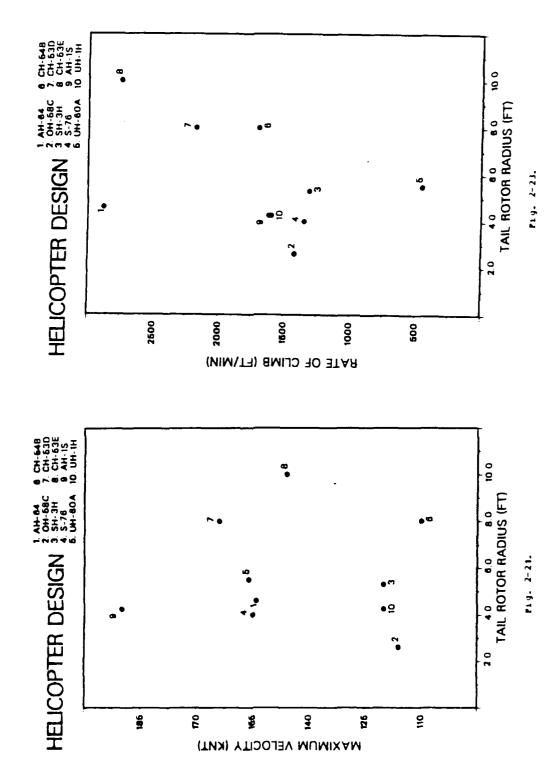


Fig. 2-21 and 2-23.

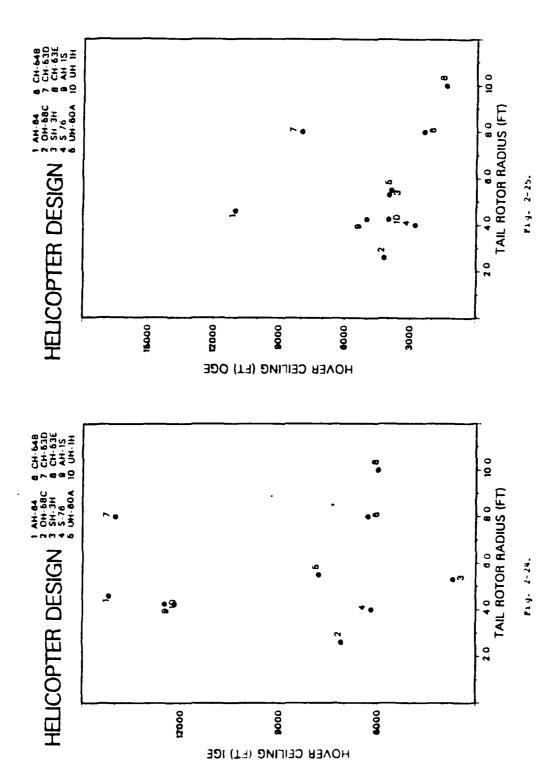


Fig. 2-24 and 2-25.

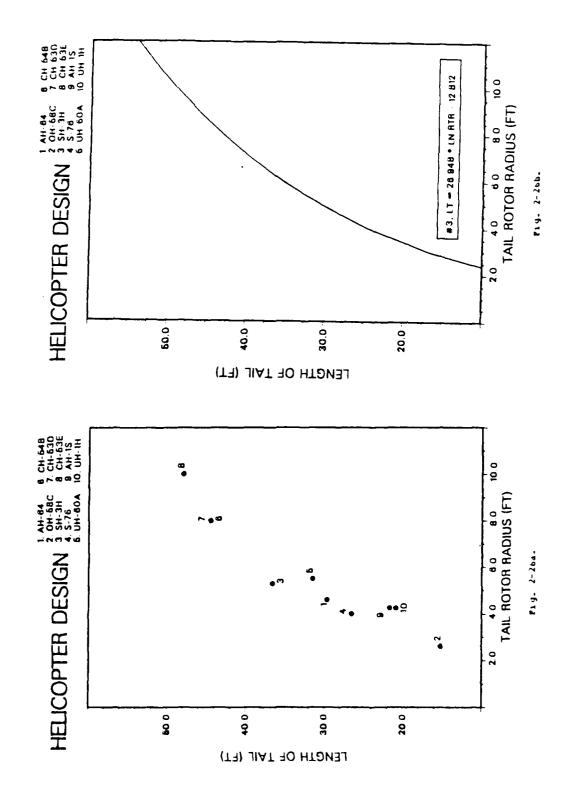


Fig. 2-26a ind 2-26b.

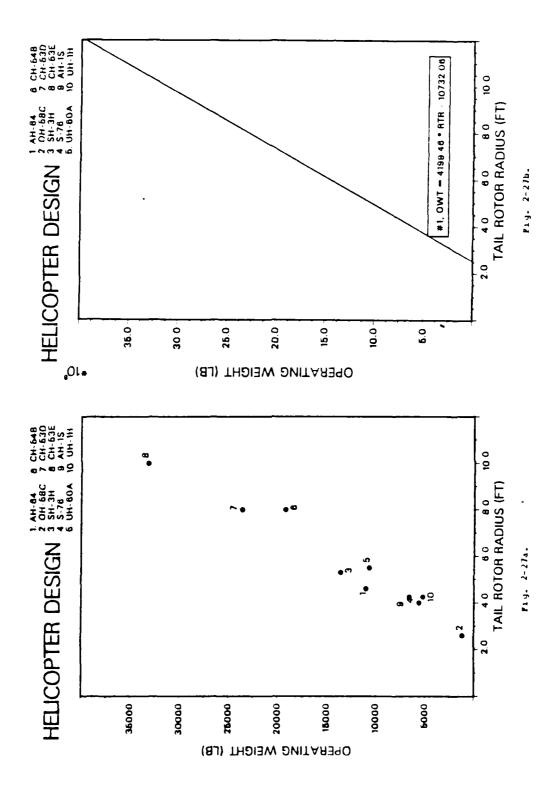


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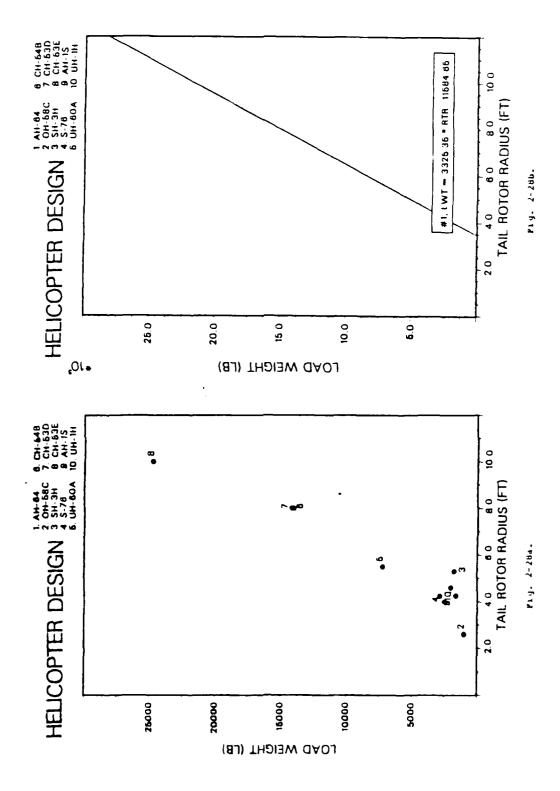
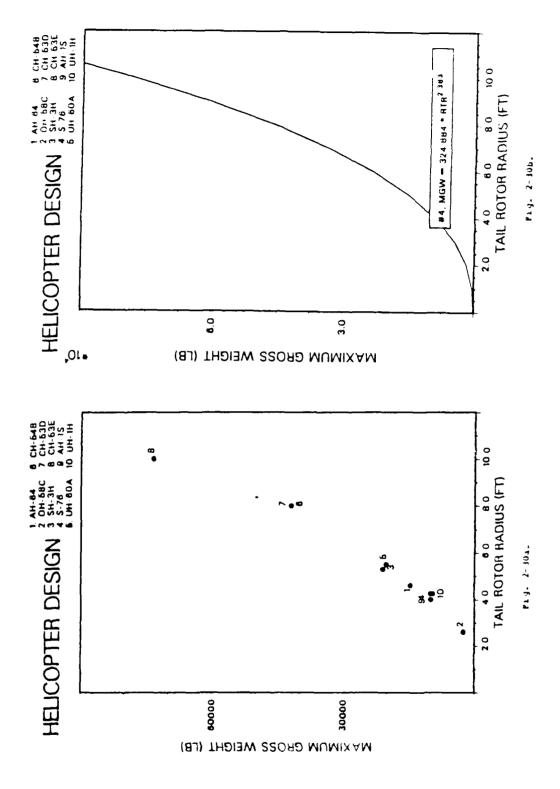


Fig. 2-28a and 2-28b.



Eig. 2-30a and 2-30b.

Number of Main Rotor Blades Pairings.

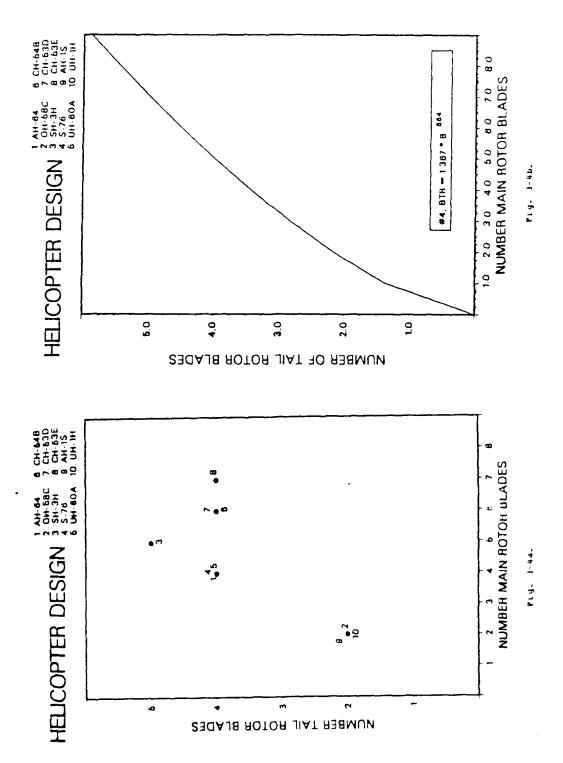


Fig. 3-4a and 3-4b.

1., ;

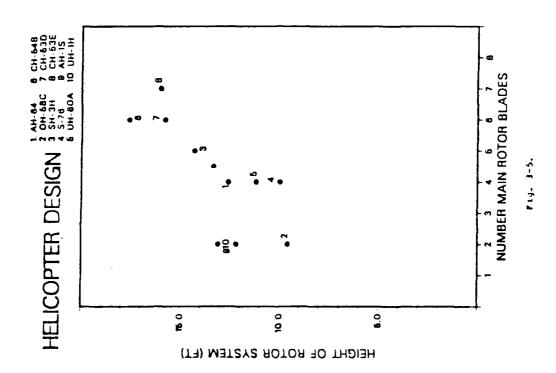


Fig. 3-5.

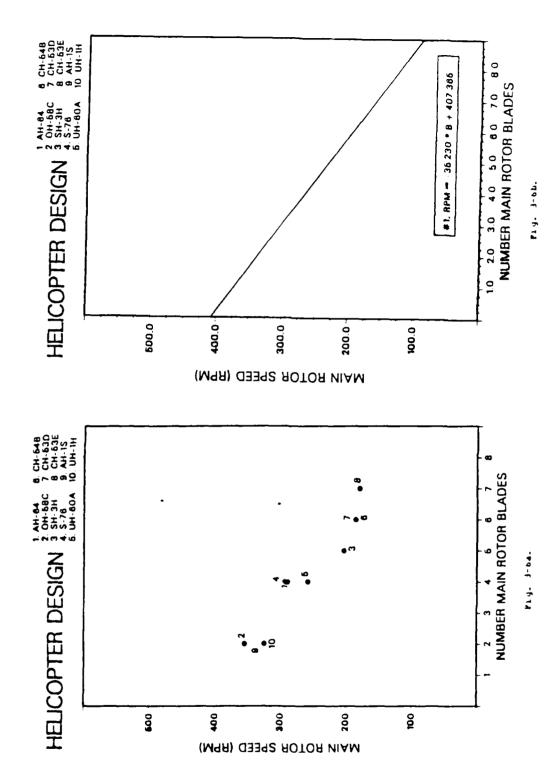


Fig. 3-6a and 3-on.

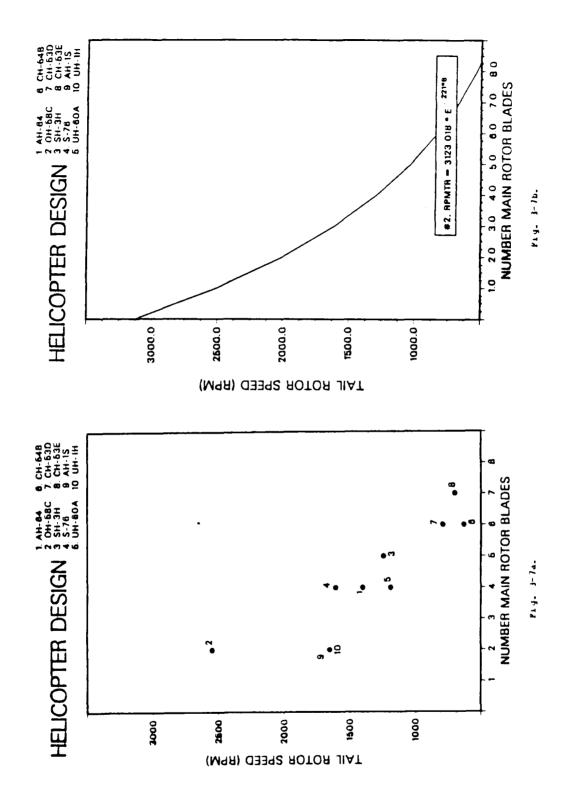
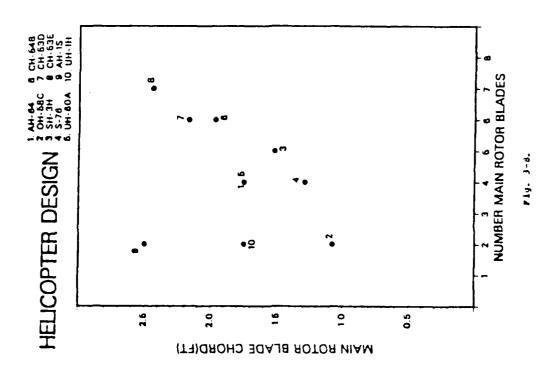
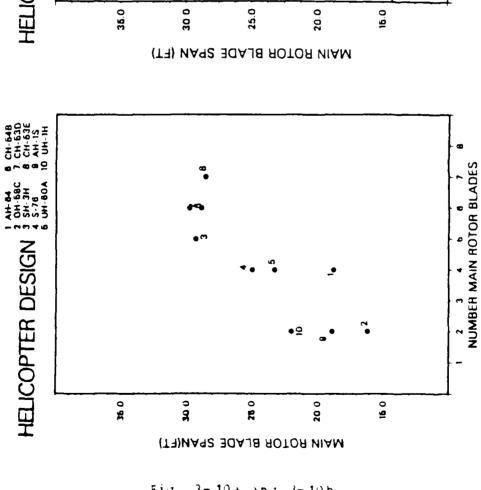


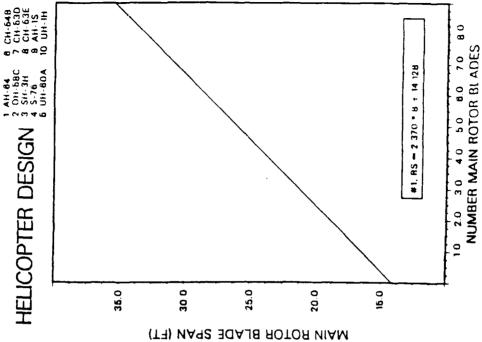
Fig. 3-7a and 3-7b.



Pig. 3-8.

Fig. 3-10a and 3-10b.





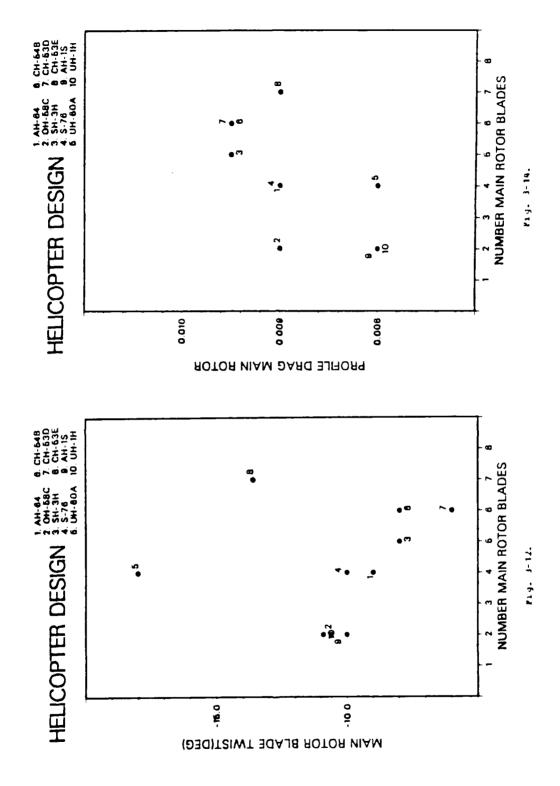
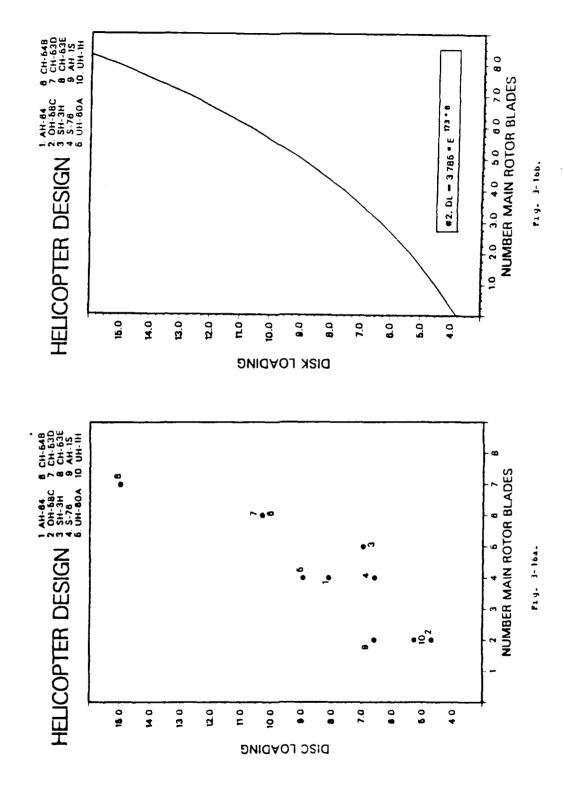


Fig. 3-12 and 3-14.



e

Fig. 3-16a and 3-16b.

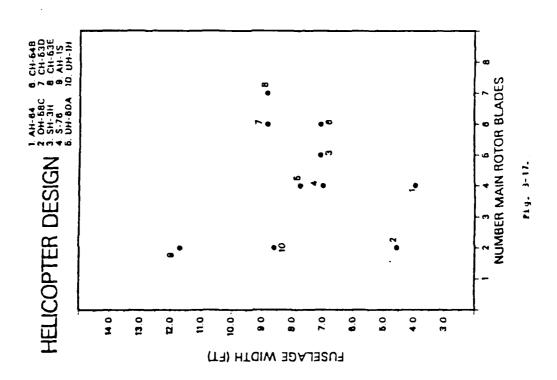


Fig. 3-17.

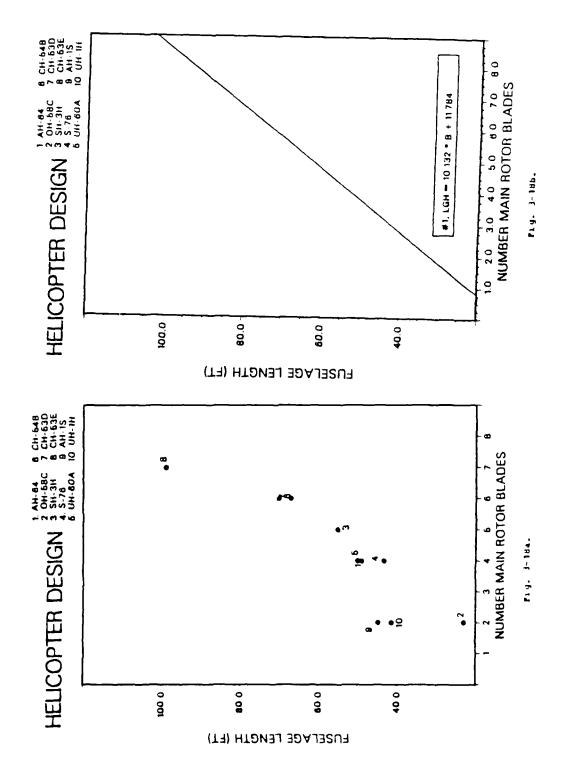
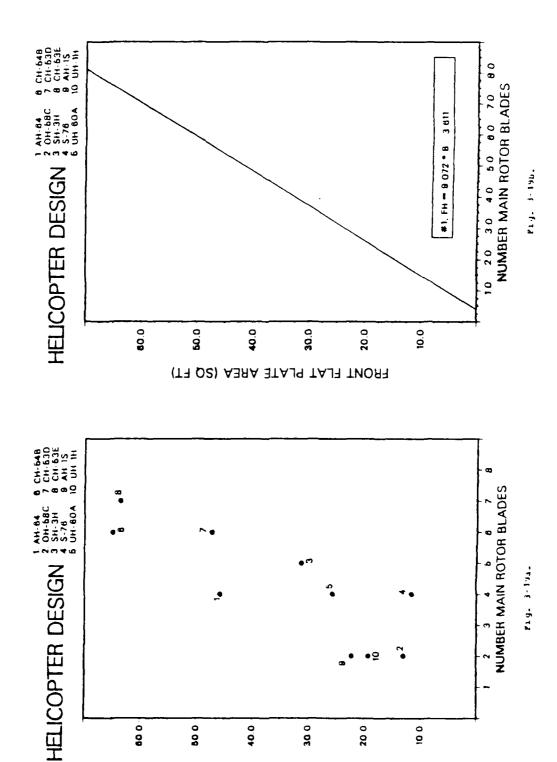


Fig. 3-18a and 3-18b.



FRONT FLAT PLATE AREA(SF)

Fig. 3-19a and 3-19b.

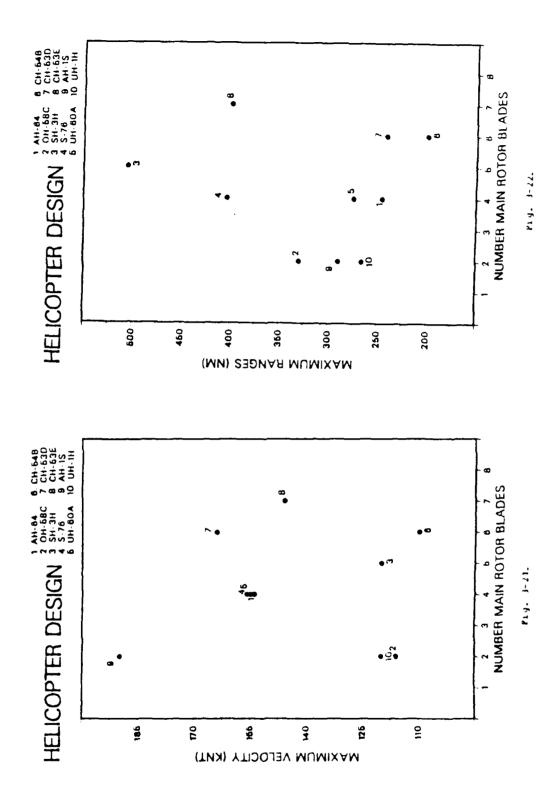
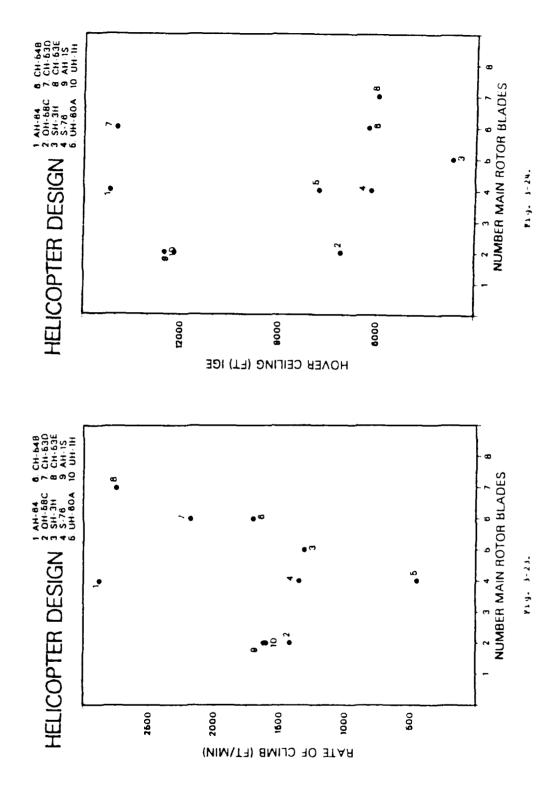
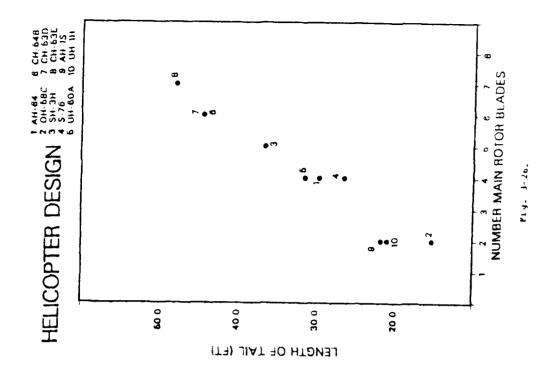


Fig. 3-21 and 3-22.



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Fig. 3-23 and 3-24.



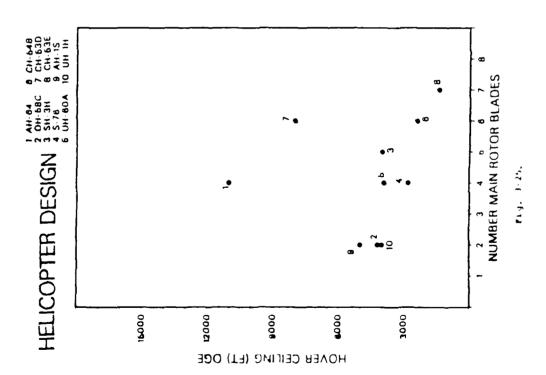


Fig. 3-25 and 3-26.

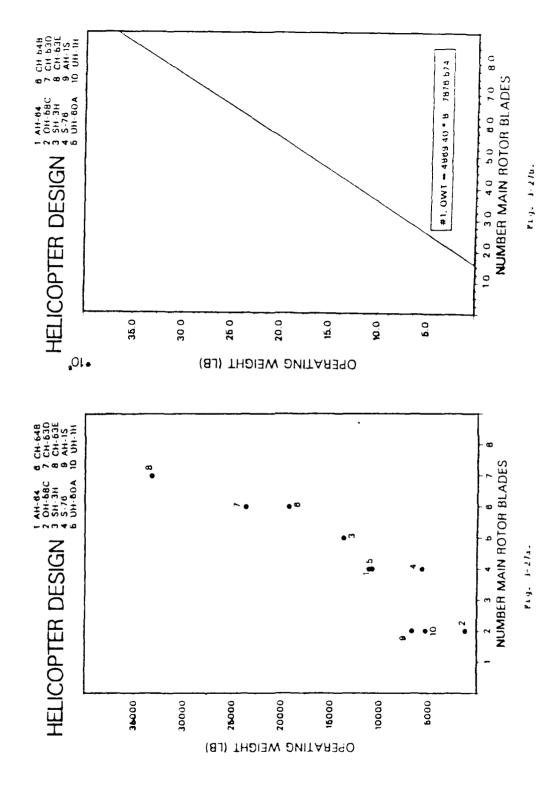
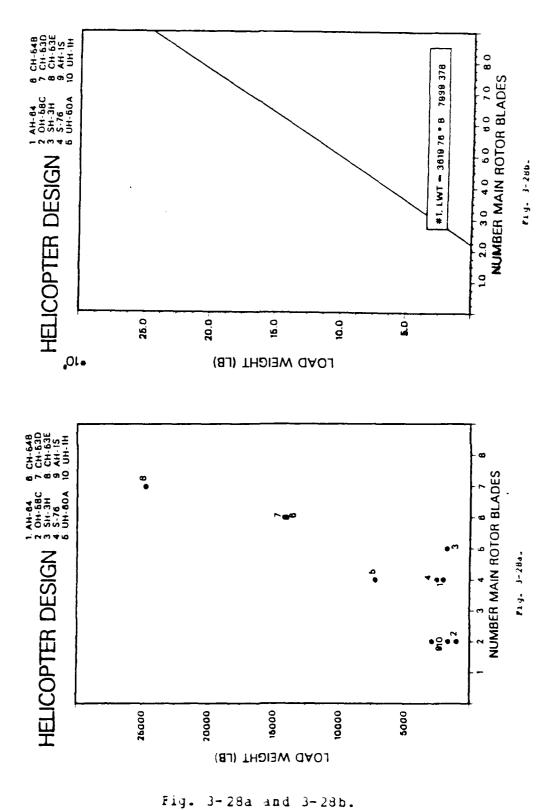
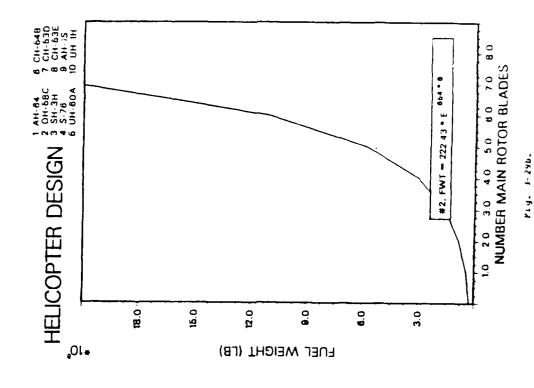


Fig. 3-27a and 3-27b.







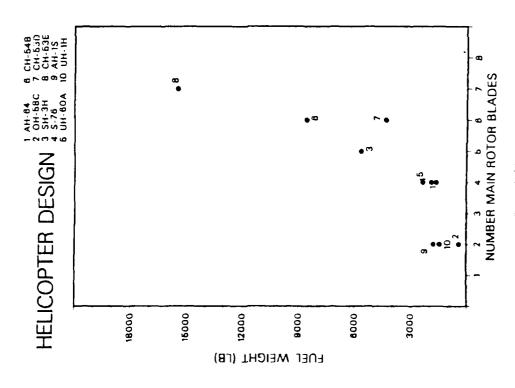
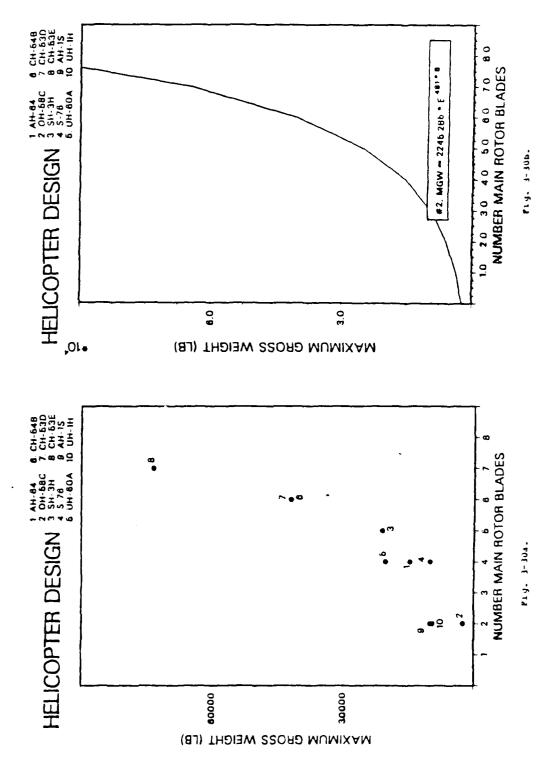


Fig. 3-29a and 3-29b.



Fig. 3-30a and 3-30b.



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Number of Tail Rotor Blades Pairings.

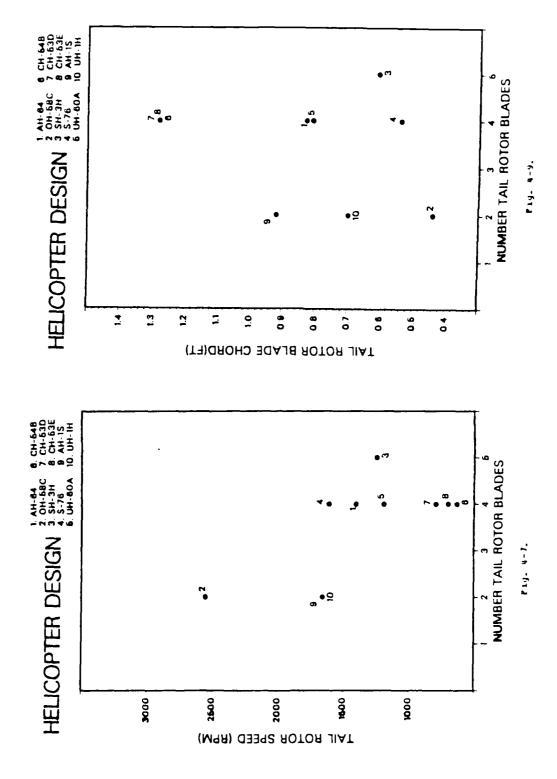


Fig. 4-7 and 4-3.

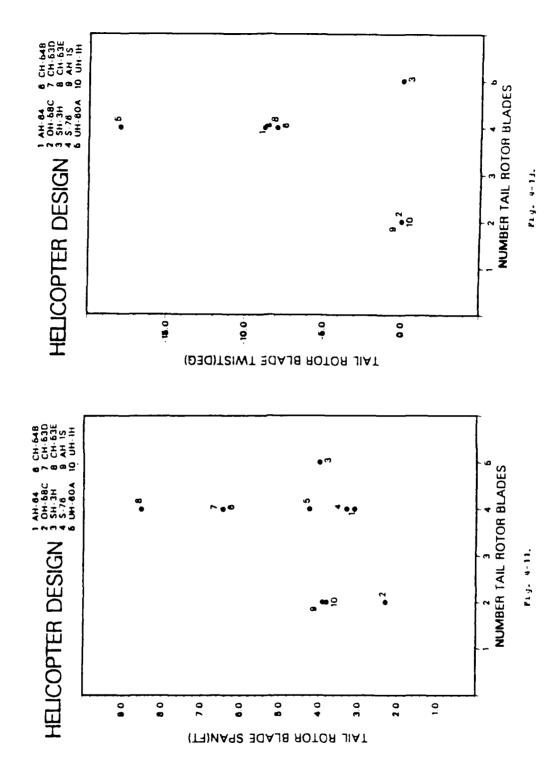
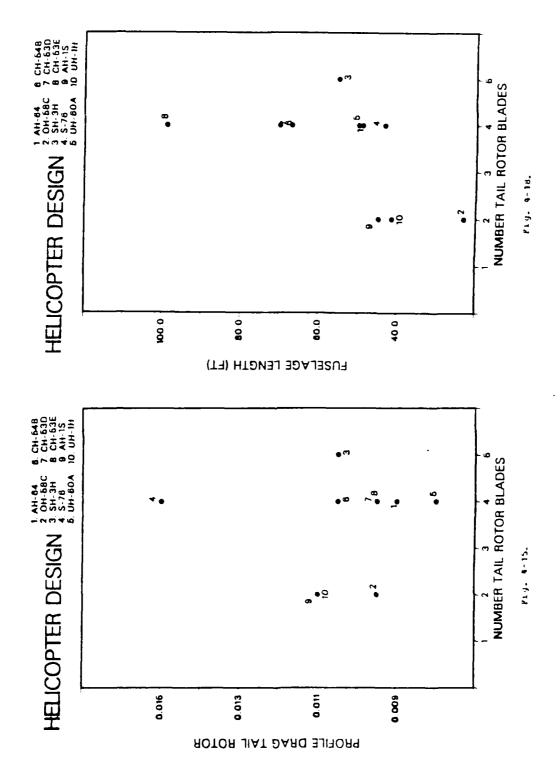


Fig. 4-11 and 4-13.



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Fig. 4-15 and 4-18.

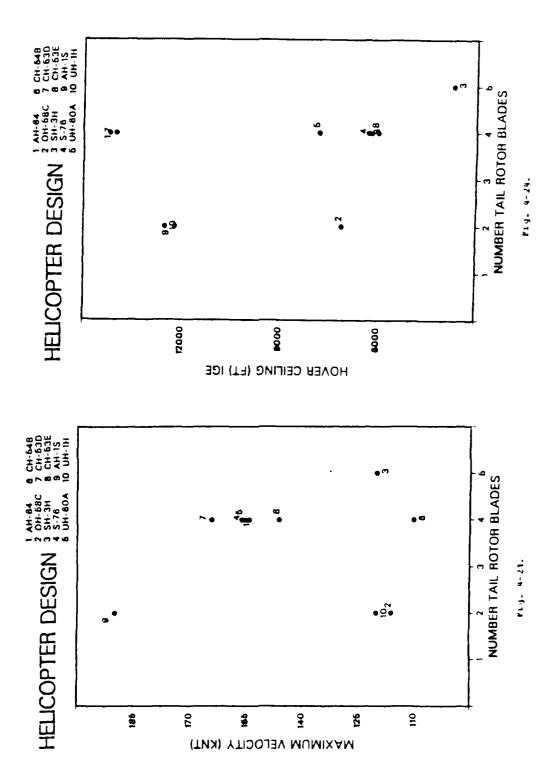
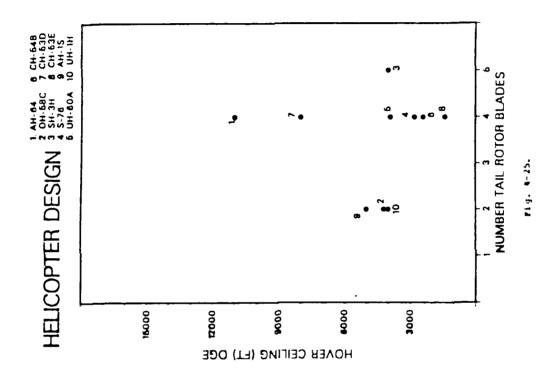


Fig. 4-21 and 4-24.



Pig. 4-25.

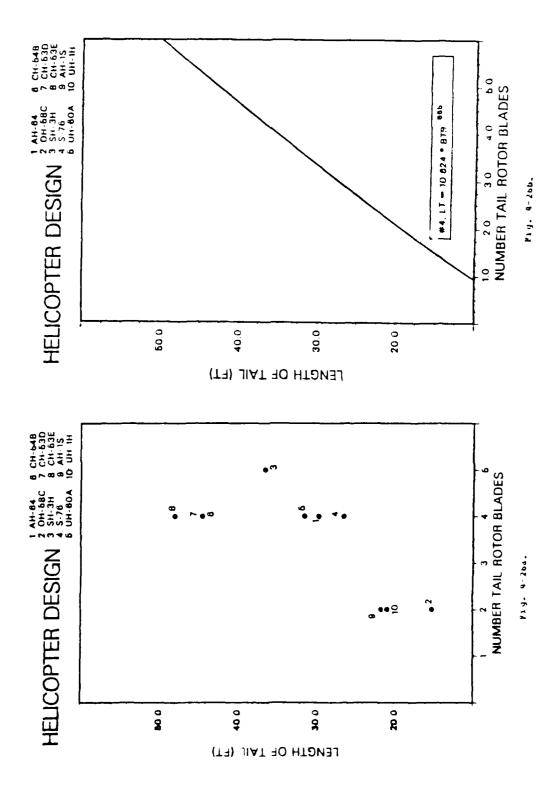
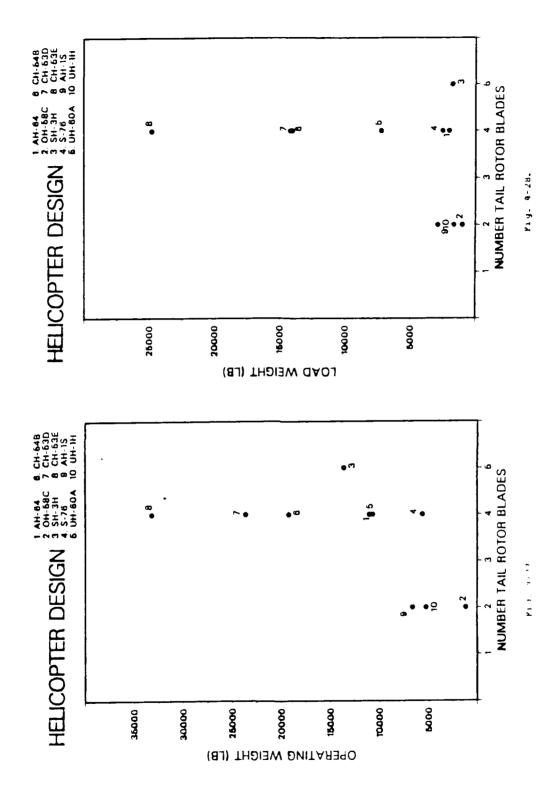


Fig. 4-25a and 4-26b.

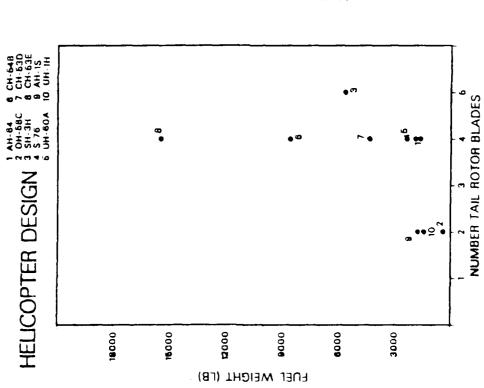


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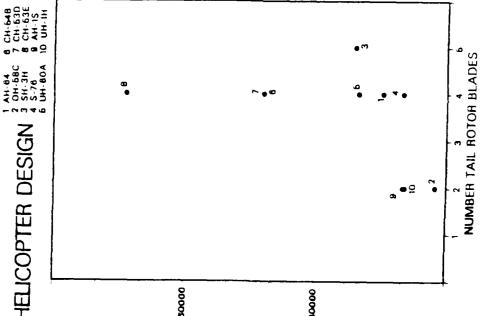
Fig. 4-27 and 4-28.



Fig. 4-29 and 4-30.

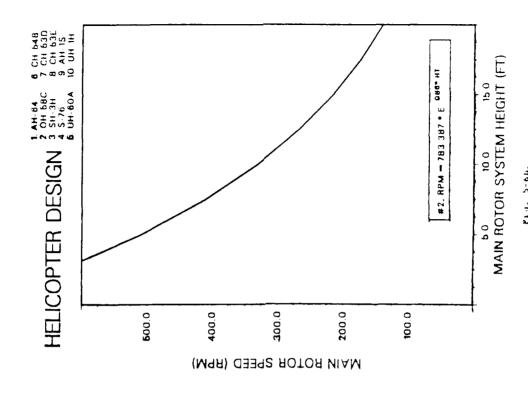


MAXIMUM GROSS WEIGHT (LB)

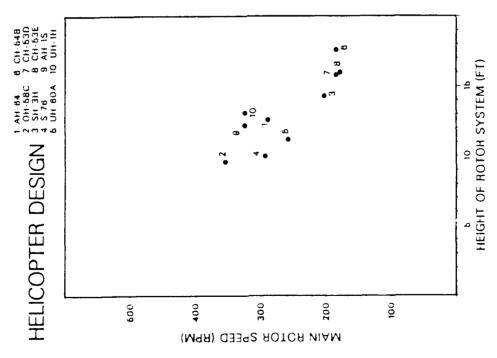


HELICOPTER DESIGN

Height of Main Rotor System Pairings.

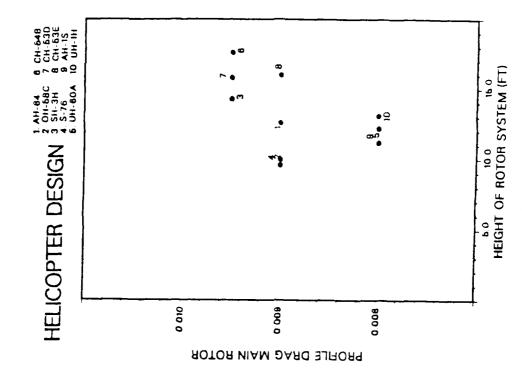


G.



P19. 5-64.

Fig. 5-ba and 5-bb.



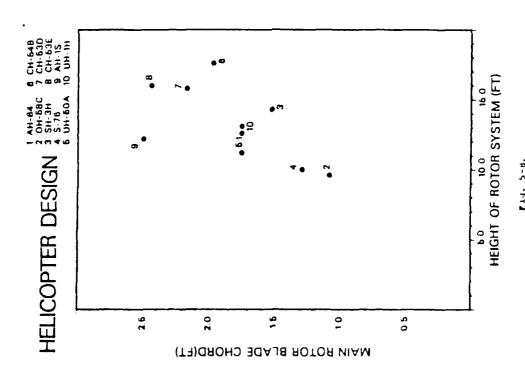
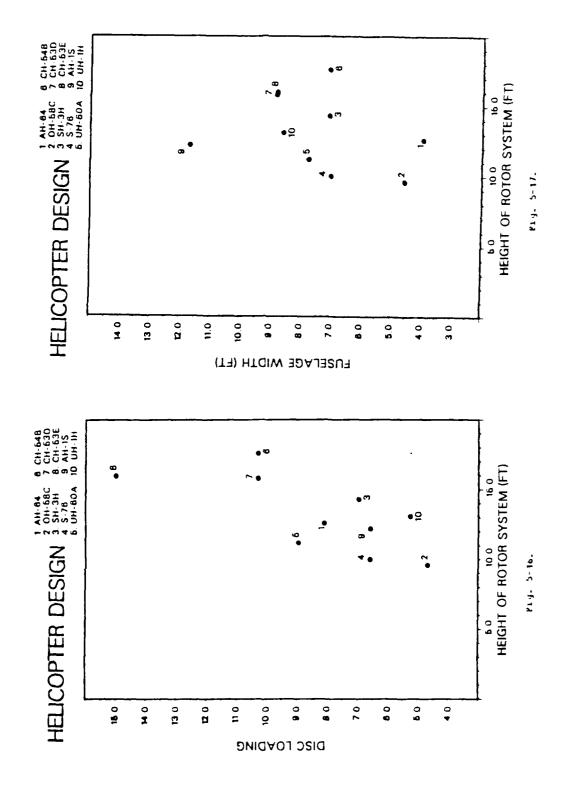
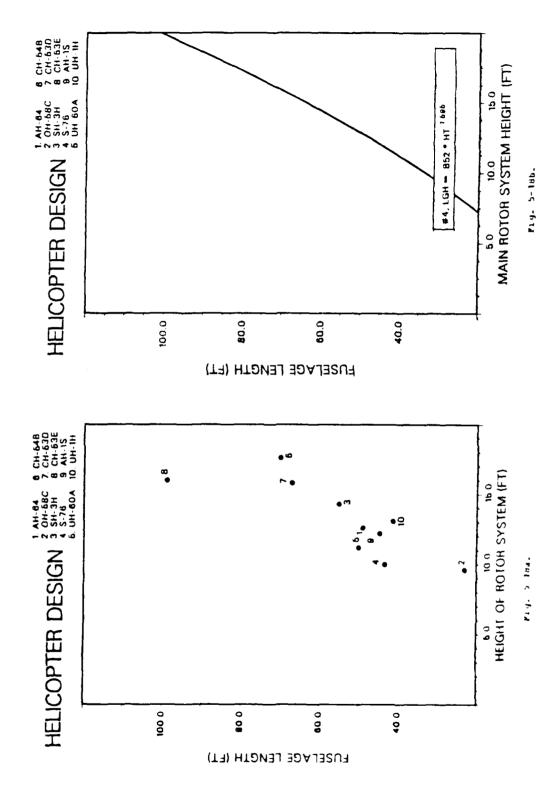


Fig. 5-8 and 5-14.



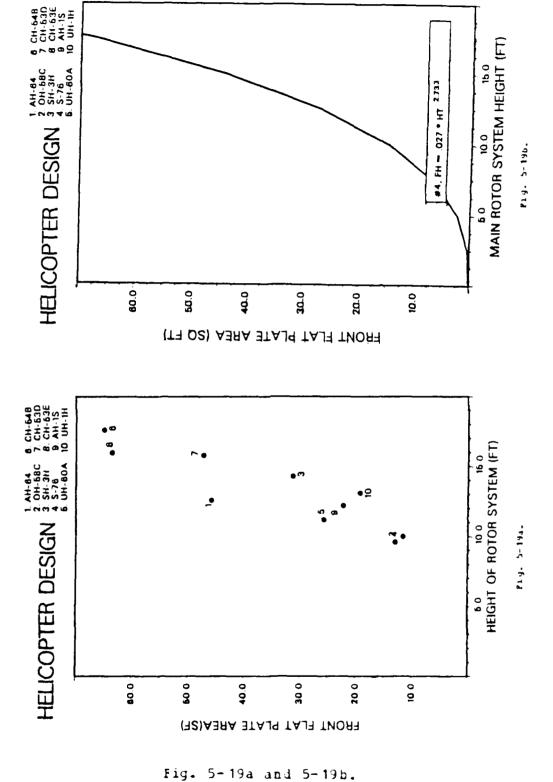
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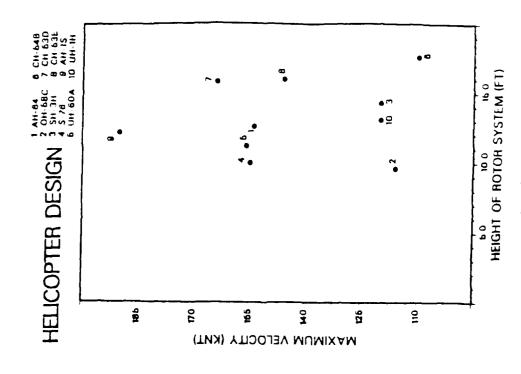
Fig. 5-16 and 5-17.



I

Fig. 5-18a and 5-182.





G

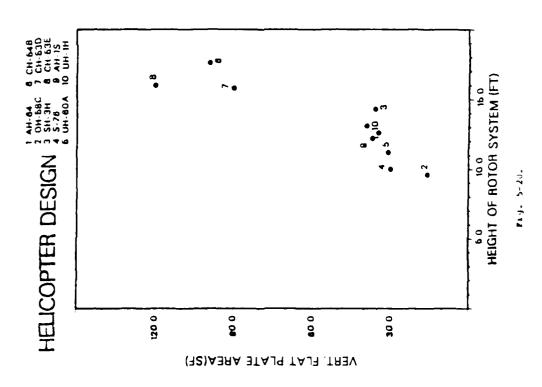


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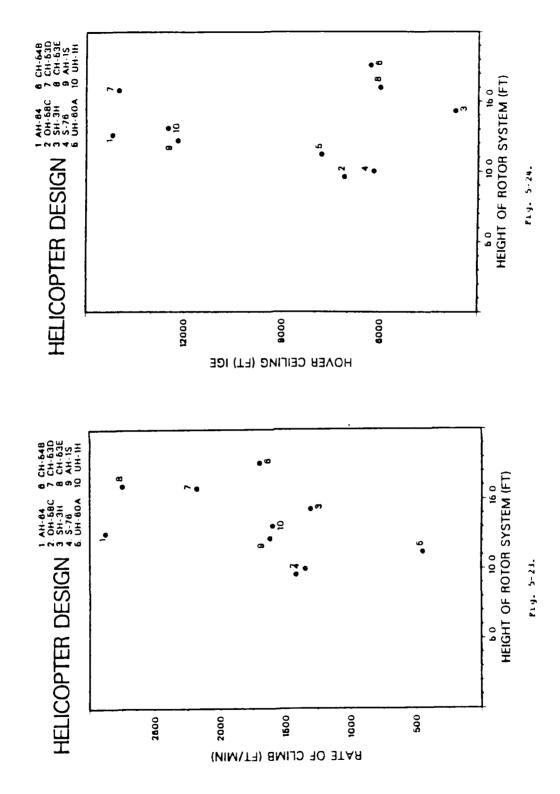
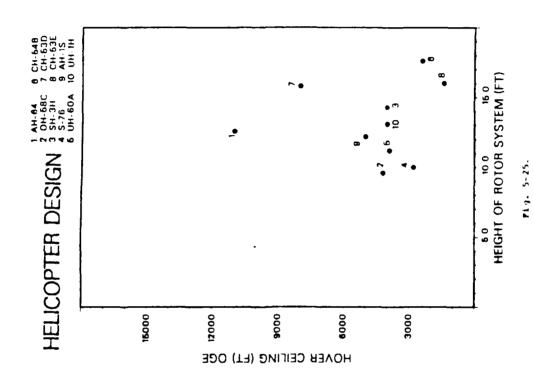


Fig. 5-23 and 5-24.



C

Fig. 5-25.

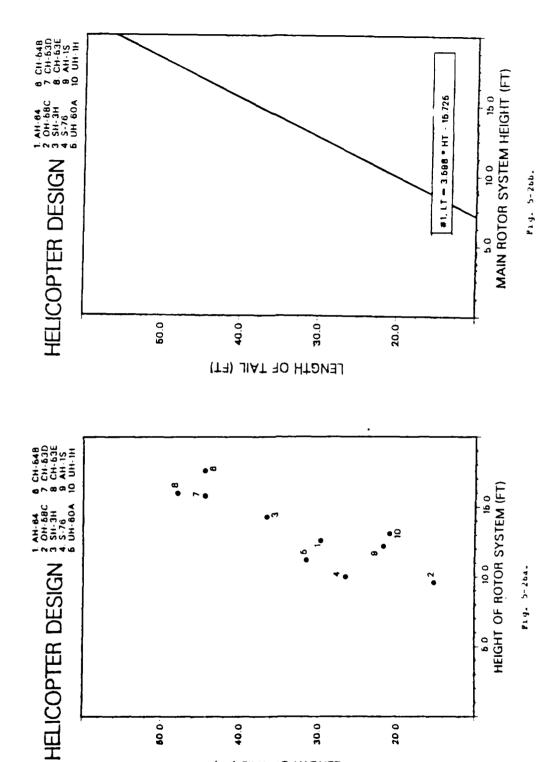


Fig. 5-26a and 5-26b.

LENGTH OF TAIL (FT)

20 0

40.0

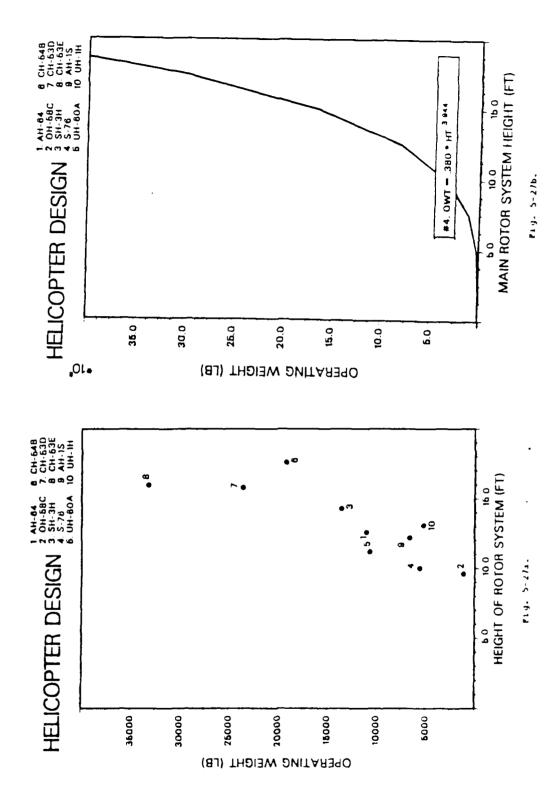
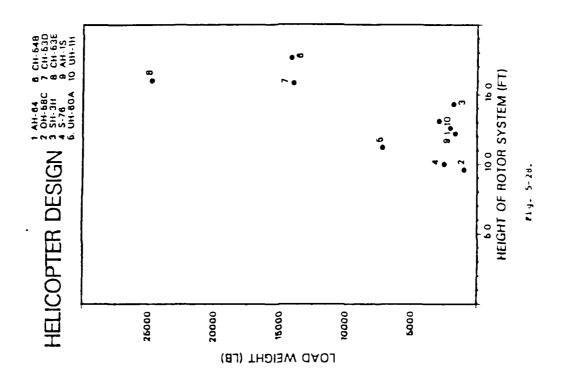


Fig. 5-27a and 5-27b.



Pig. 5-28.

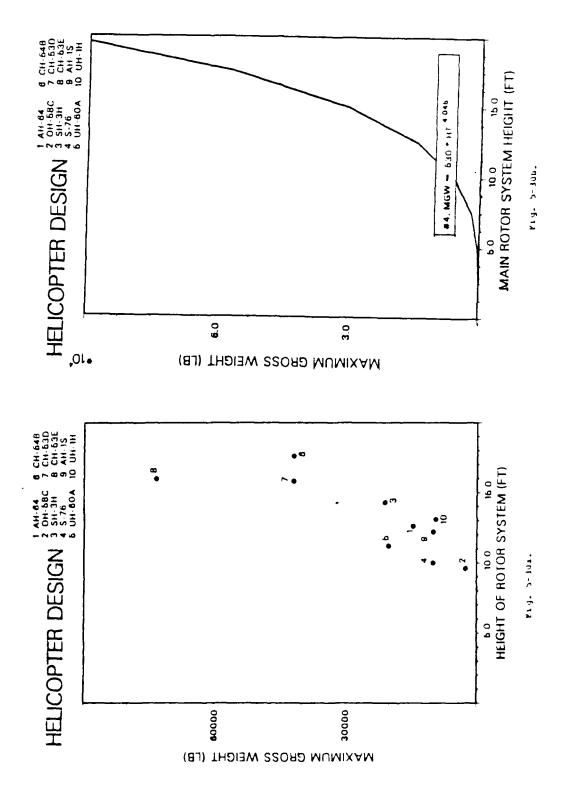


Fig. 5-30a and 5-30b.

Speed of Main Rotor Pairings.

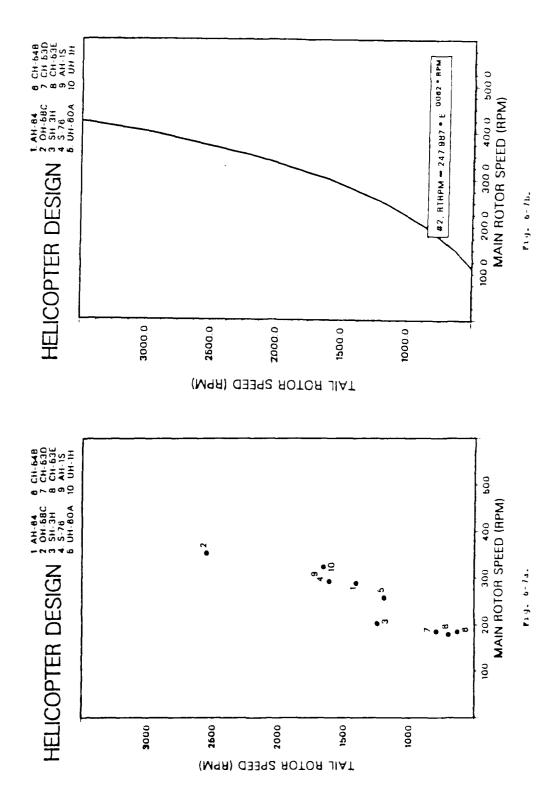


Fig. 6-7a and 5-7b.

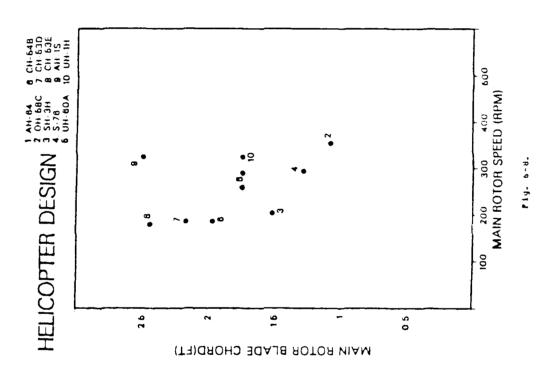


Fig. 5-8.

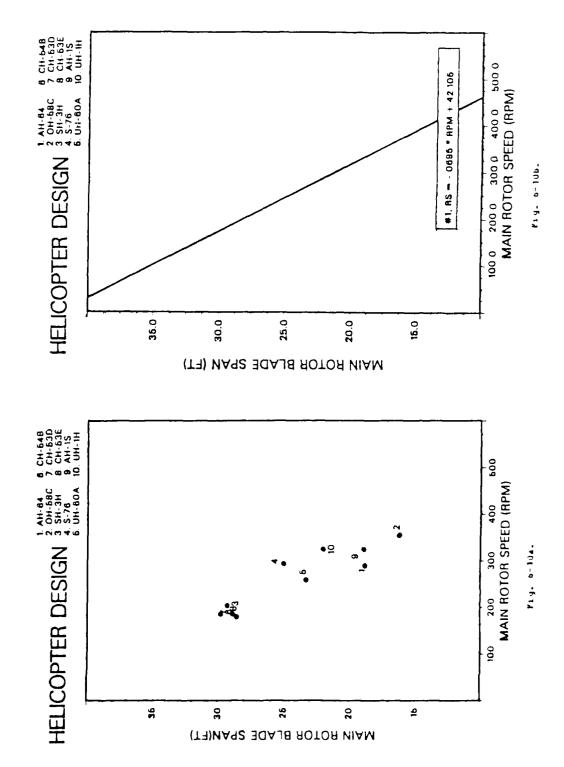
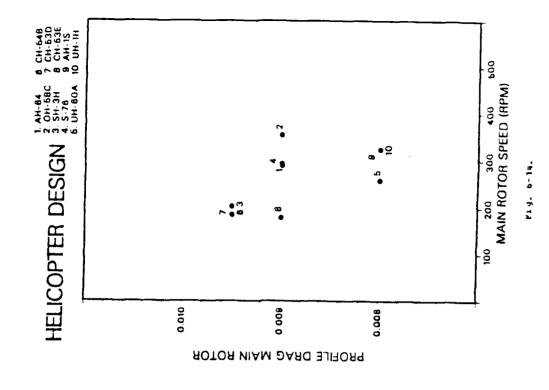


Fig. 6-10a and 6-10p.



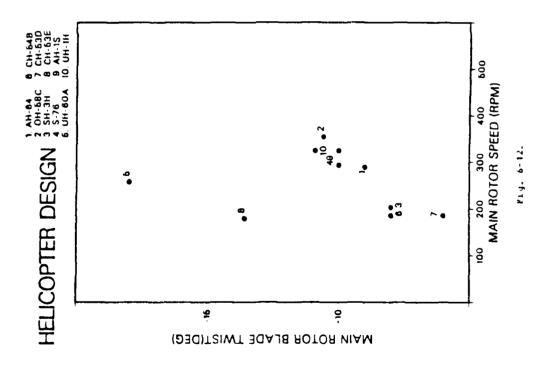


Fig. 6-12 and 6-14.

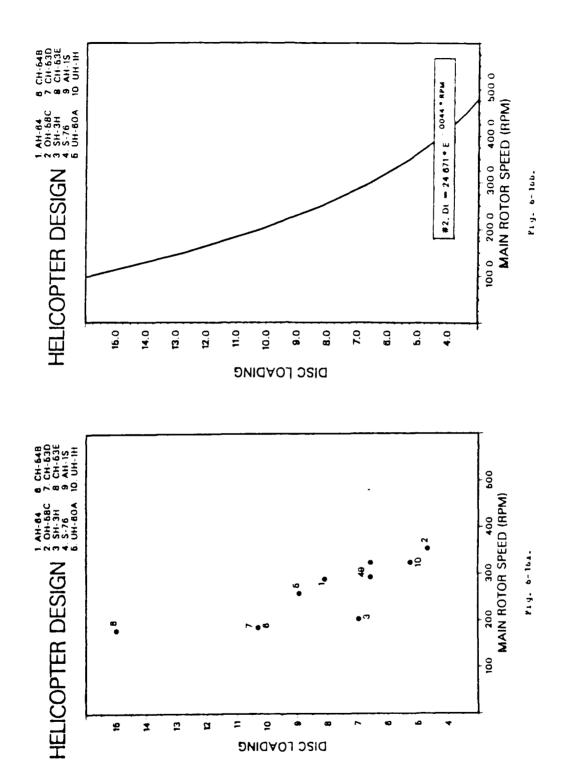
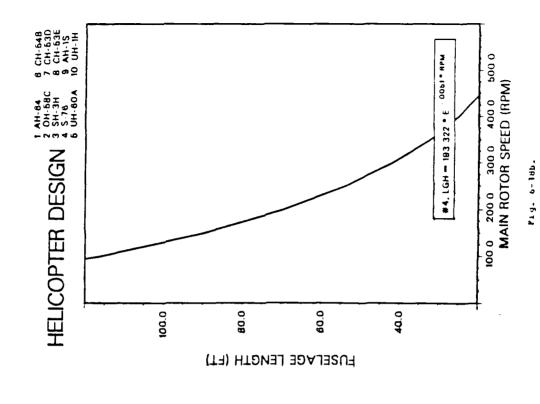
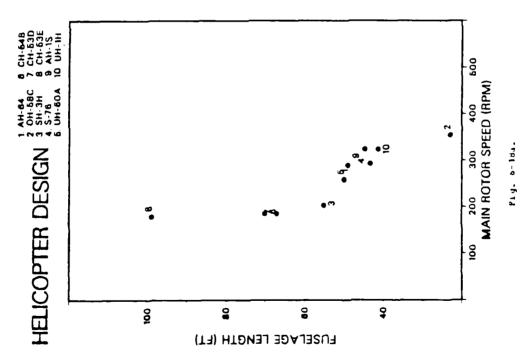


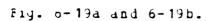
Fig. 6-16a and 6-16b.

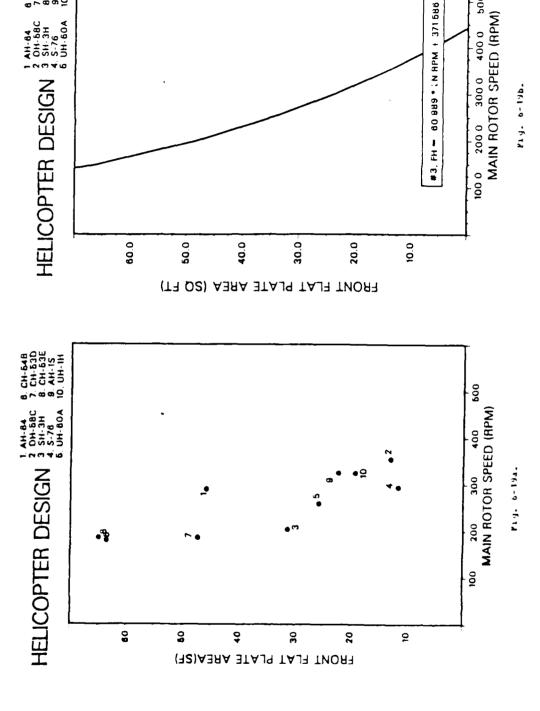




O

Fig. 6-18a and 6-18b.





8 CH-548 7 CH-530 8 CH-53E 9 AH-15 10 UH-111

1 AH-84 2 OH-68C 3 SH-3H 4 S-76 6 UH-60A

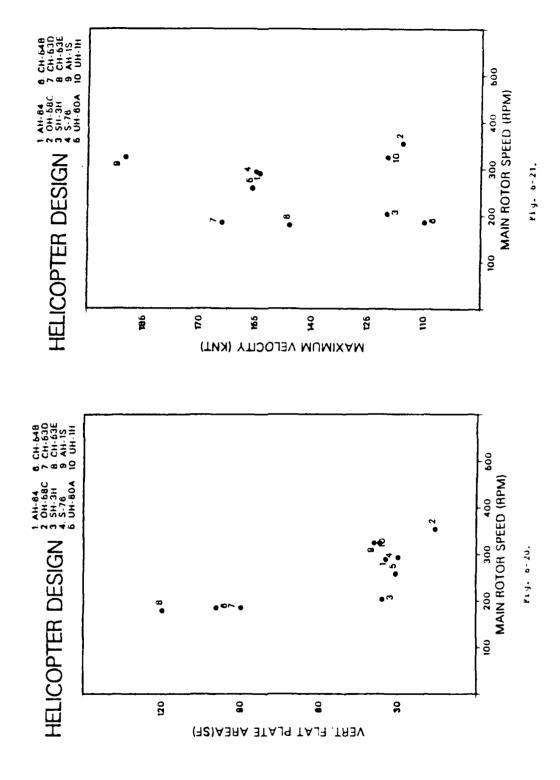
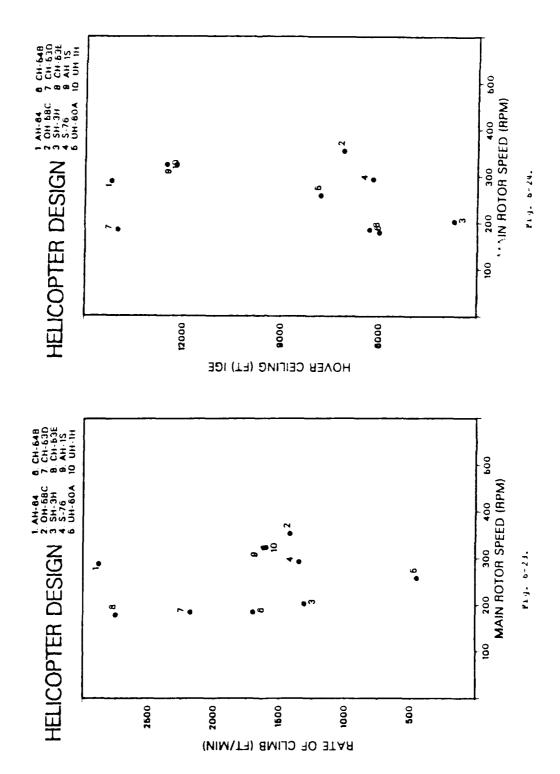


Fig. 6-20 and 6-21.



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Fig. 6-23 and 6-24.

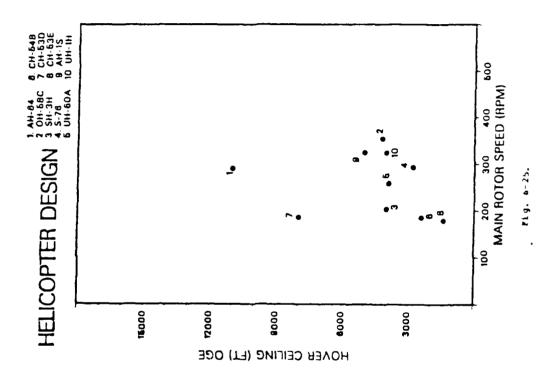
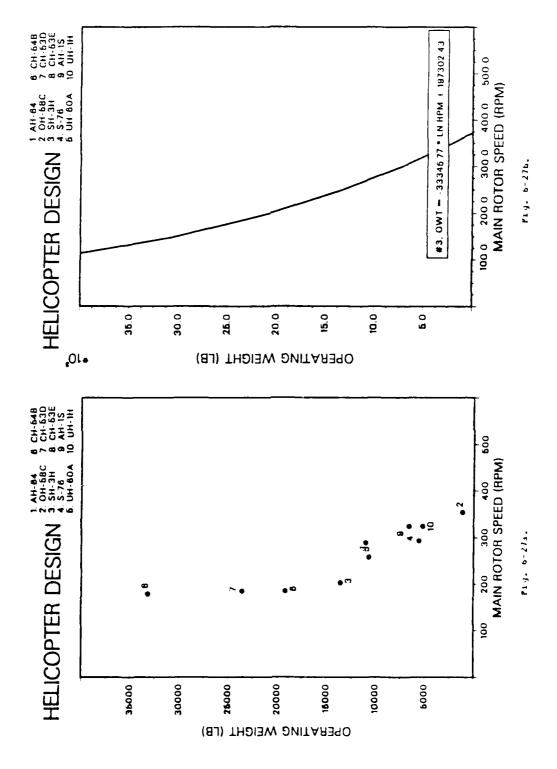


Fig. 6-25.



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Fig. 6-27a and b-27b.

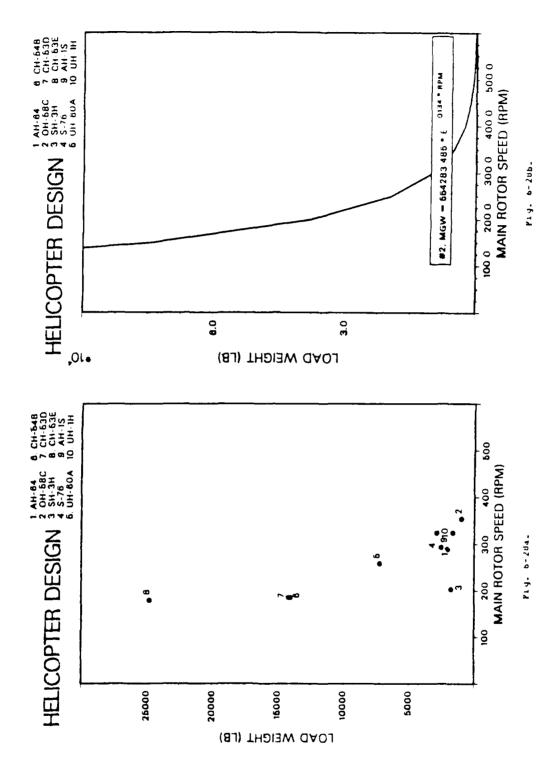
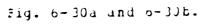
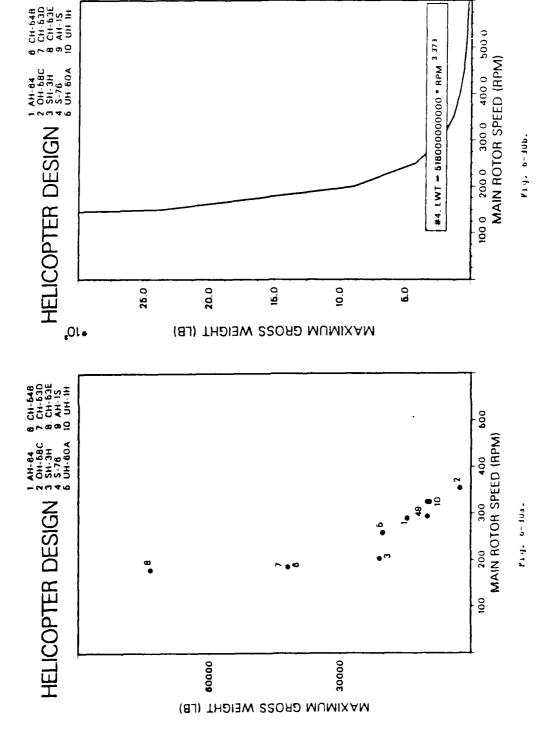
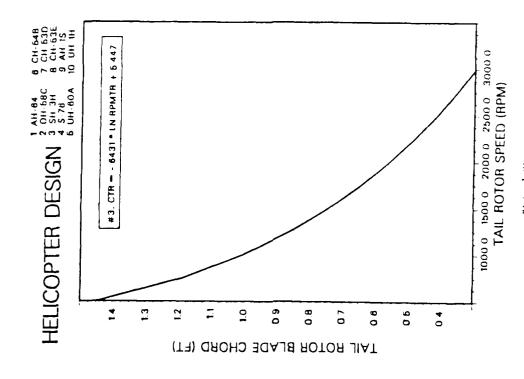


Fig. b-28a and 6-23b.





Speed of Tail Rotor Radius Pairings.



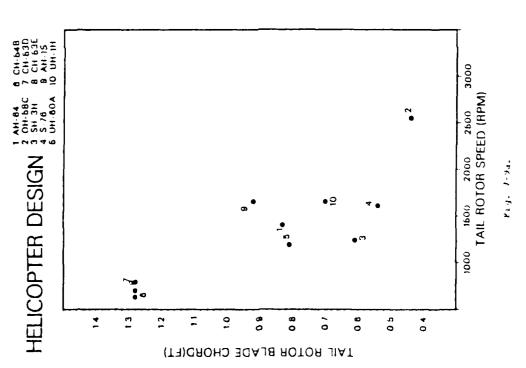
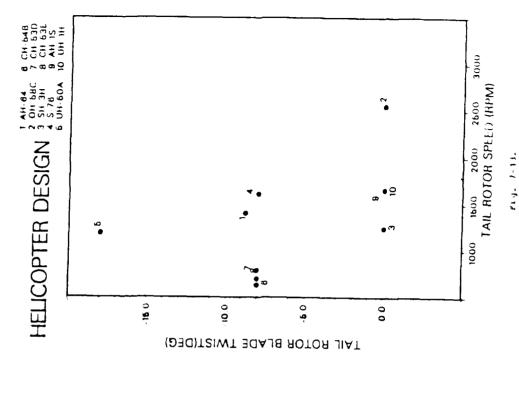
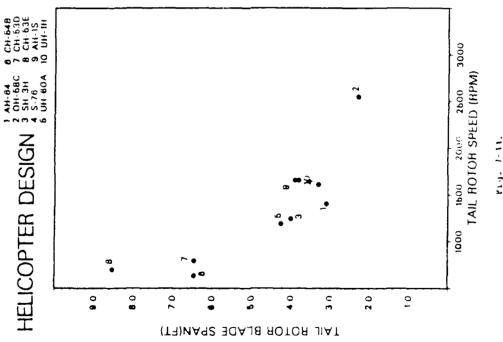


Fig. 7-9a and 7-9p.





Eig. 7-11 and 7-13.

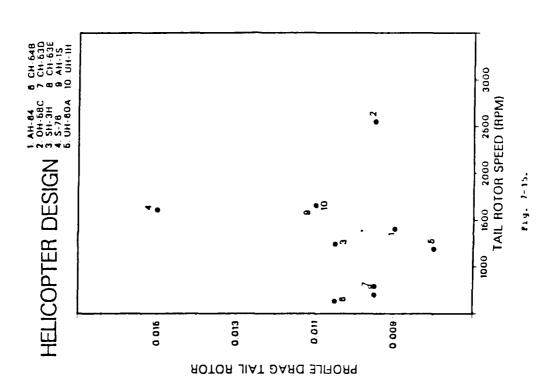
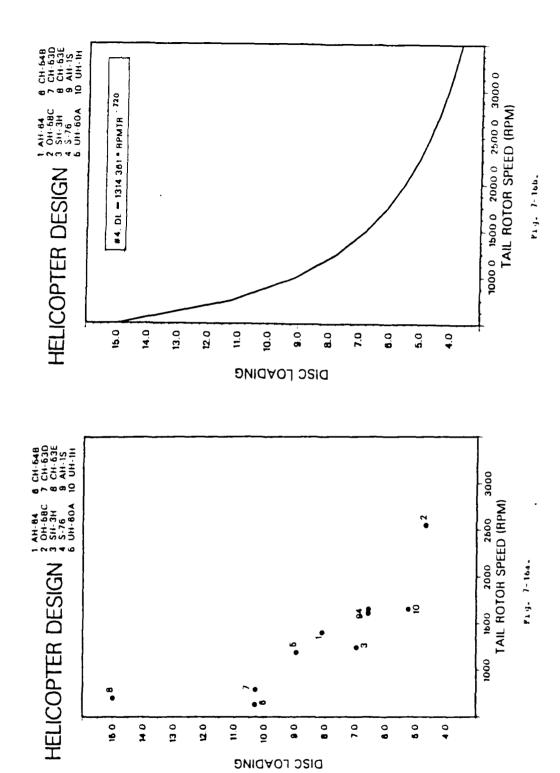
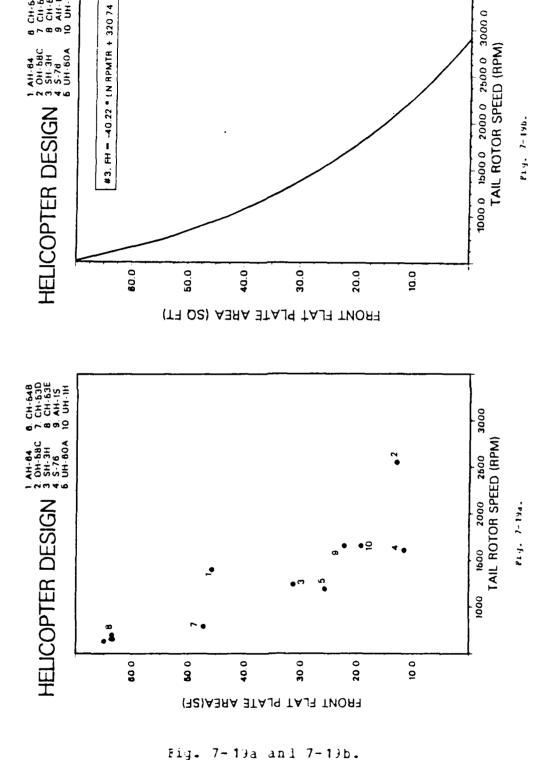


Fig. 7-15.



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Fig. 7-10a and 7-10b.



8 CH-648 7 CH-630 8 CH-63E 9 AH-15 10 UH-1H

1. AH-84 2. OH-68C 3. SH-3H 4. S-78 6. UH-60A

P1 4. 7-19b.

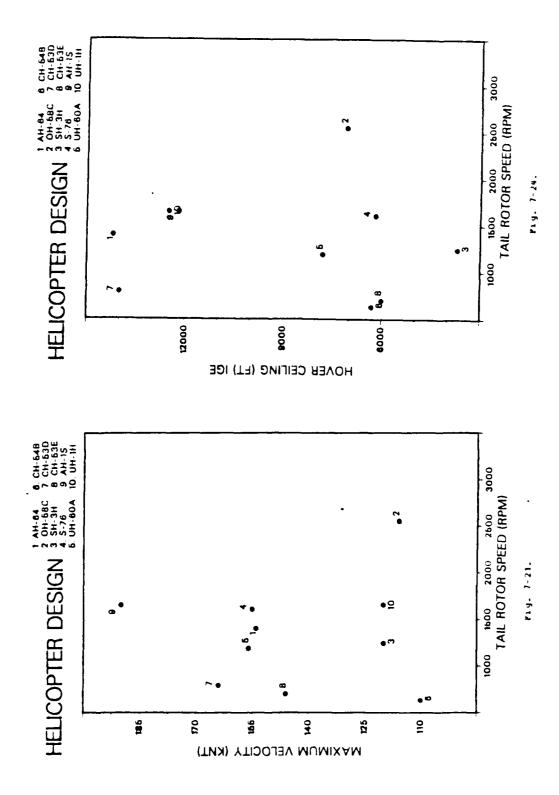


Fig. 7-21 and 7-24.

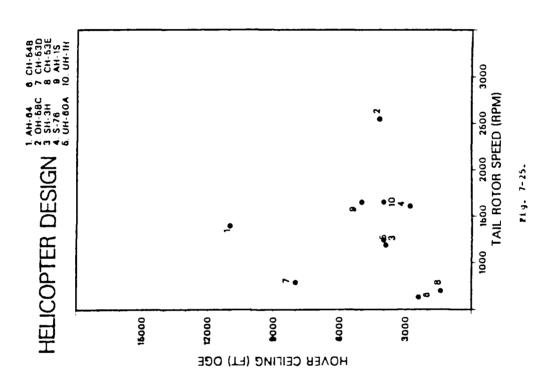
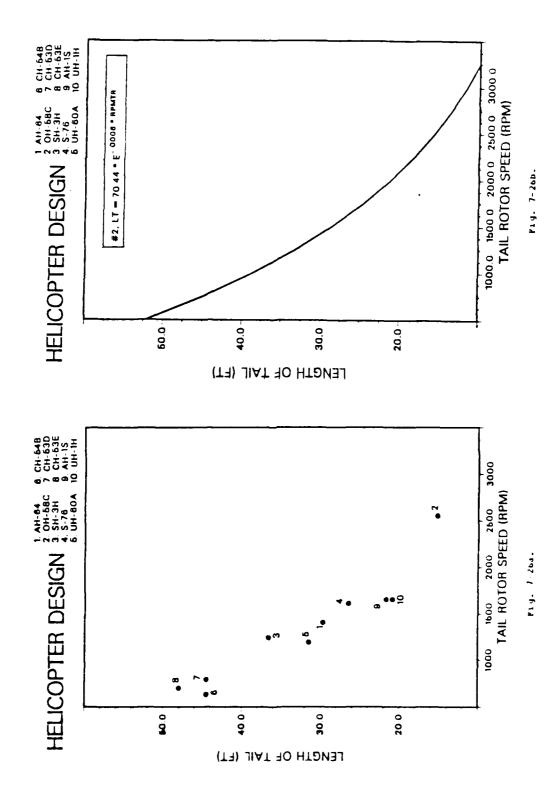


Fig. 7-25.



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Fig. 7-26a and 7-25b.

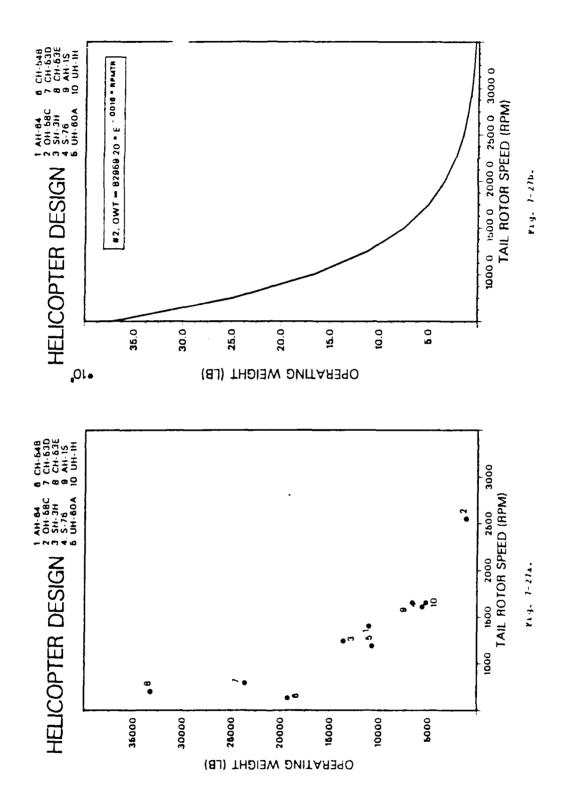
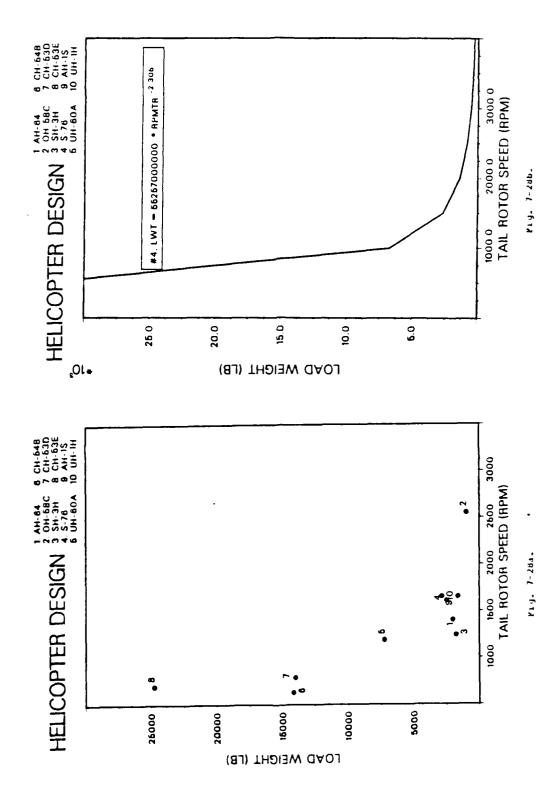


Fig. 7-27a and 7-27b.



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Fig. 7-28a and 7-28b.

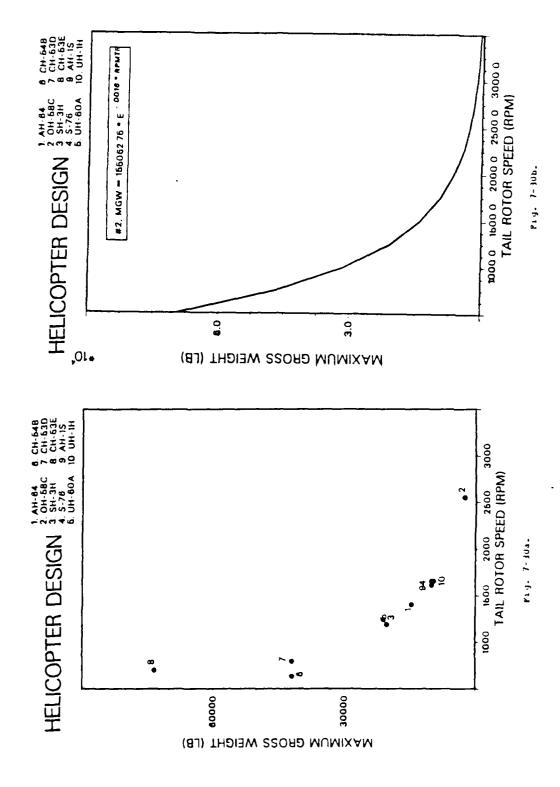


Fig. 7-30a anu 7-30b.

Chord of Main Rotor Blade Pairings.



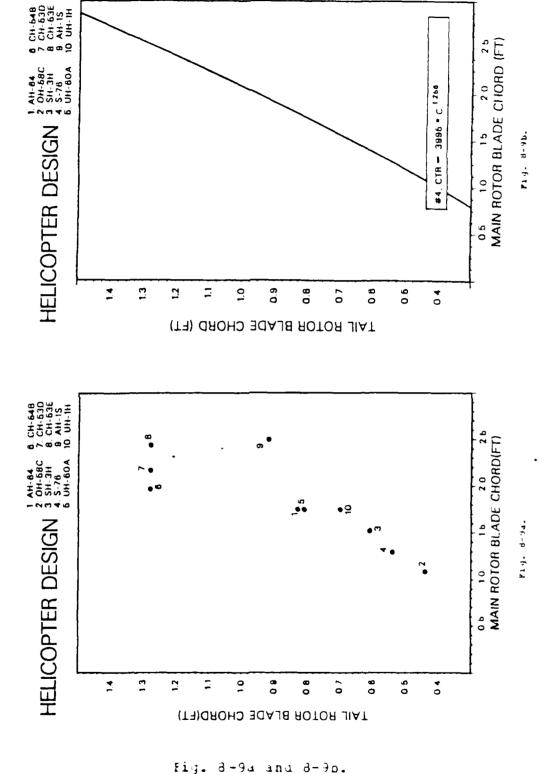
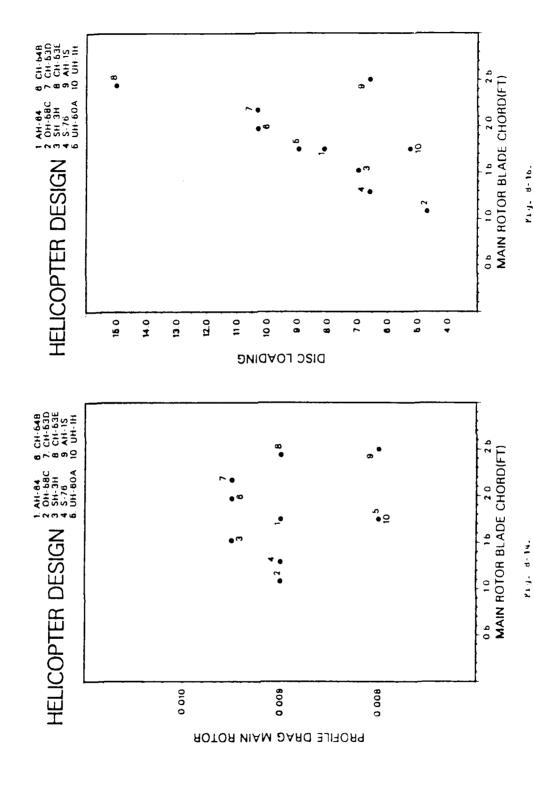


Fig. 8-10 and 8-12.

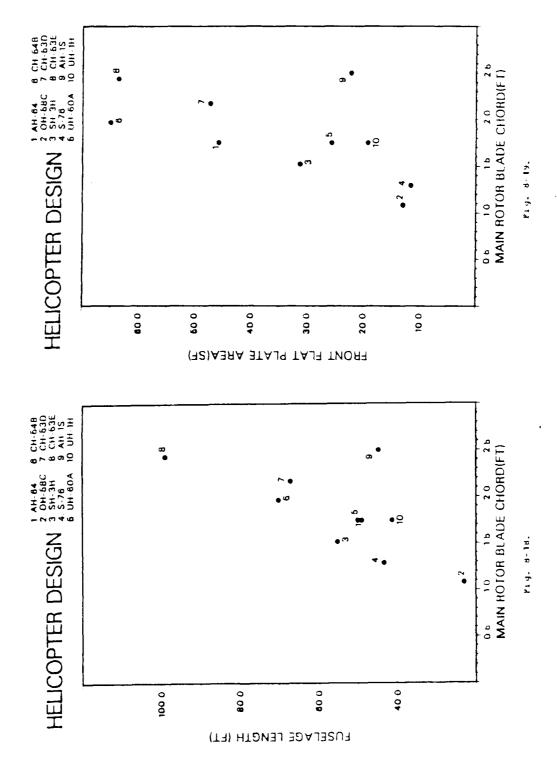


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Fig. 8-14 and 8-16.



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Fig. 3-16 and 3-19.

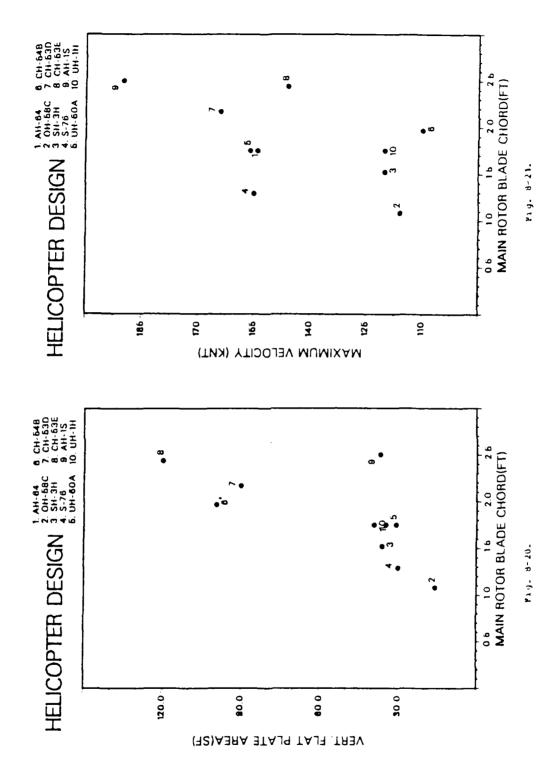
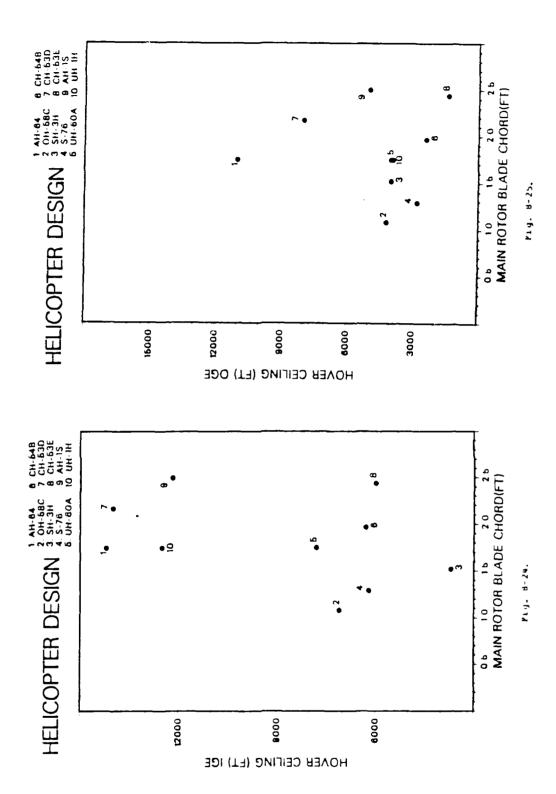


Fig. 8-20 and 3-21.



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Fig. 8-24 and 8-25.

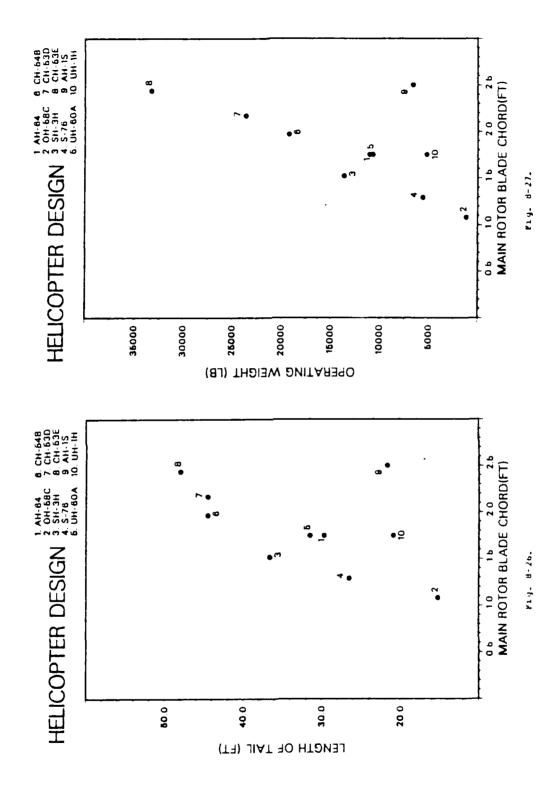


Fig. 8-26 and 8-27.

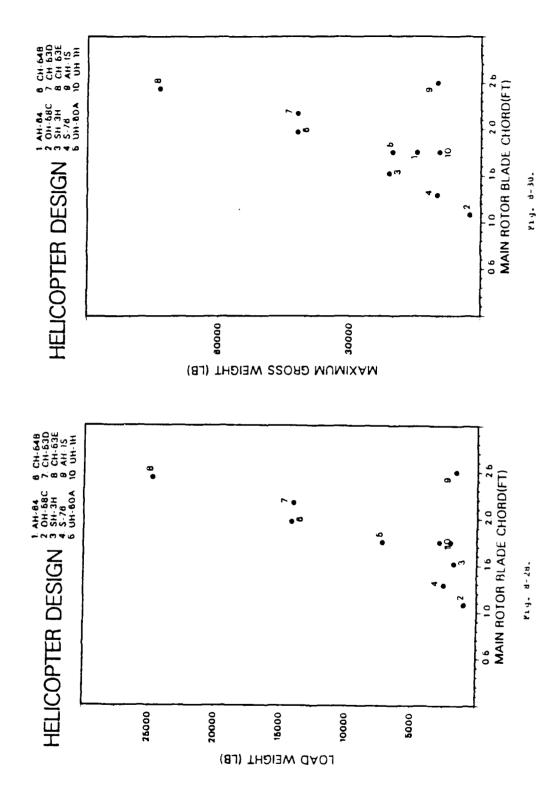
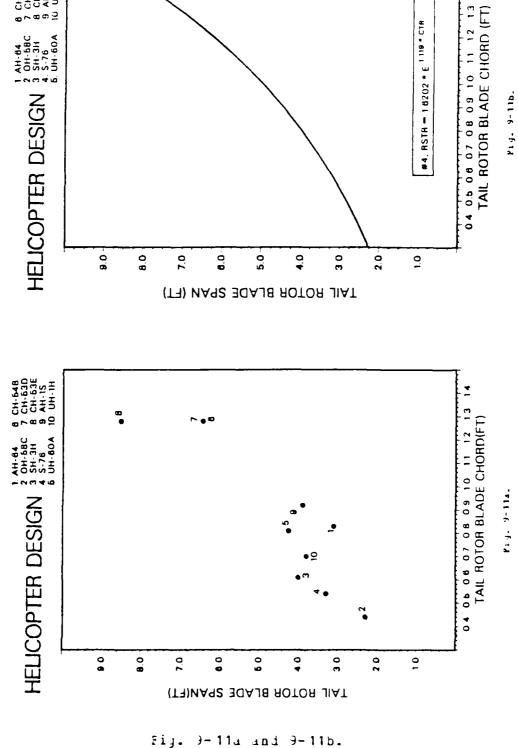


Fig. 8-28 and 8-30.

Chord of Tail Rotor Blade Pairings.





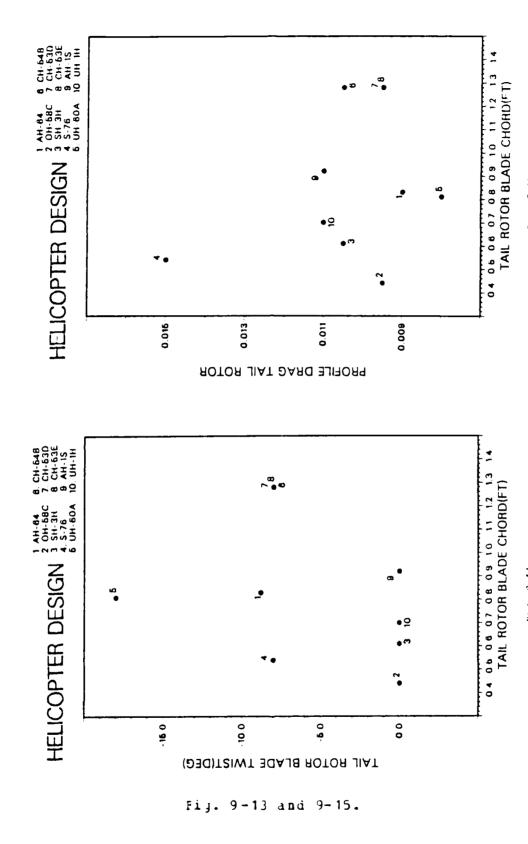
8 CH-648 7 CH-63D 8 CH-63E 9 AH-1S 10 UH-1H

1. AH-84 2. OH-58C 3. SH-3H 4. S-76 5. UH-60A

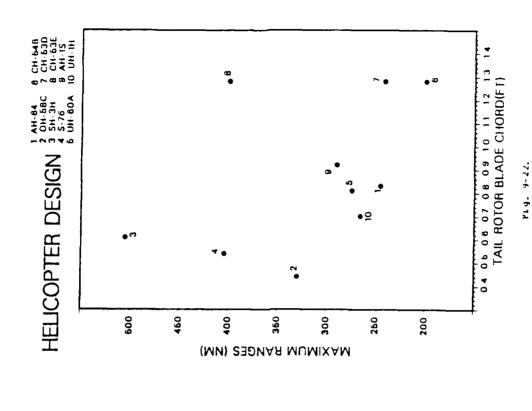
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P19. 9-11b.



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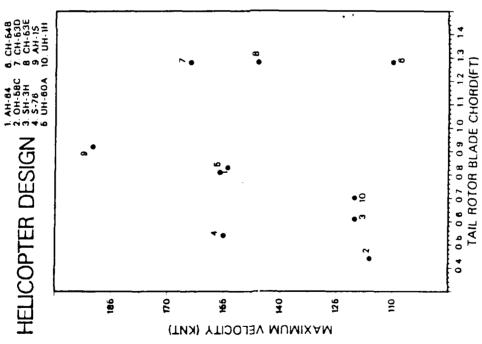


Fig. 9-21 and 9-22.

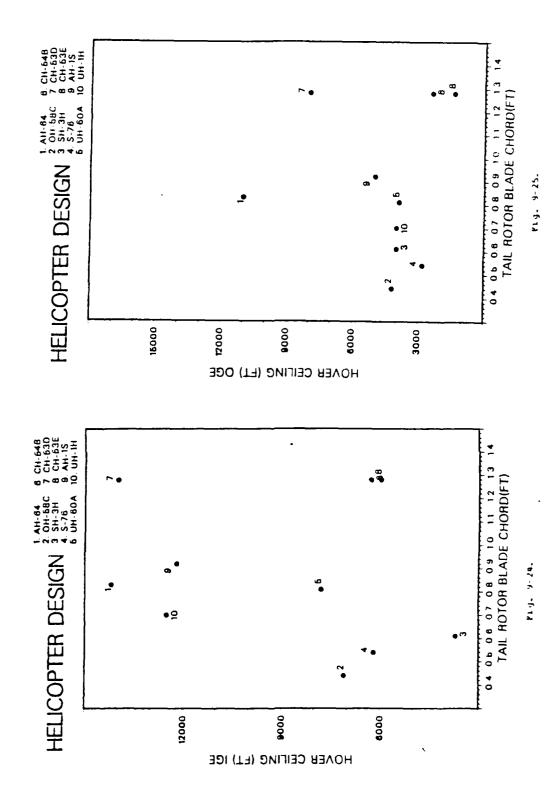


Fig. 9-24 and 9-25.

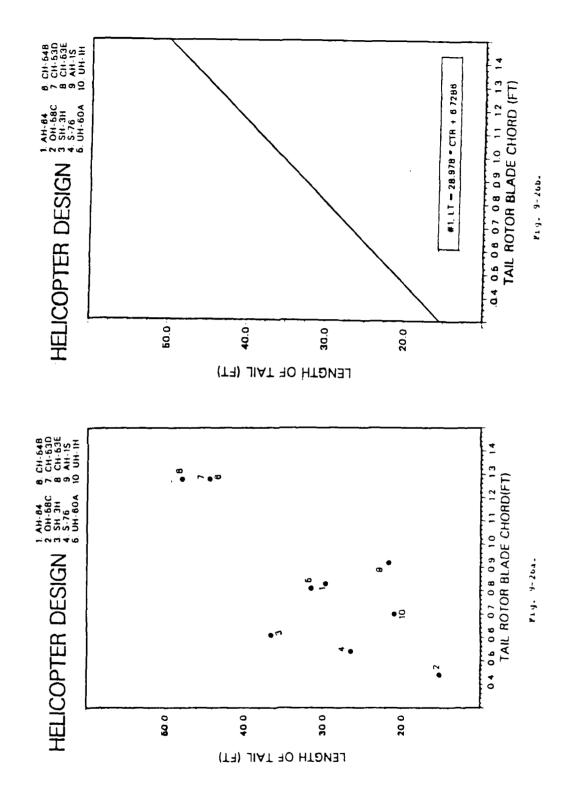


Fig. 9-26a and 9-25b.

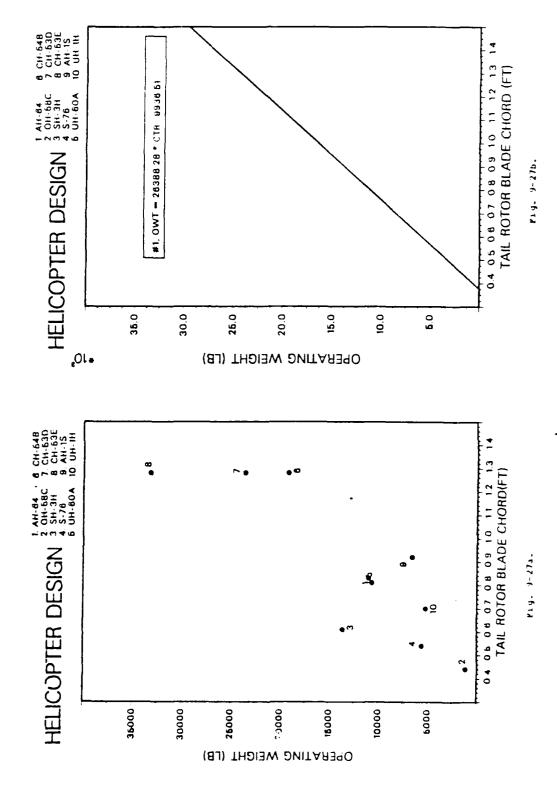
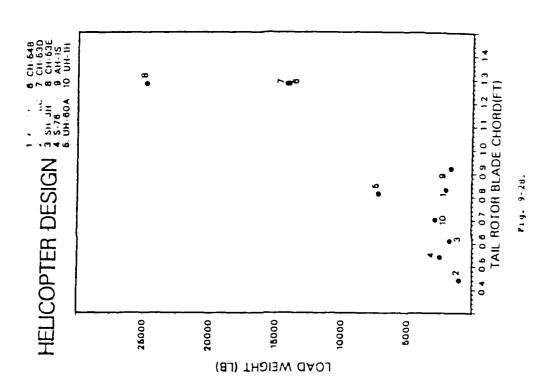
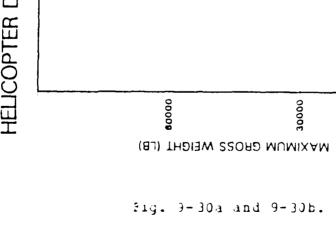
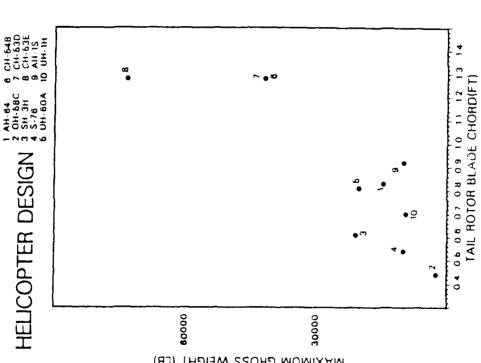


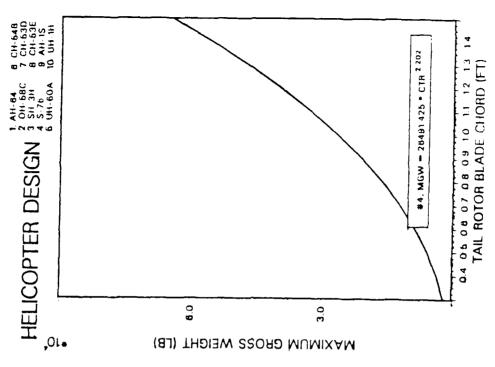
Fig. 9-27a and 9-27b.



Pig. 9-28.

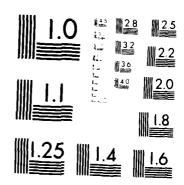






Span of Main Rotor Pairings.

DETERMINATION OF QUANTITATIVE RELATIONSHIPS BETWEEN SELECTED CRITICAL HELICOPTER DESIGN PARAMETERS(U) NAVAL POSTGRADUATE SCHOOL MONTEREY CA R S PETRICKA SEP 84 F/G 1/3 AD-A152 034 3/4 UNCLASSIFIED NL



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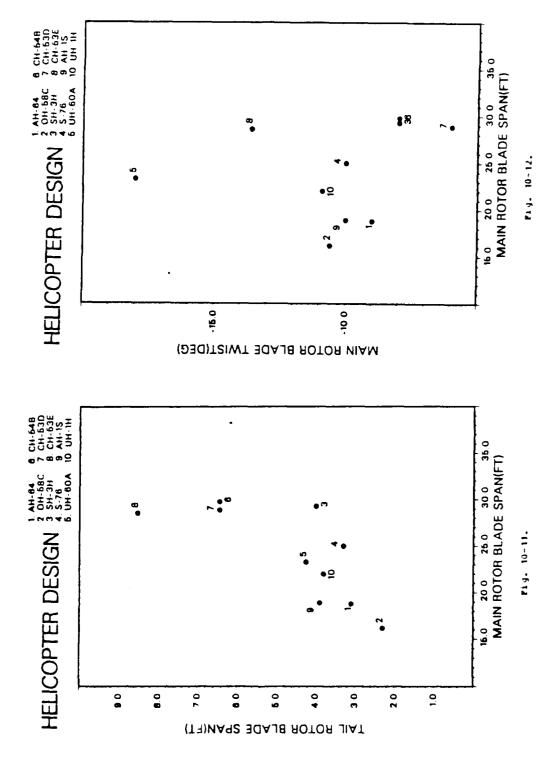


Fig. 10-11 and 10-12.

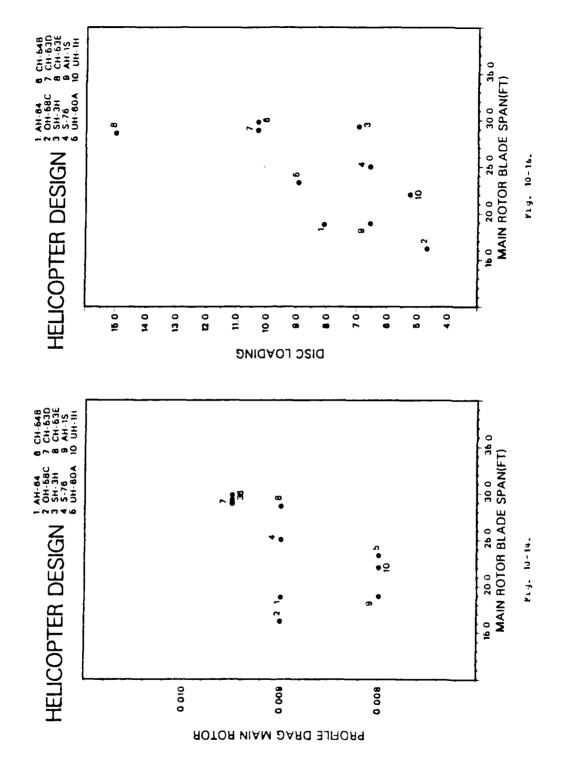
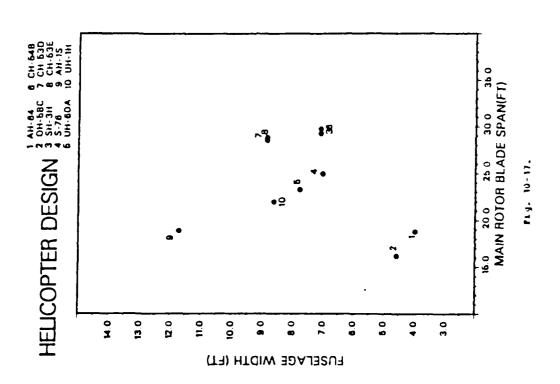


Fig. 10-14 and 10-16.



Pig. 10-17.

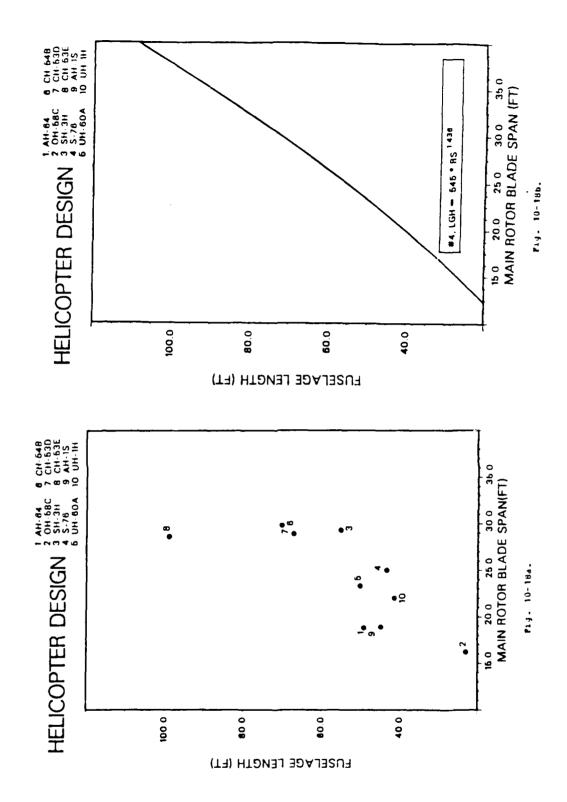
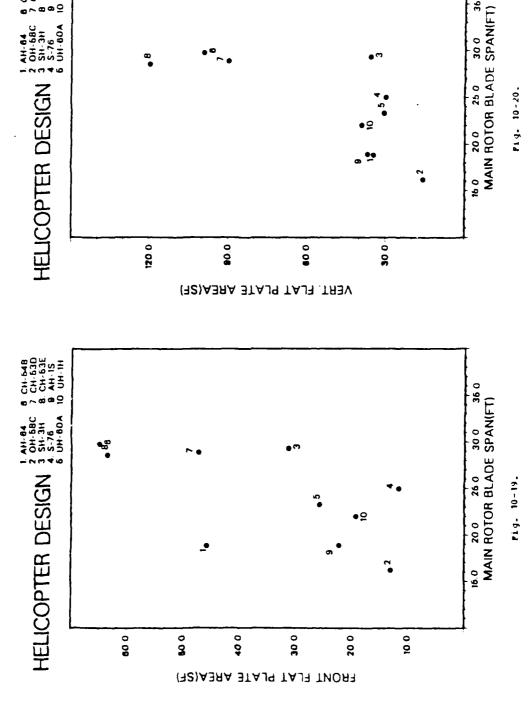


Fig. 10-18a and 10-18b.

Fig. 10-19 and 10-20.



6 CH-648 7 CH-630 8 CH-63E 9 AH-1S 10 UH-1H

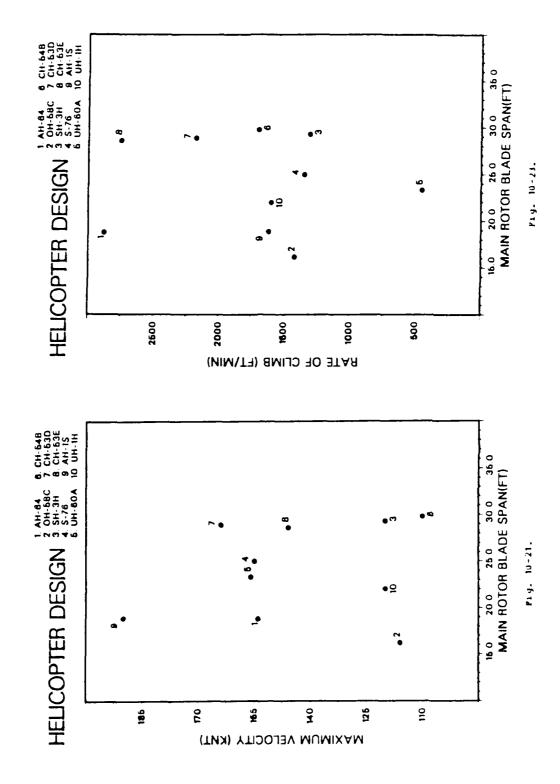


Fig. 10-21 and 10-23.

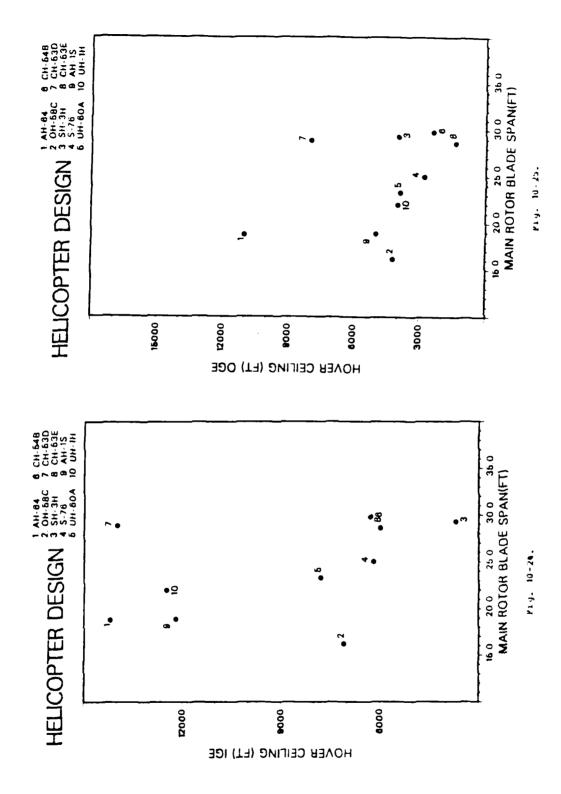
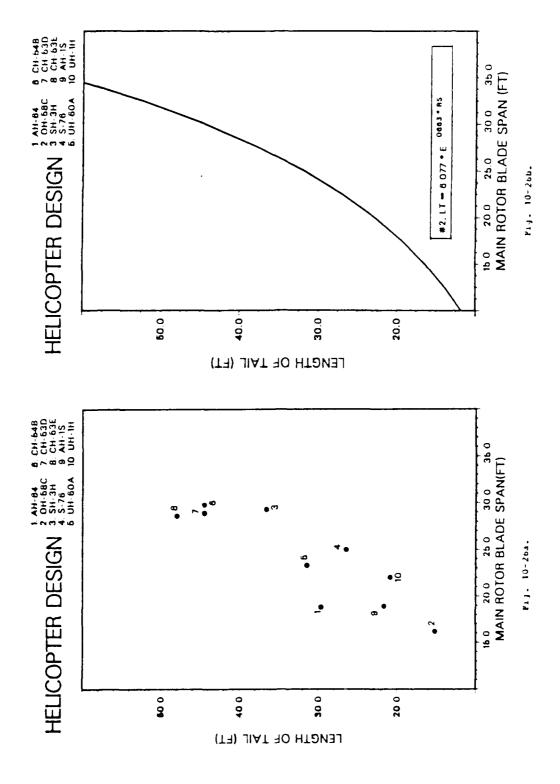
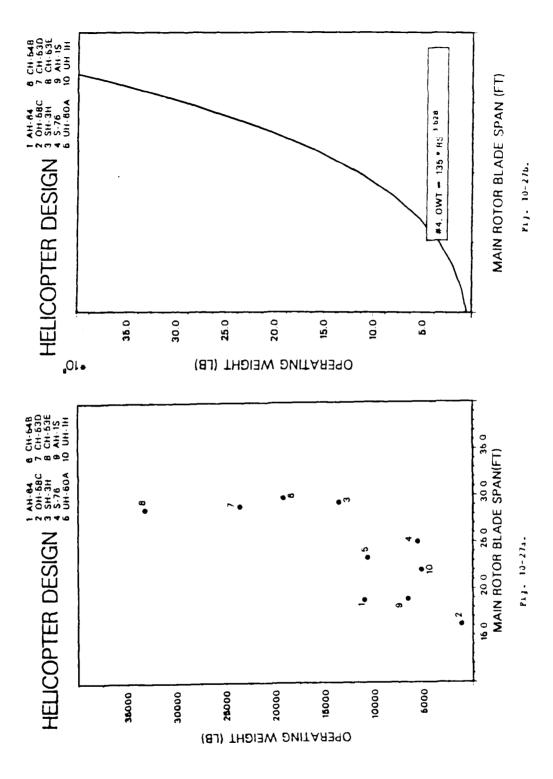


Fig. 10-24 and 10-25.



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Fig. 10-26a and 10-26b.



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Fig. 10-27a and 10-27b.

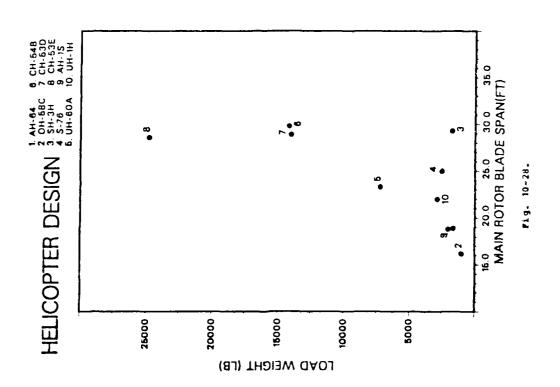
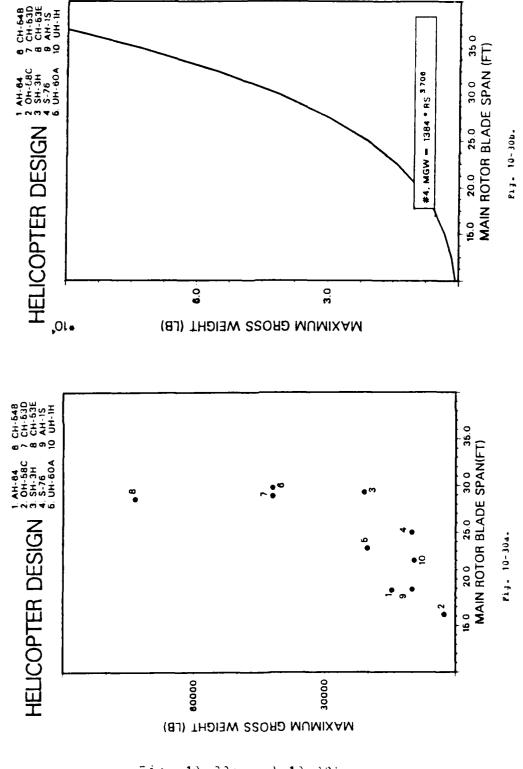
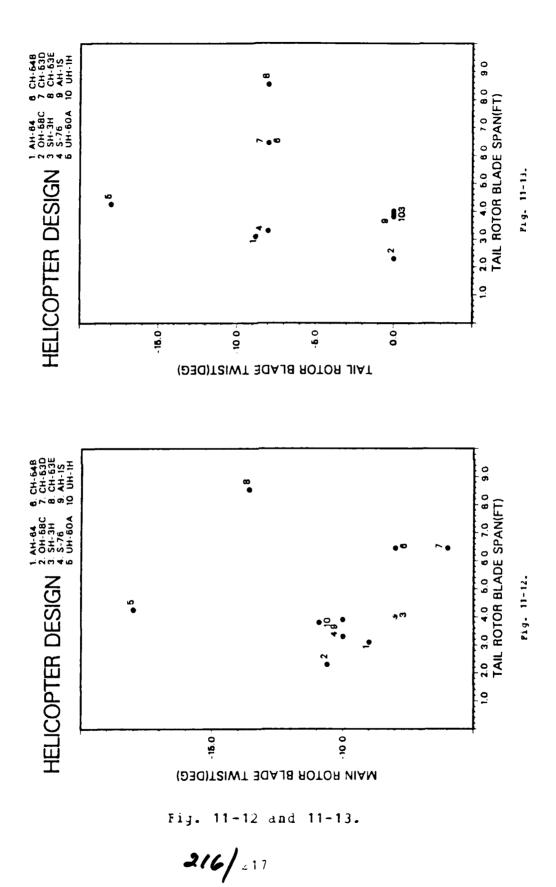


Fig. 10-28.

Fig. 10-30a and 10-30b.



Span of Tail Rotor Pairings.



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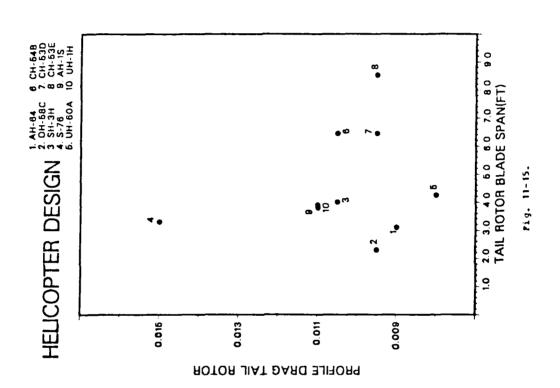
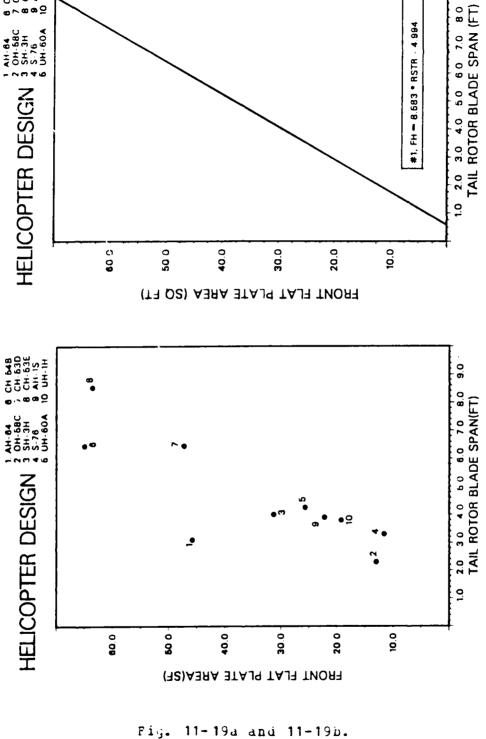


Fig. 11-15.



8 CH-548 7 CH-53D 8 CH-53E 9 AH-1S 10 UH-1H

1 AH-84 2 OH-68C 3 SH-3H 4 S-76 6 UH-60A

P14. 11-194.

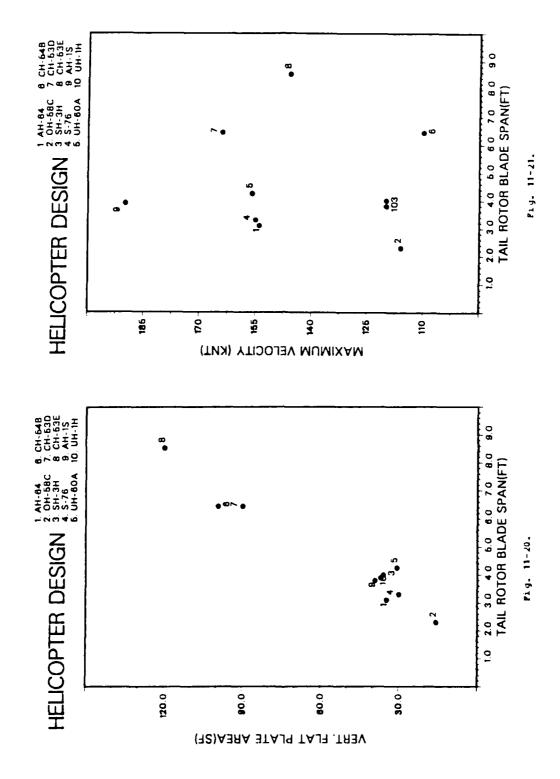


Fig. 11-20 and 11-21.

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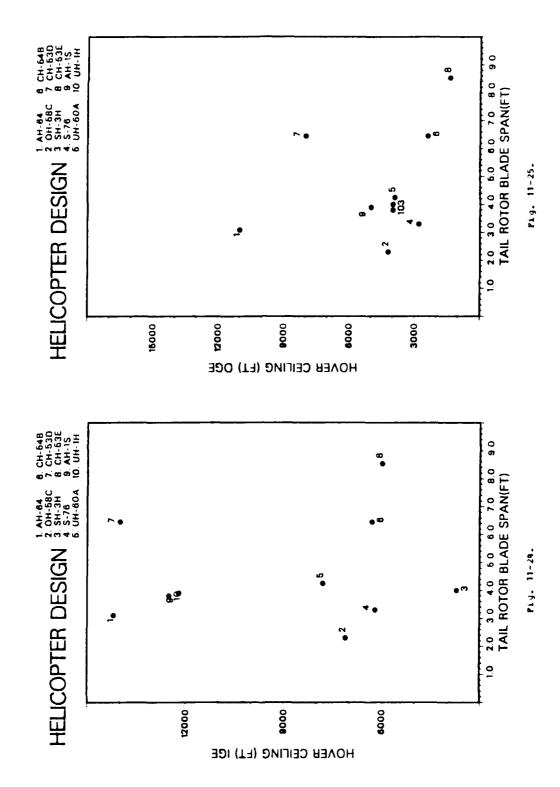


Fig. 11-24 and 11-25.

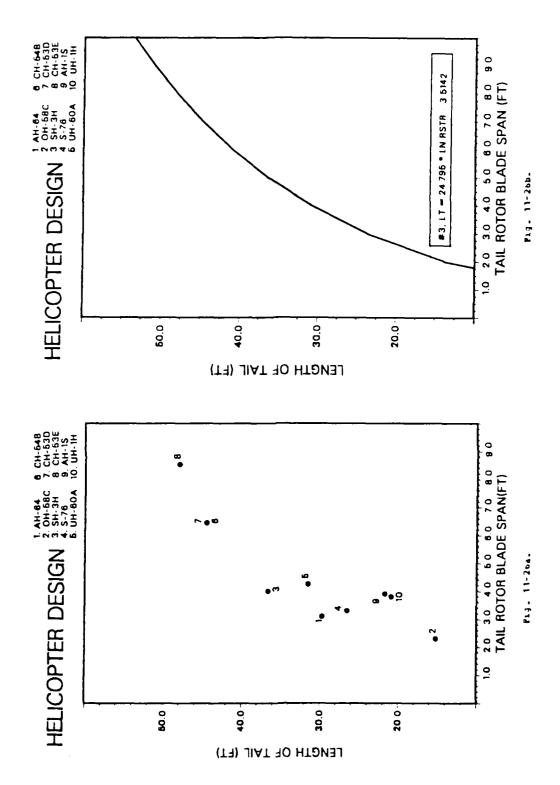


Fig. 11-2ea and 11-2eb.

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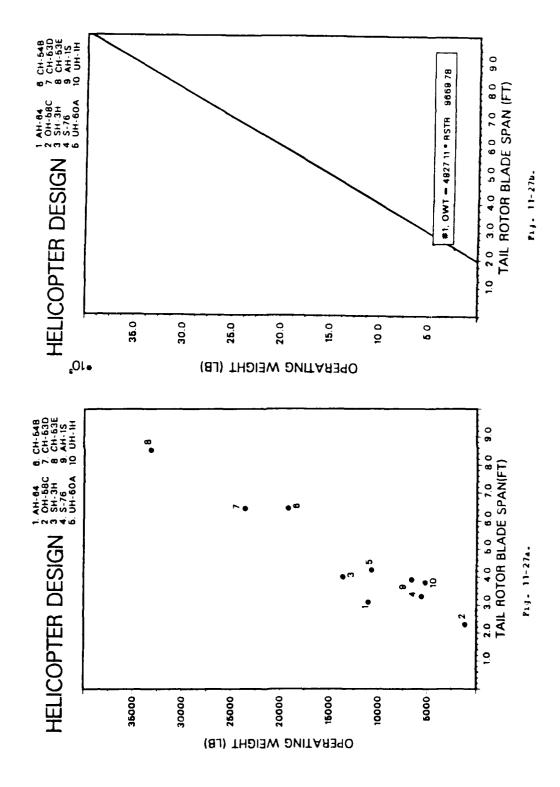


Fig. 11-27a and 11-27b.

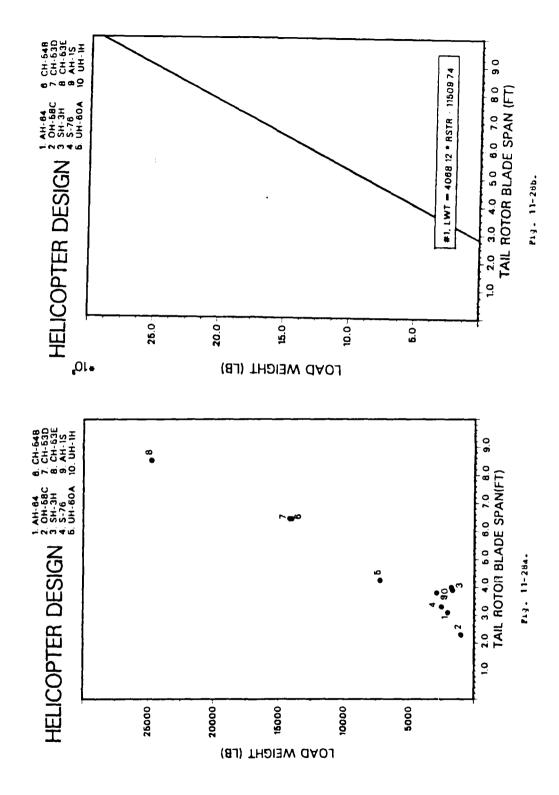
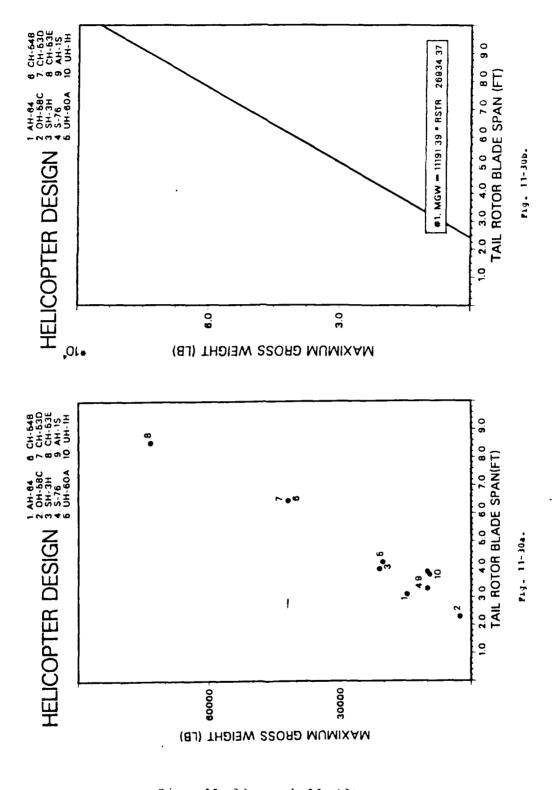
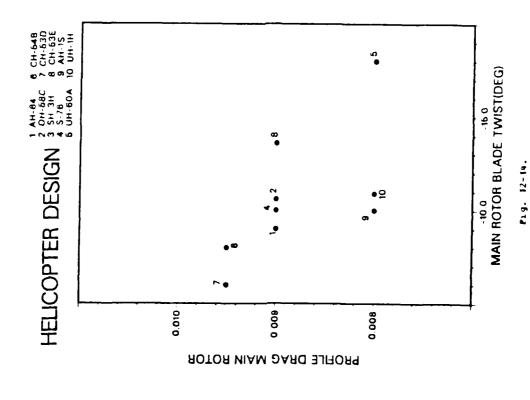


Fig. 11-28a and 11-28b.

Fig. 11-30a and 11-30b.



Twist of Main Rotor Blade Pairings.



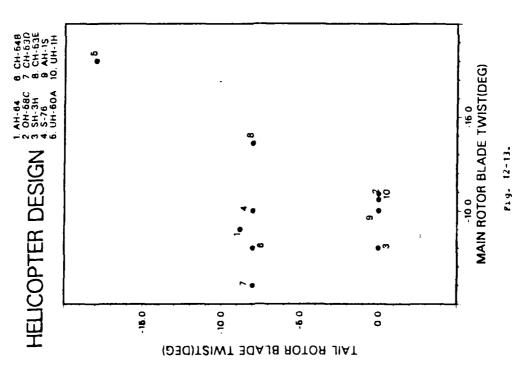
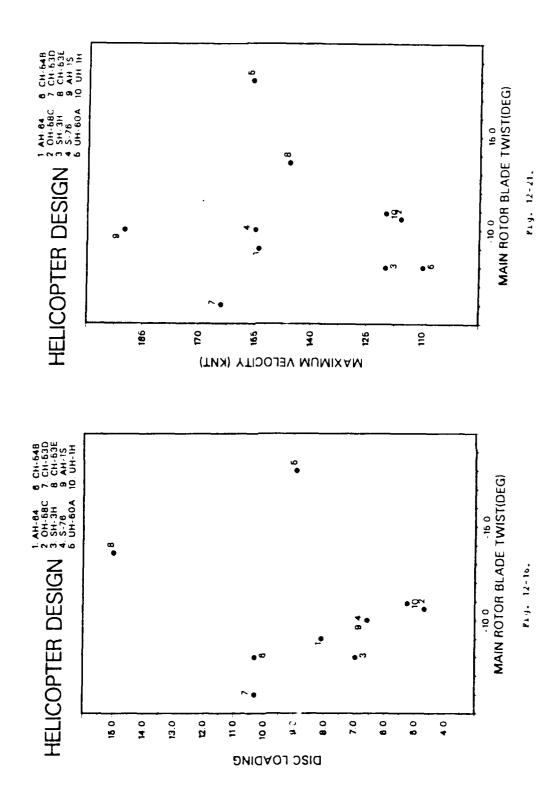


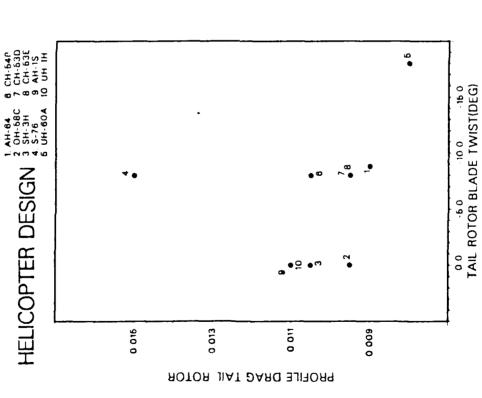
Fig. 12-13 and 12-14.

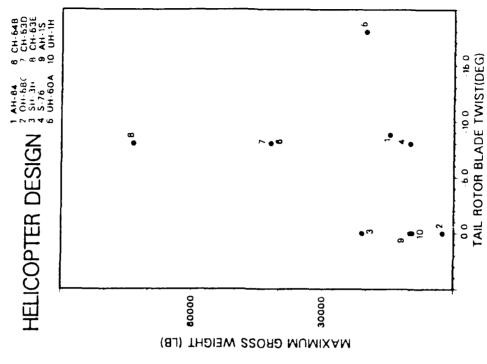


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Fig. 12-16 and 12-21.

Twist of Tail Rotor Blade Pairings.





P1 9. 13- 30.

P19. 13-15.

Profile Drag of Main Rotor Blade Pairings.

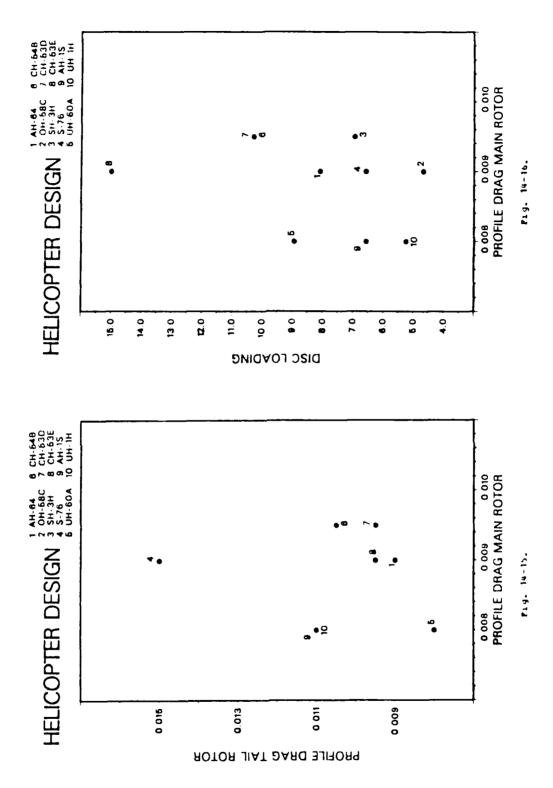


Fig. 14-15 and 14-16.

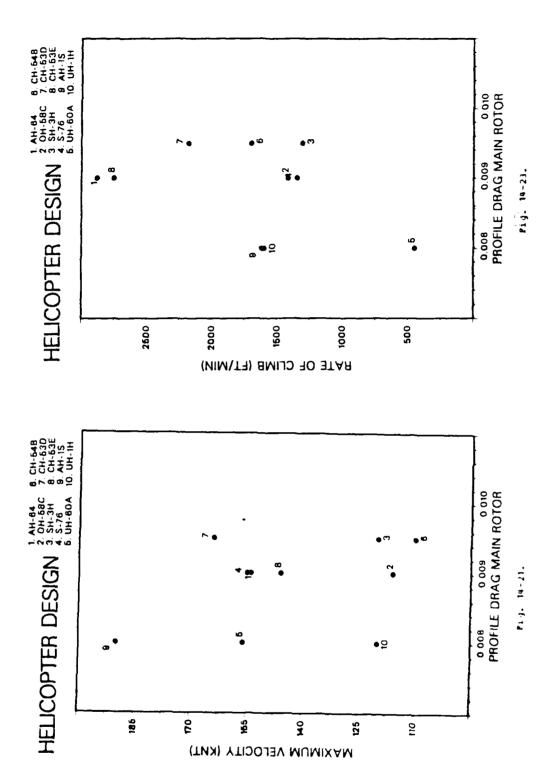


Fig. 14-21 and 14-23.

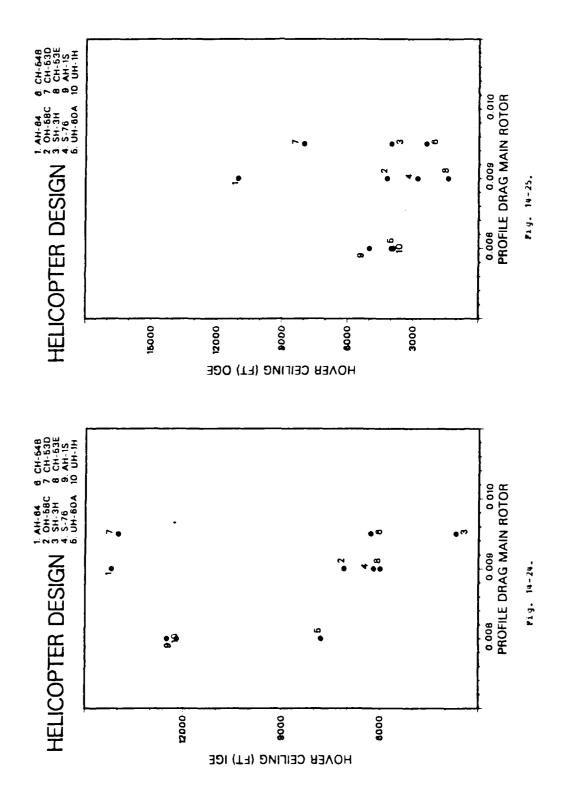
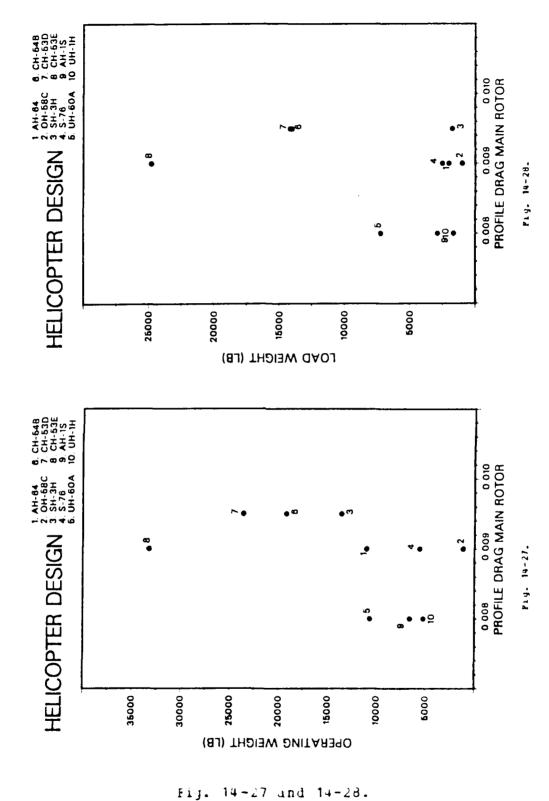
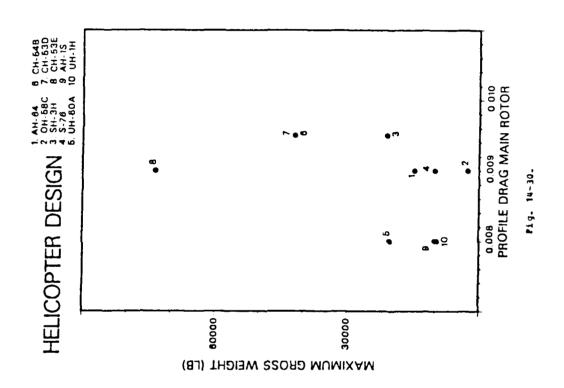


Fig. 14-24 and 14-25.





Pig. 14-30.

Profile Drag of Tail Rotor Blade Pairings.

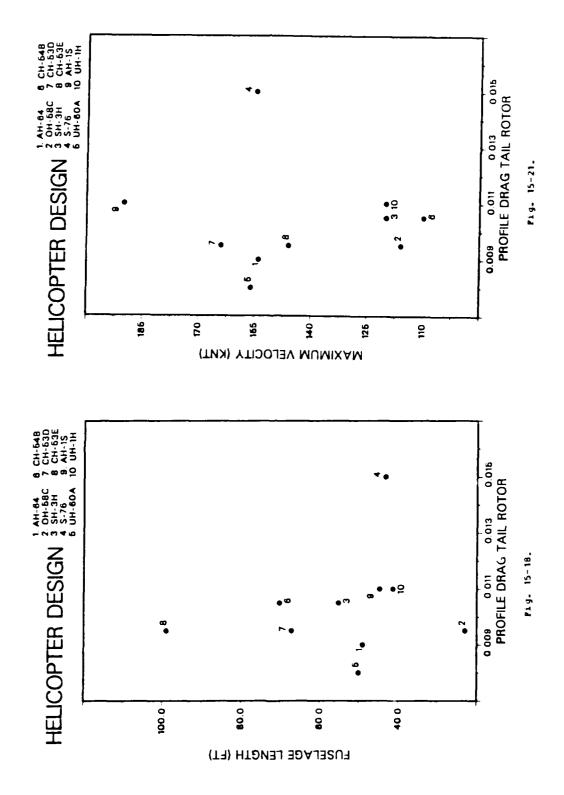


Fig. 15-1d and 15-21.

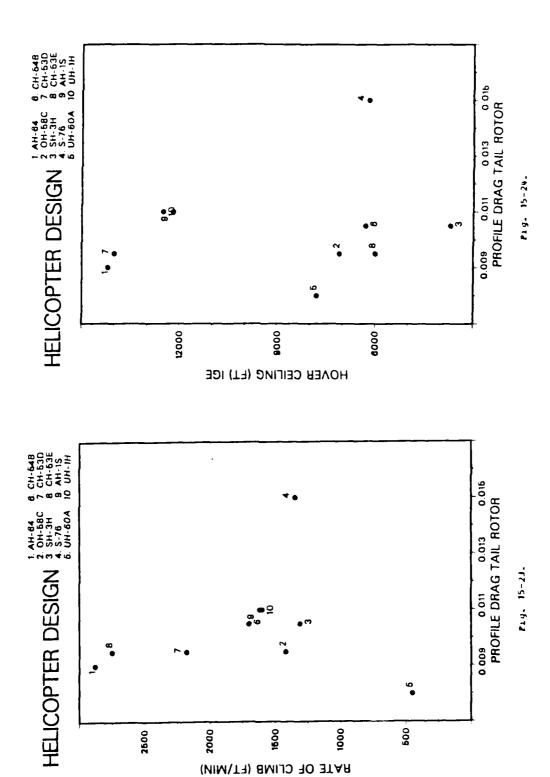
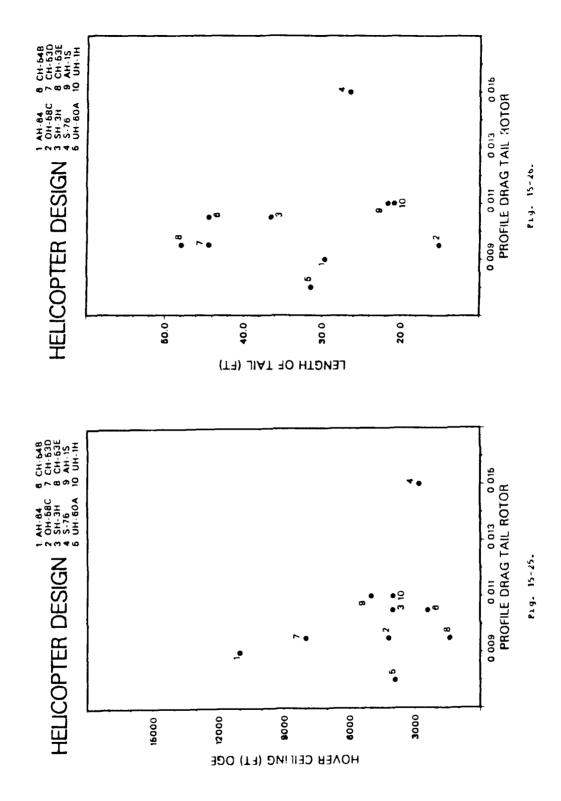


Fig. 15-23 and 15-24.



£19. 15-25 ind 15-26.

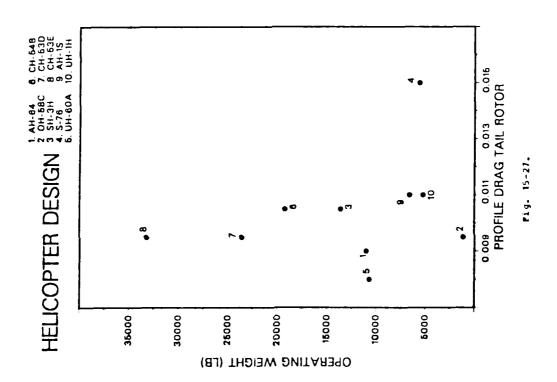
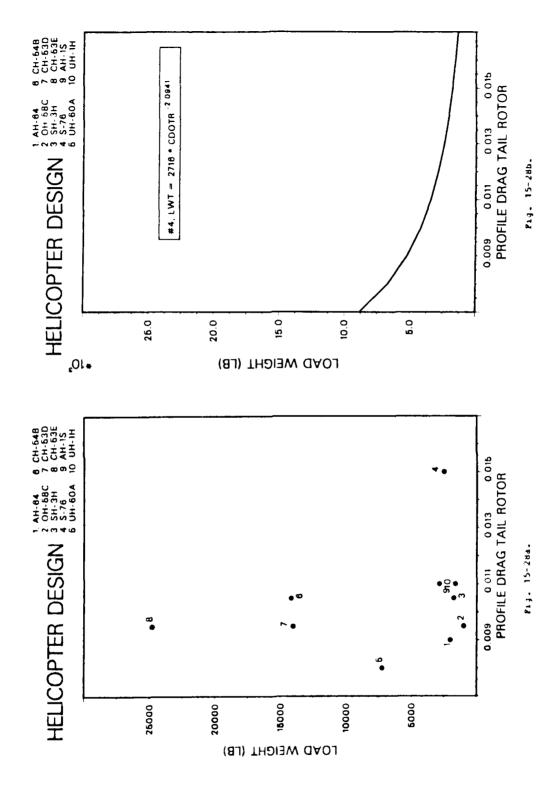


Fig. 15-27.



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Fig. 15-2sa and 15-28p.

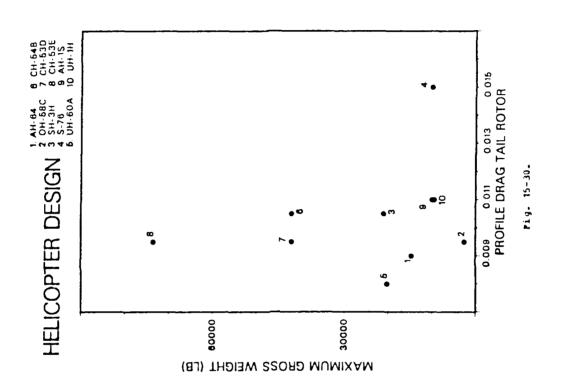


Fig. 15-30.

Disc Loading of the Main Rotor System Pairings.

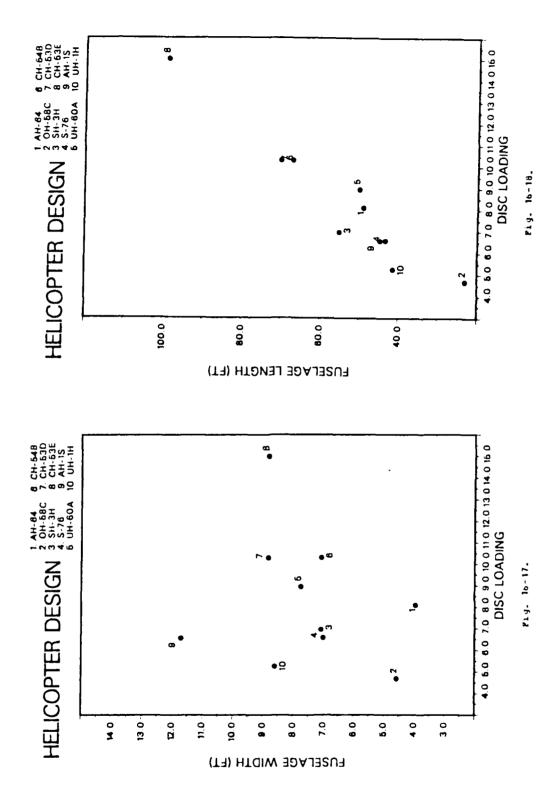
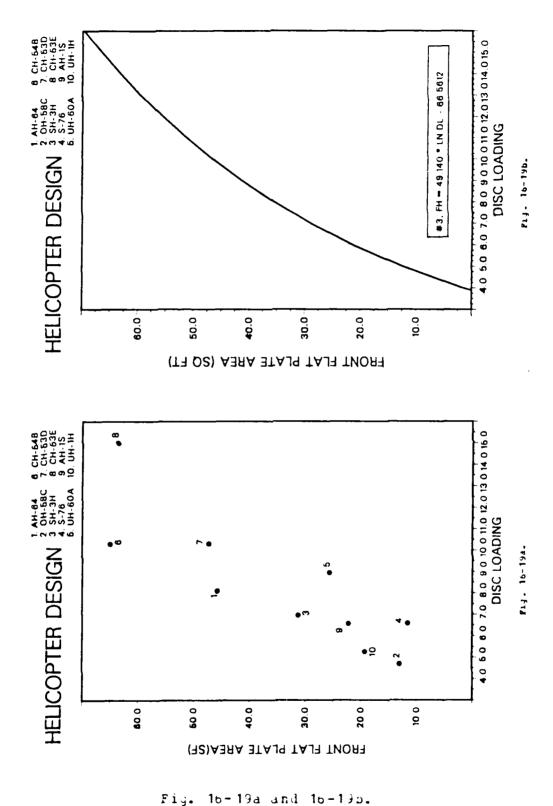


Fig. 16-17 and 10-18.



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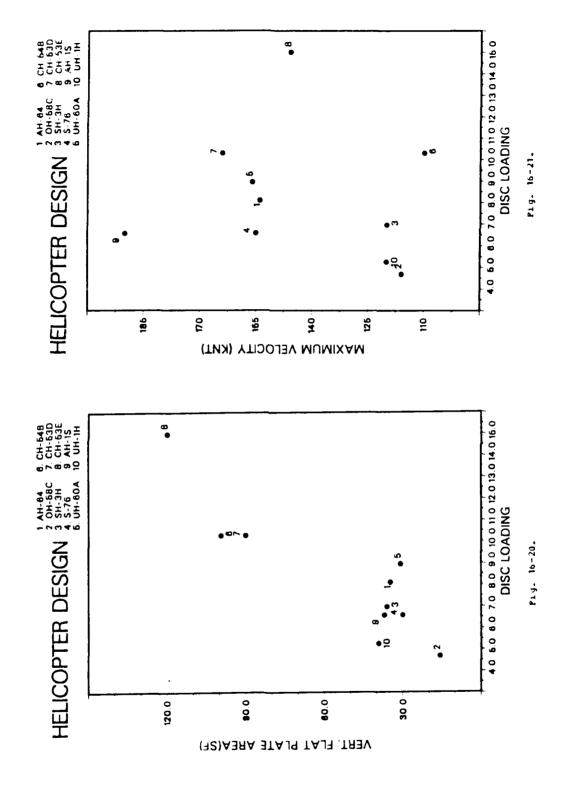


Fig. 16-23 and 16-21.

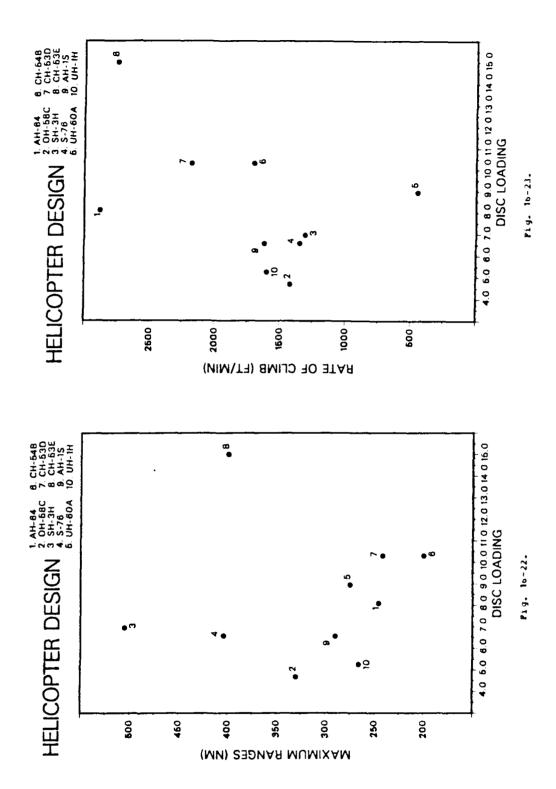


Fig. 16-22 and 10-23.

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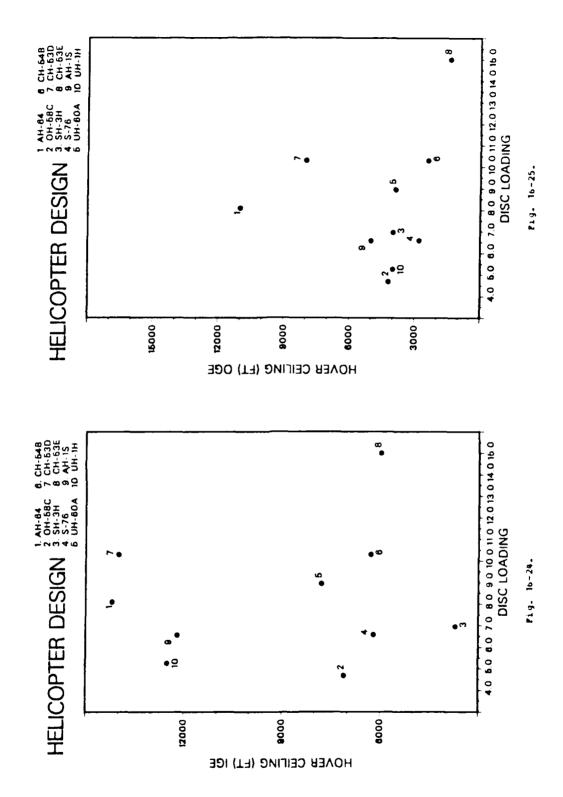
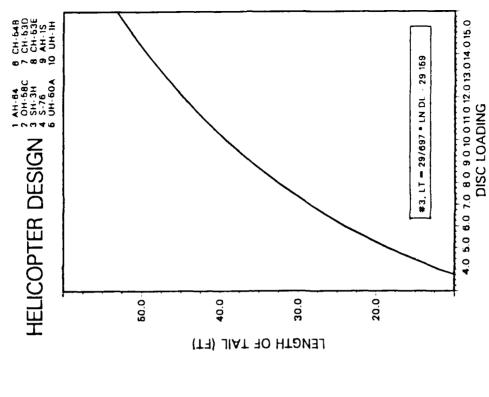


Fig. 16-24 and 10-25.



Piy. 16-26b.

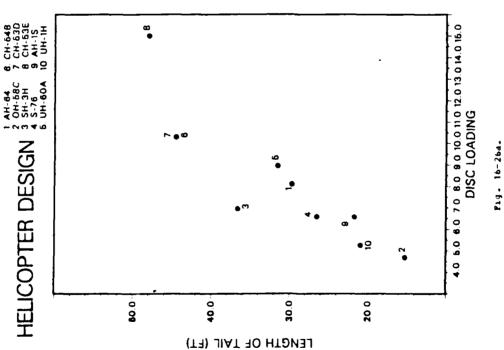


Fig. 16-20a and 16-20b.

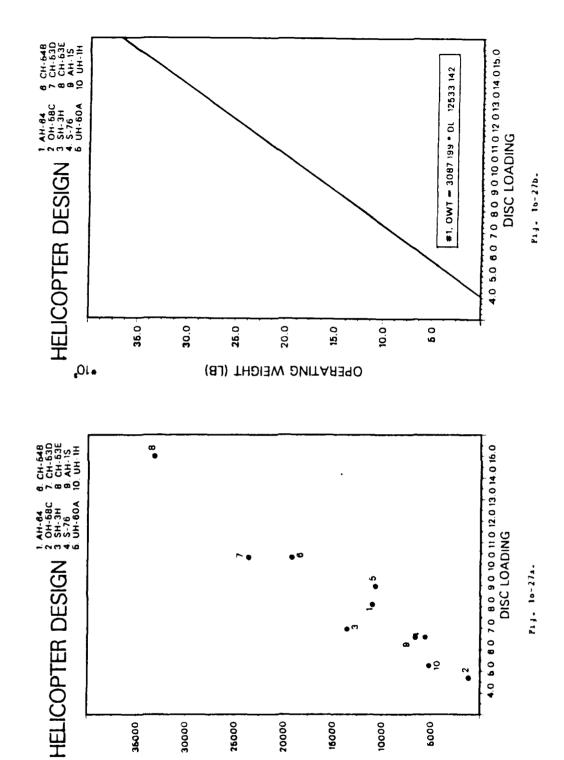


Fig. 10-27a and 10-27p.

OPERATING WEIGHT (LB)

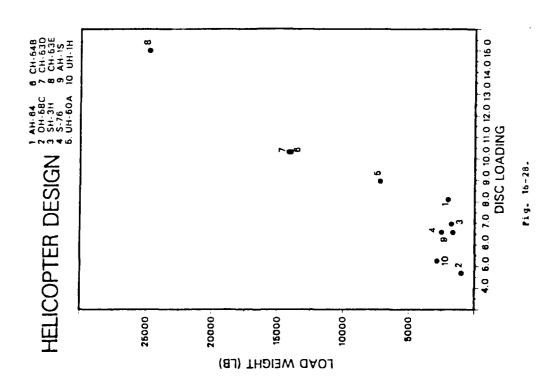
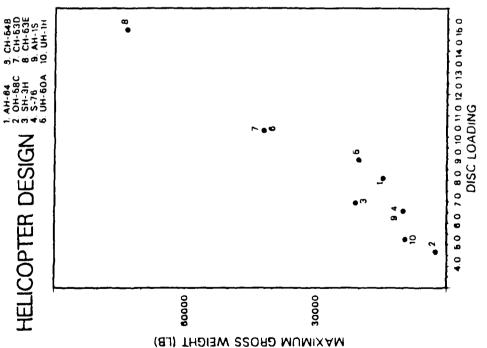
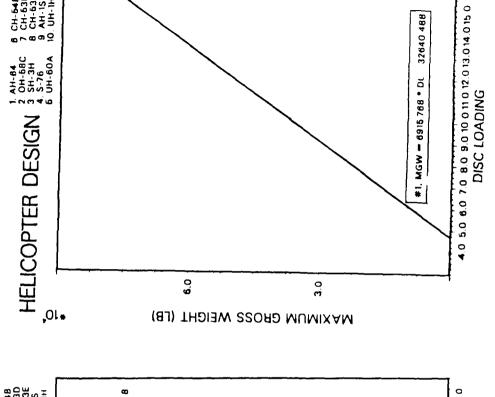


Fig. 16-28.

Fig. 16-30a and 16-30b.

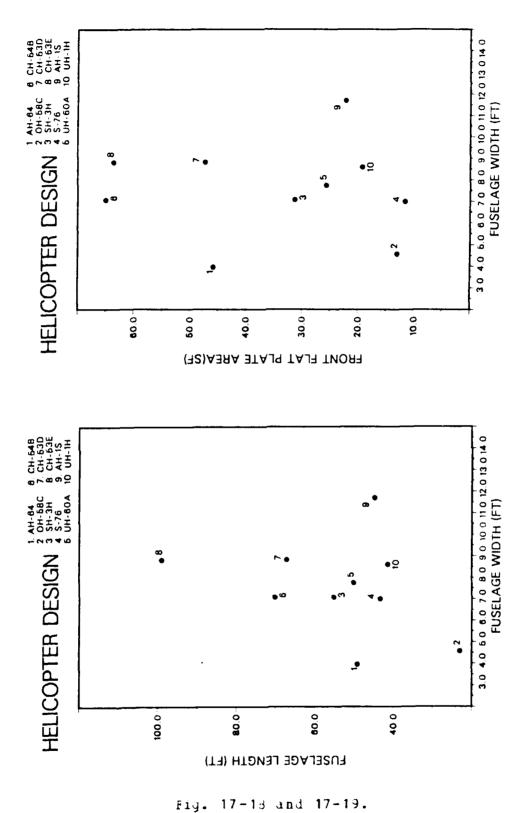




F14. 16-30b.

CH-548 CH-53D CH-53E AH-1S

Width of the Fuselage Pairings.



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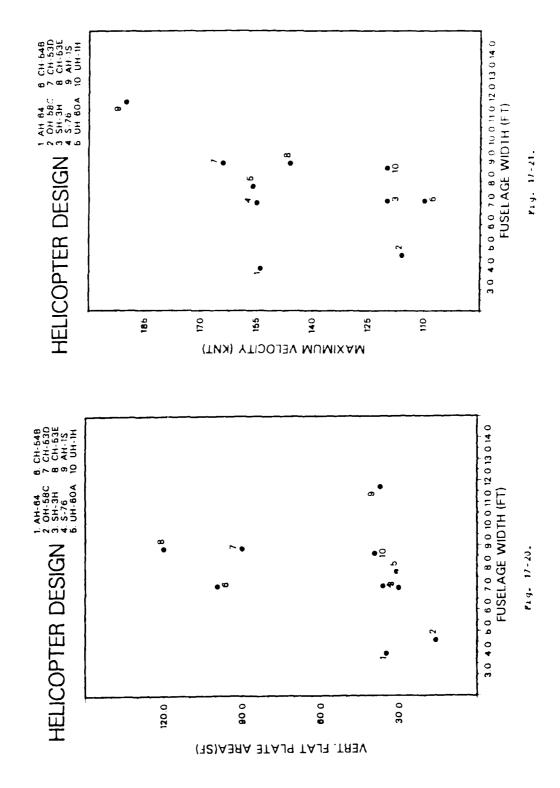


Fig. 17-20 and 17-21.

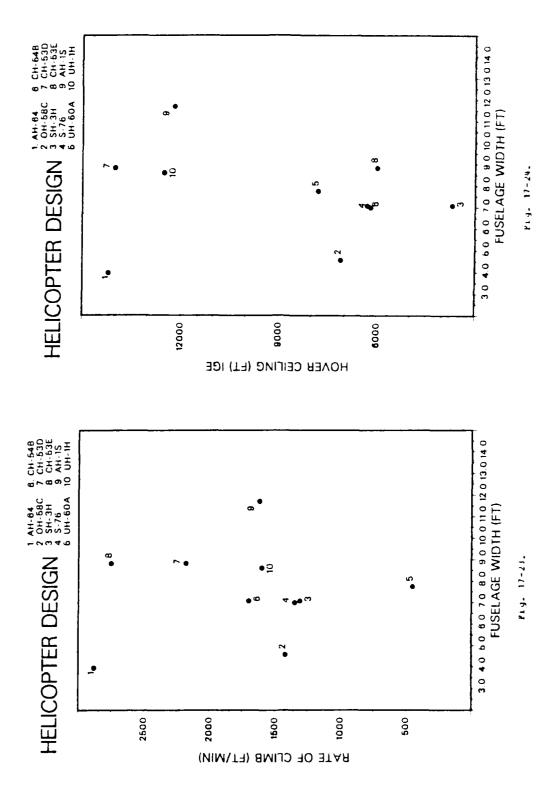


Fig. 17-23 and 17-24.

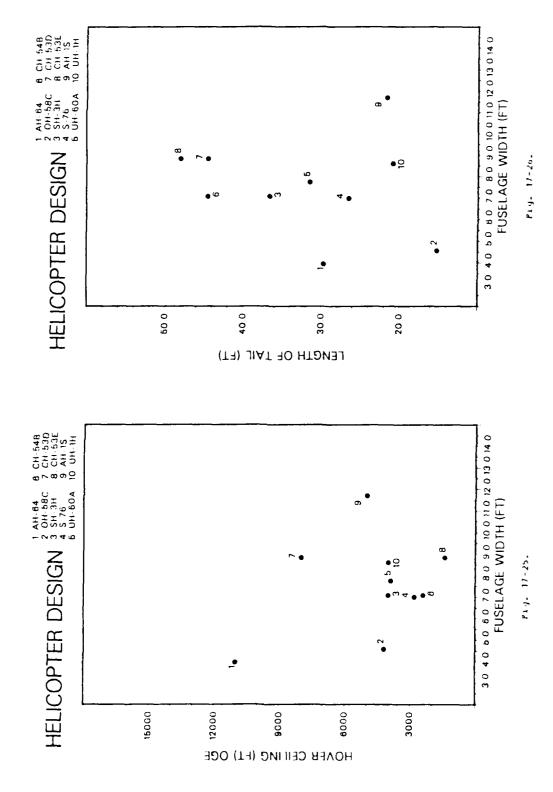


Fig. 17-25 and 17-26.

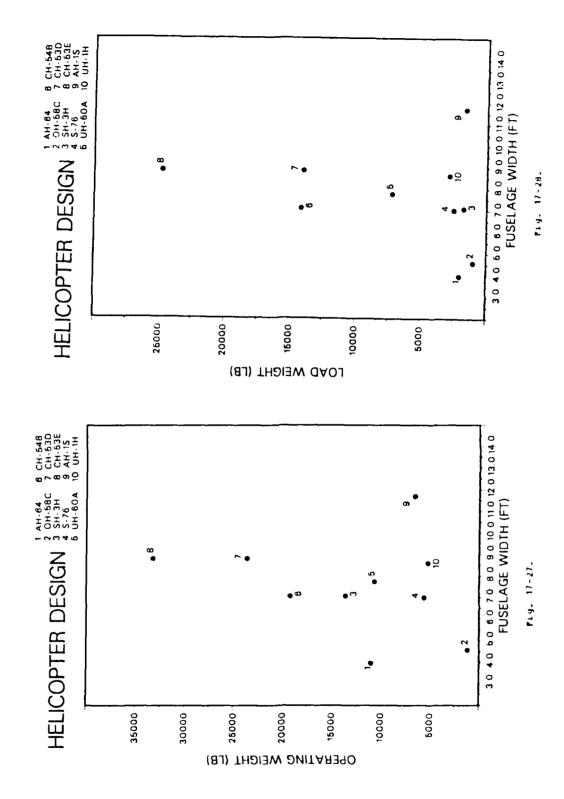


Fig. 17-27 and 17-28.

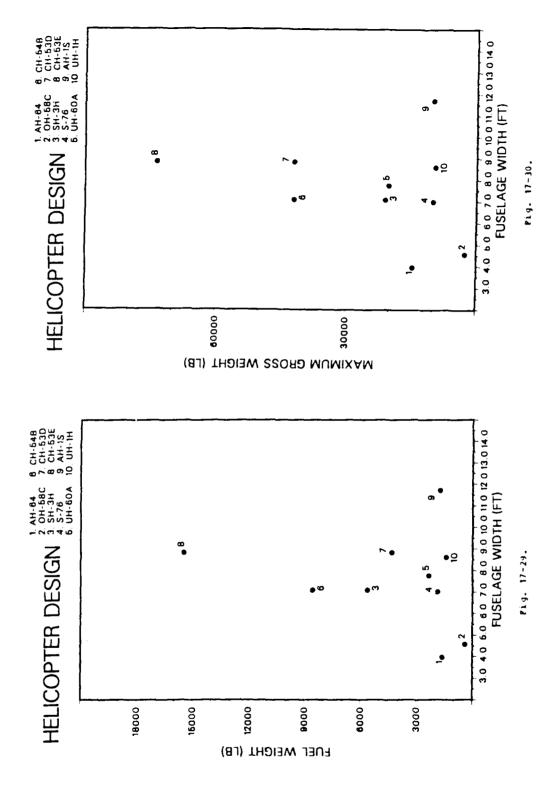
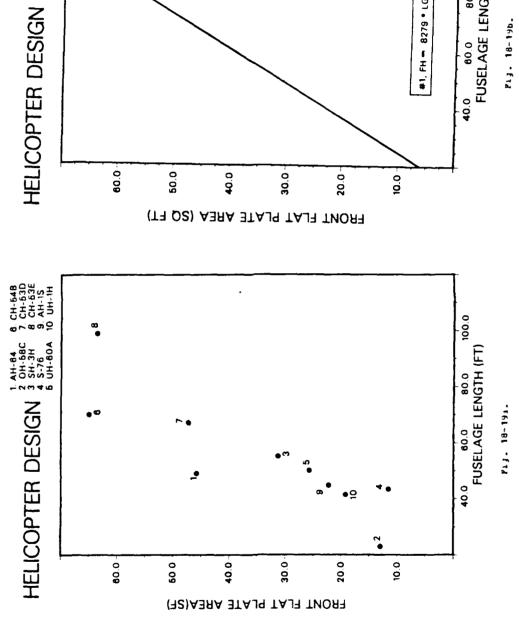


Fig. 17-29 and 17-30.

Length of Fuselage Pairings.

Pig. 18-19a and 18-19b.



100.0

40.0 80.0 π FUSELAGE LENGTH (FT)

10 4968

#1, FH = 8279 • LGH

8 CH-548 7 CH-53D 8 CH-63E 9 AH-1S 10 UH-1H

1. AH-84 2. OH-58C 3. SH-3H 4. S-76 6. UH-60A



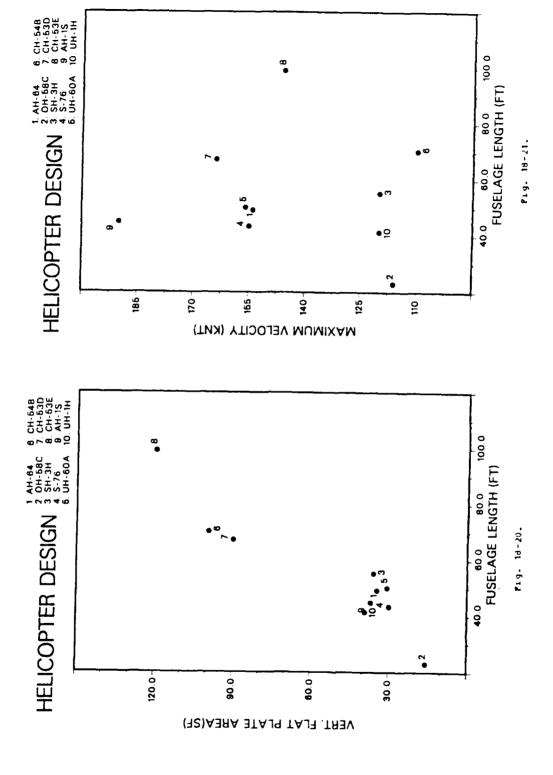


Fig. 18-20 and 18-21.

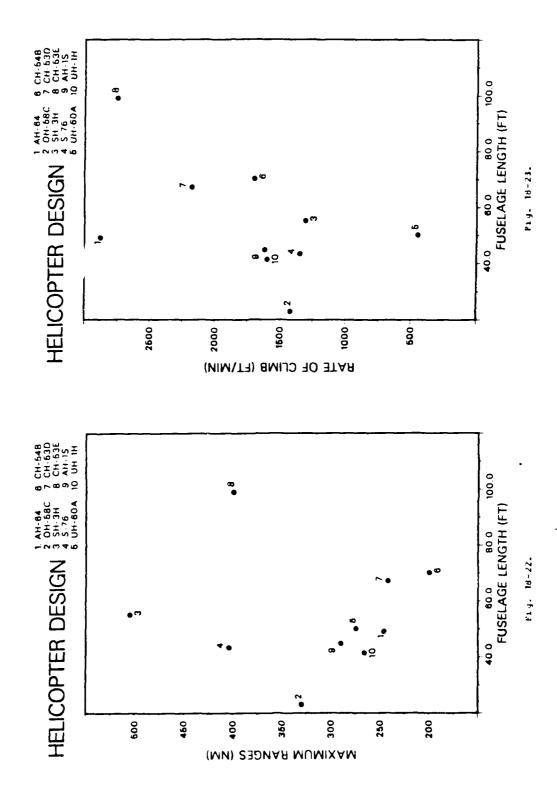


Fig. 18-22 and 18-23.

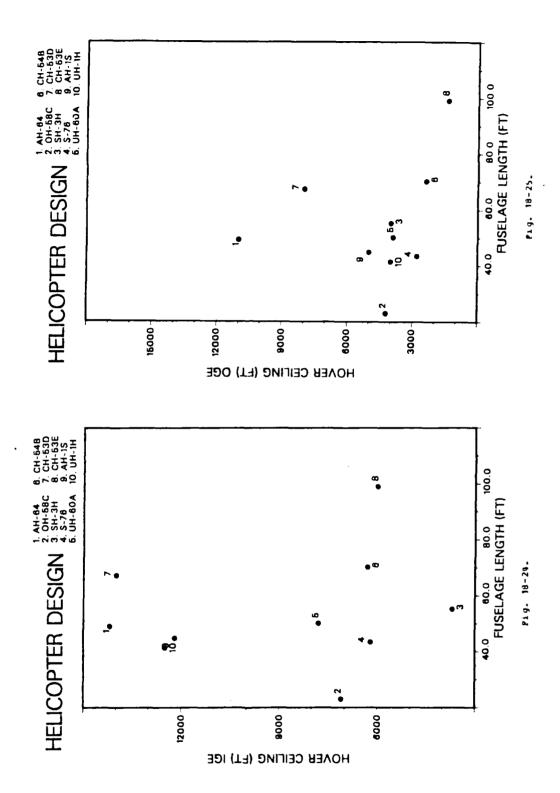


Fig. 18-24 and 18-25.

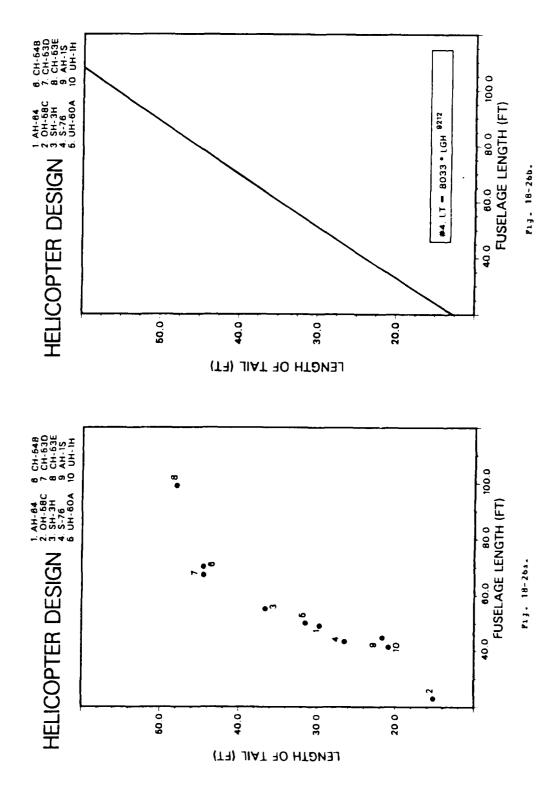
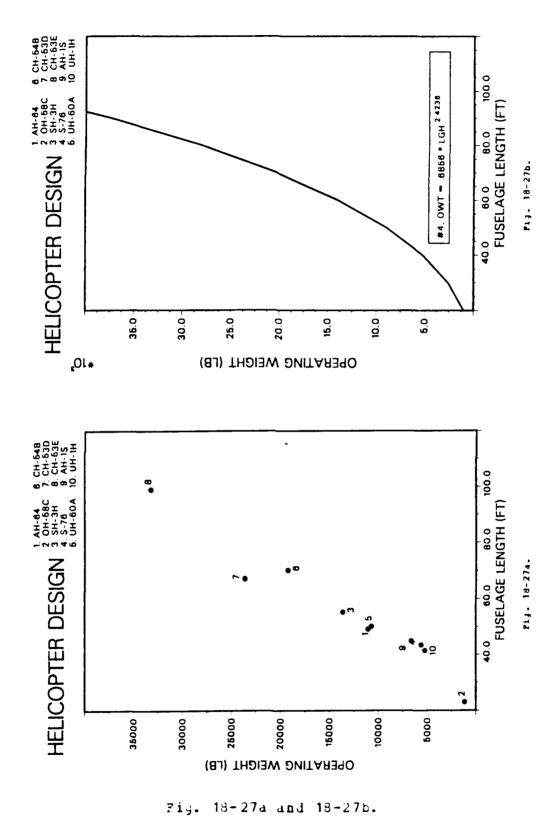


Fig. 18-26a and 18-26b.



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Manager and the same

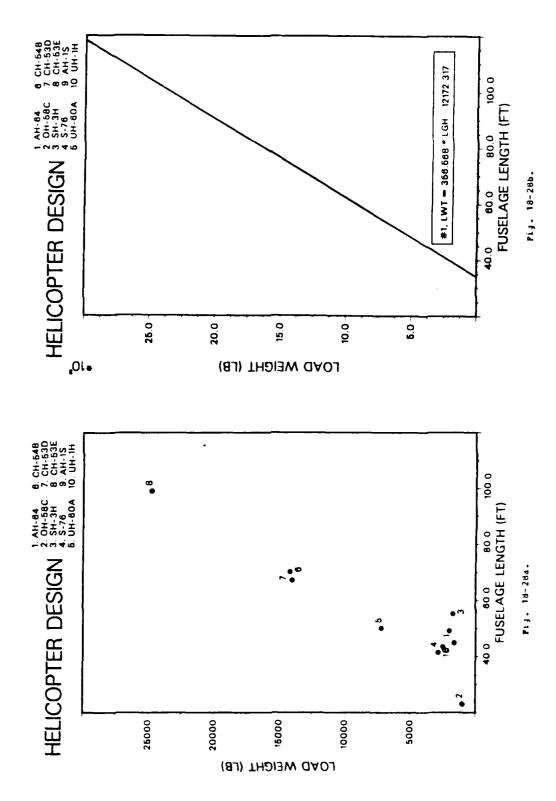
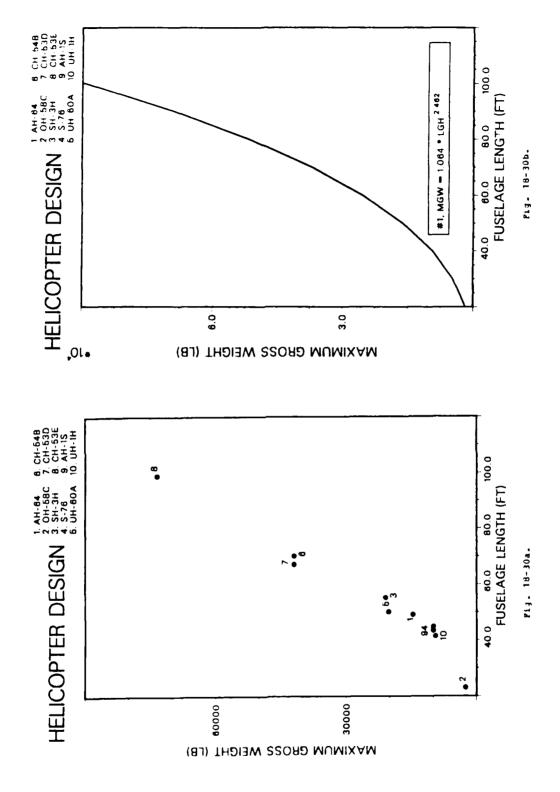


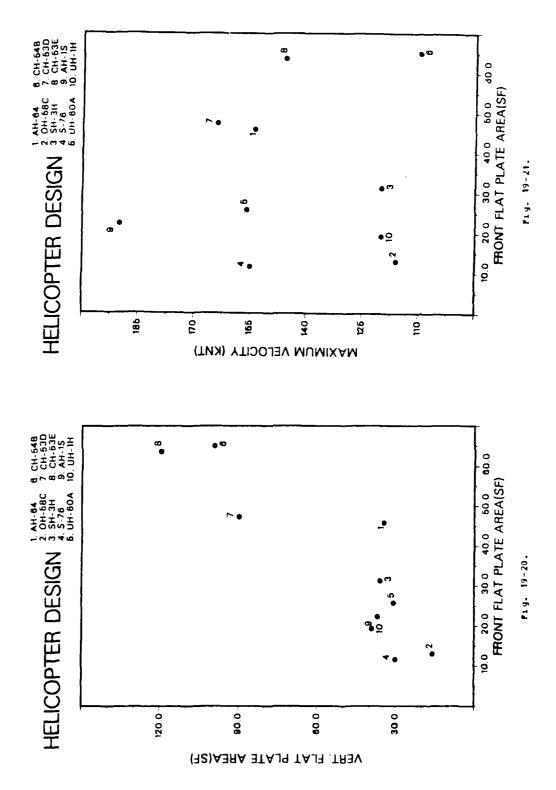
Fig. 16-23a and 18-23b.



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Fig. 13-30a and 18-30b.

Frontal Horizontal Flat Plate Area Pairings.



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Fig. 19-20 and 19-21.

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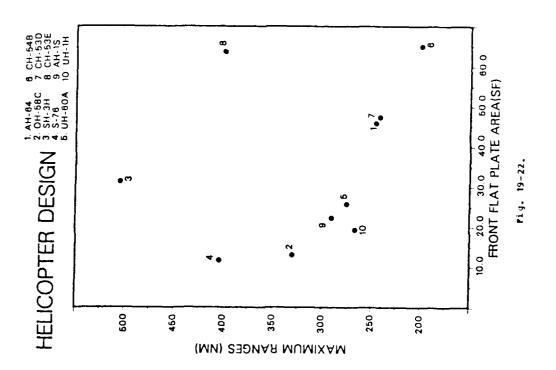
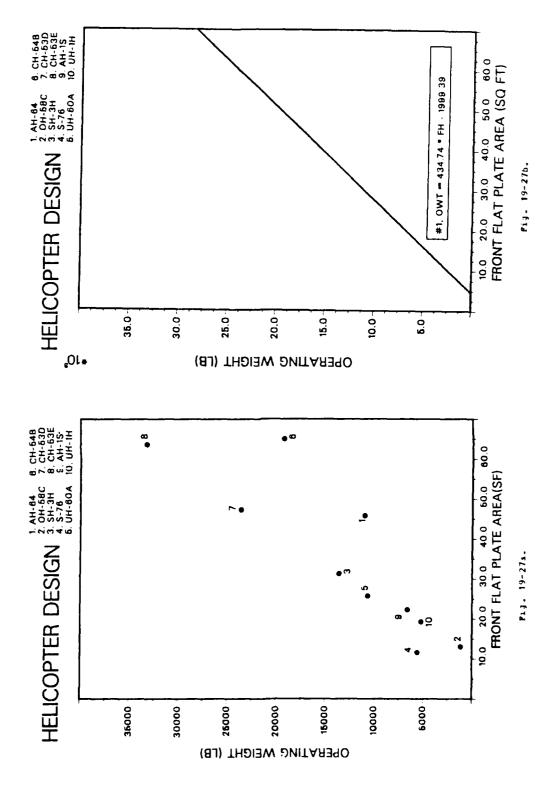
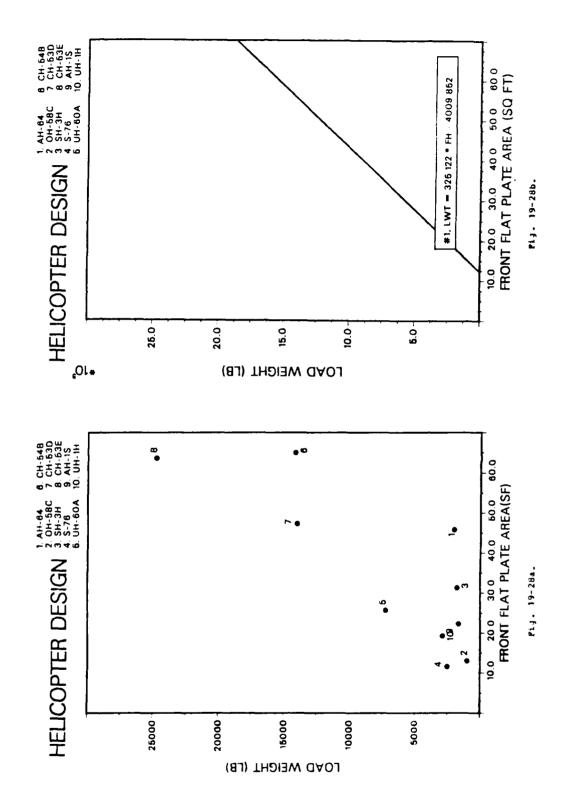


Fig. 19-22.



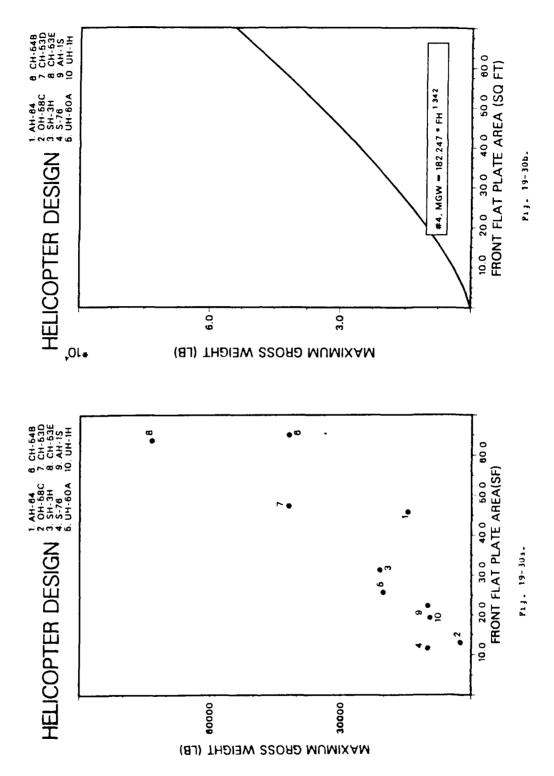
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Fig. 19-27a and 19-27b.



E

Fig. 19-28a and 19-28b.

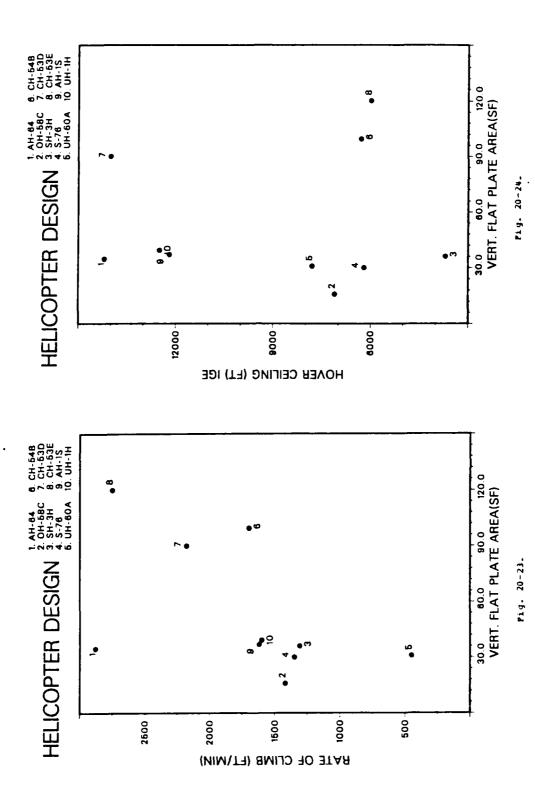


6

Fig. 13-30a and 19-30b.

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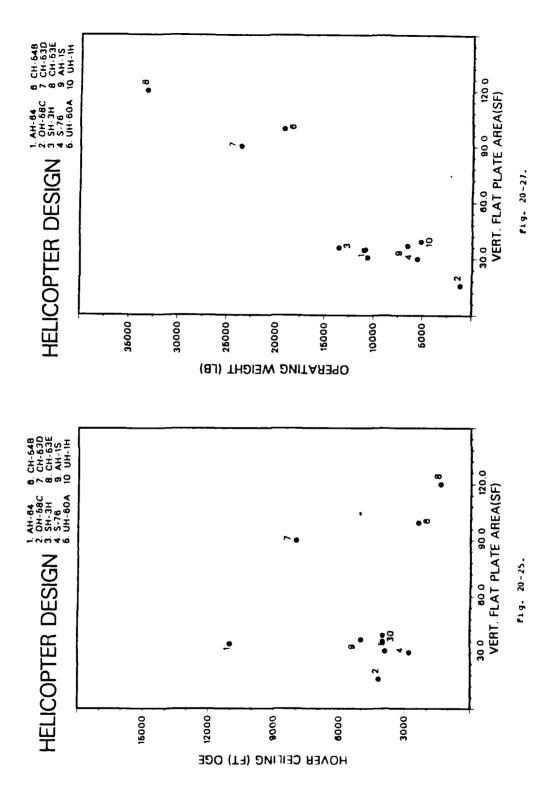
Frontal Vertical Flat Plate Area Pairings.



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Eig. 20-23 and 20-24.



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Fig. 20-25 and 20-27.

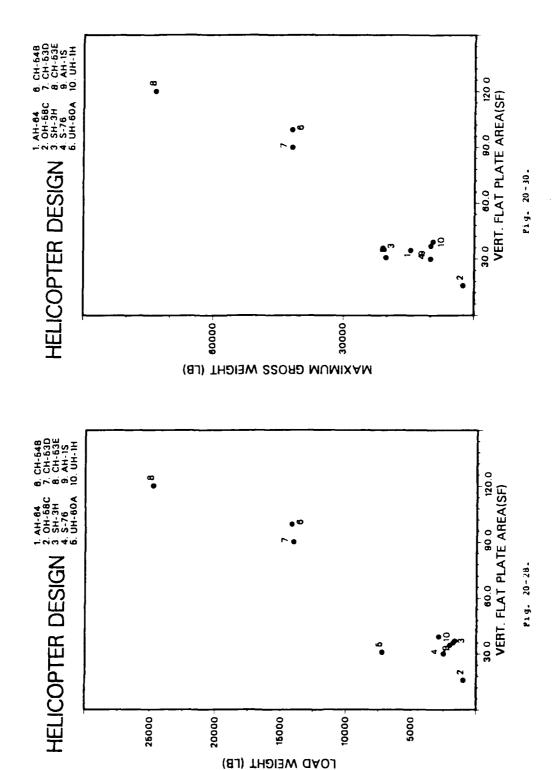
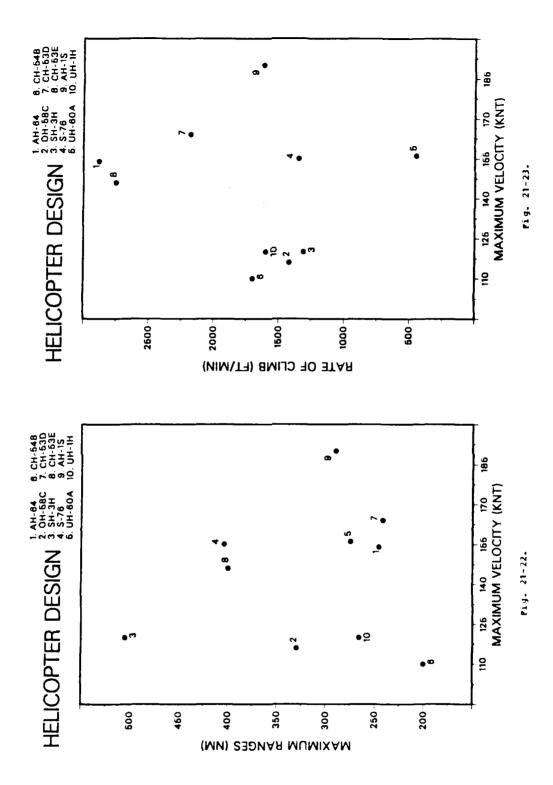


Fig. 20-28 and 20-30.

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Maximum Forward Velocity Pairings.



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Fig. 21-22 and 21-23.

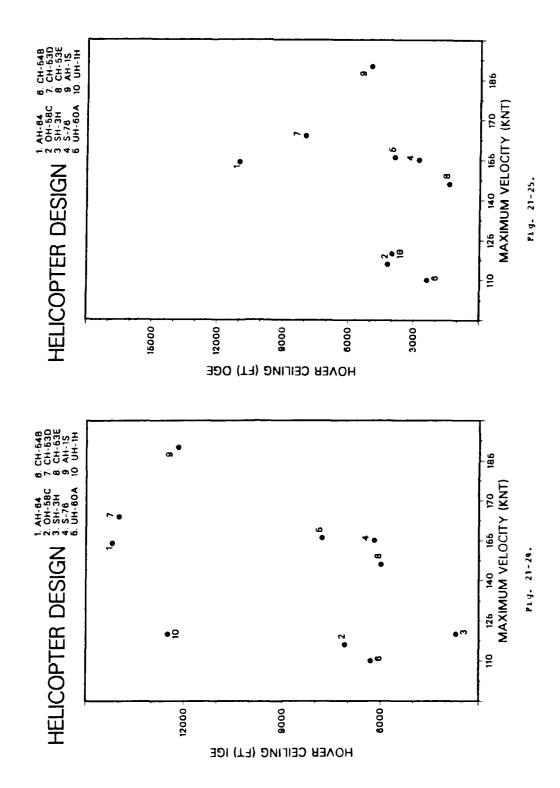


Fig. 21-24 and 21-25.

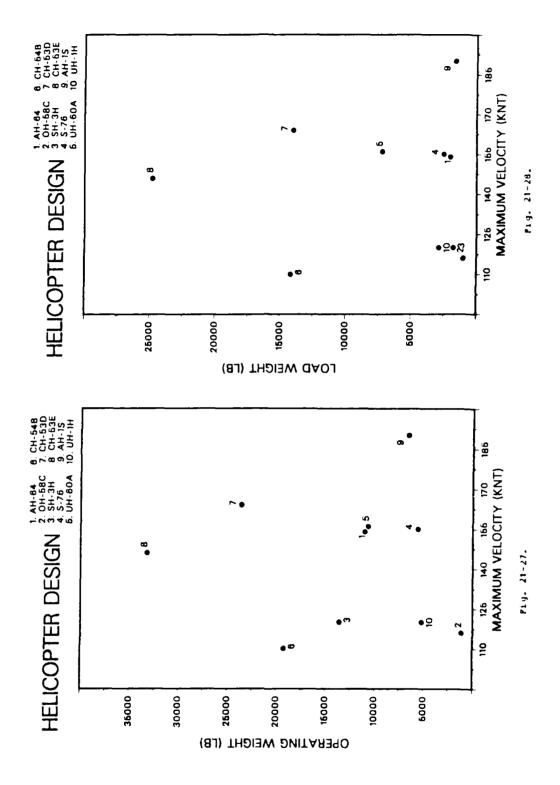
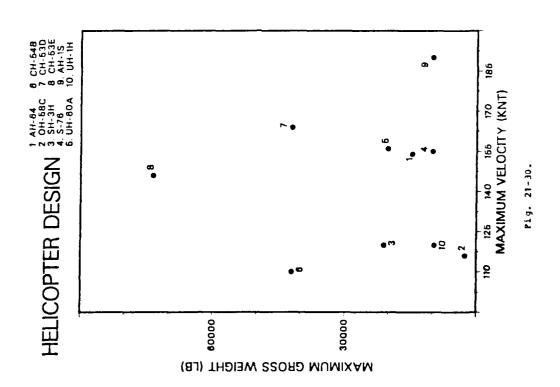


Fig. 21-27 and 21-28.



Pig. 21-30.

Maximum Range Pairings.

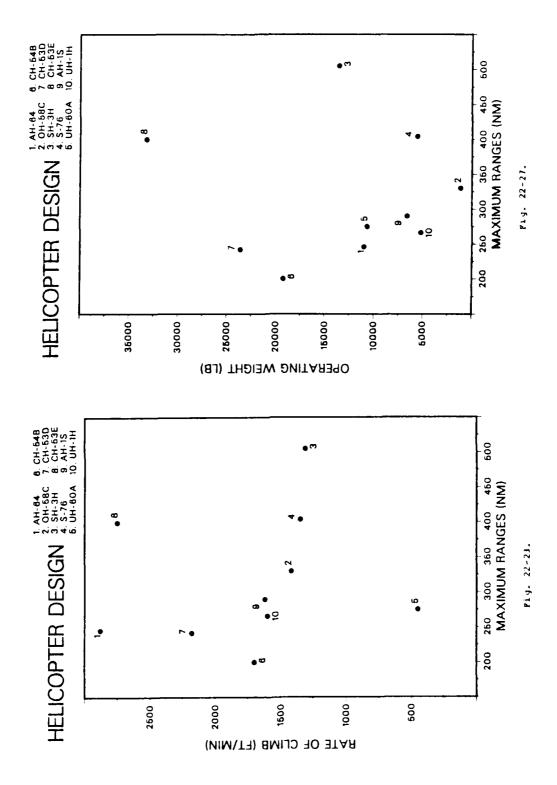


Fig. 22-23 and 22-27.

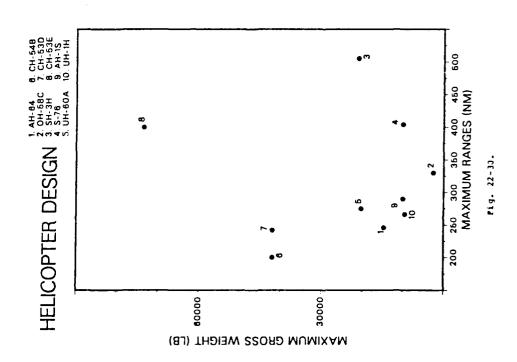


Fig. 22-30.

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Rate of Climb Pairings.

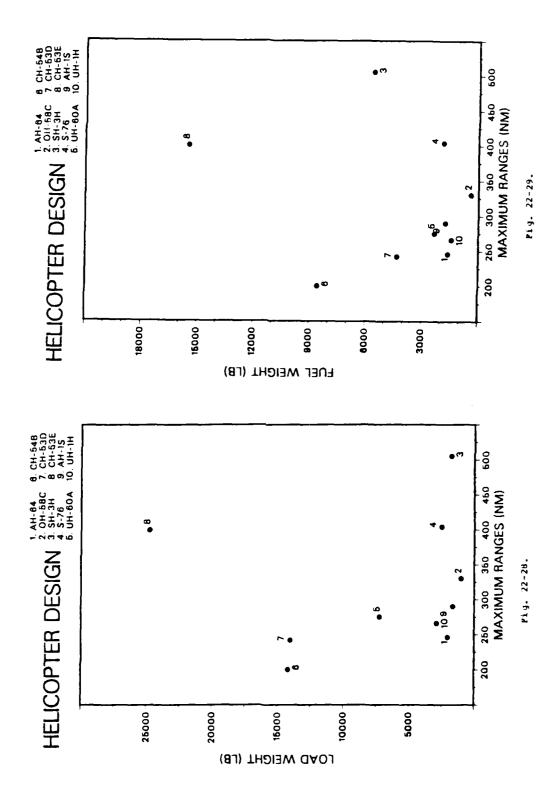


Fig. 22-28 and 22-29.

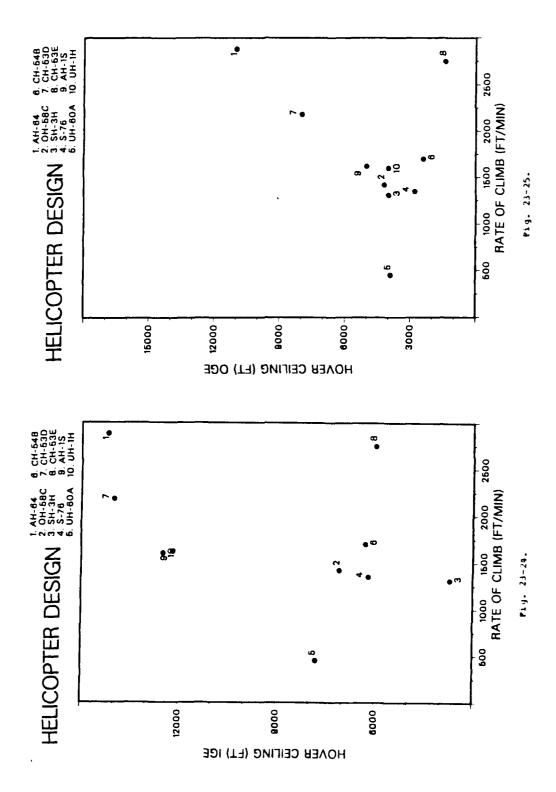
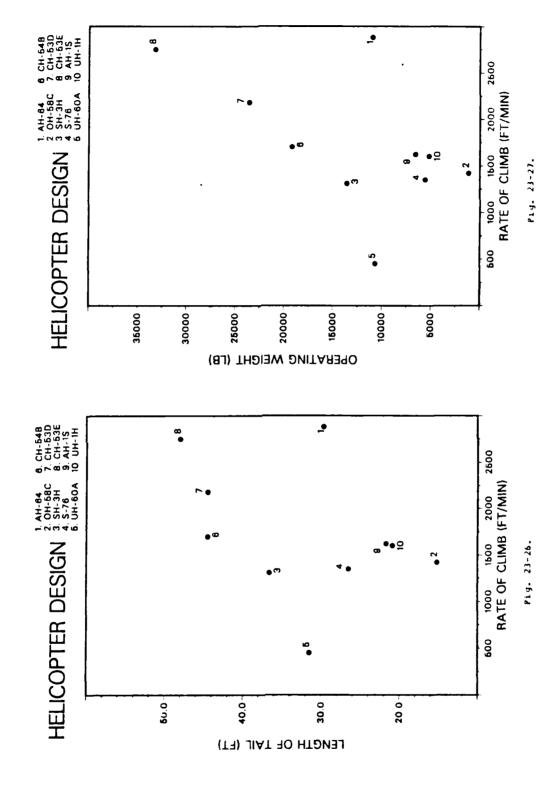


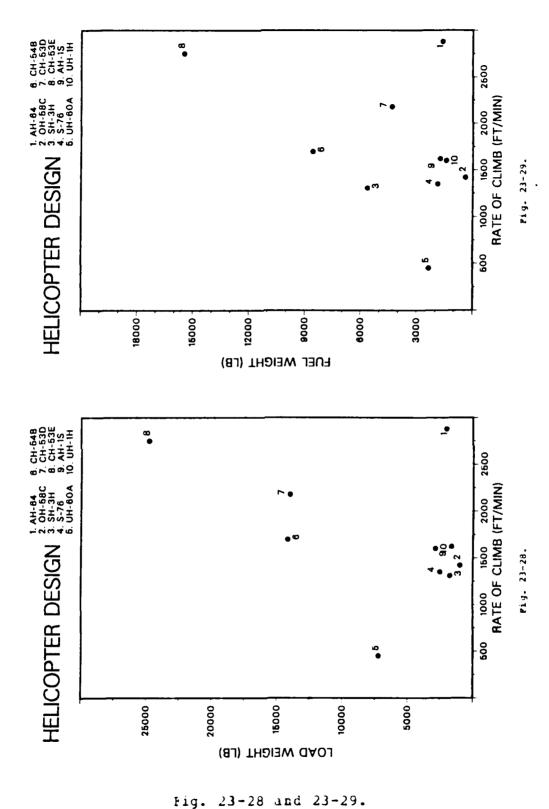
Fig. 23-24 and 23-25.



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E .

Fig. 23-20 and 23-27.



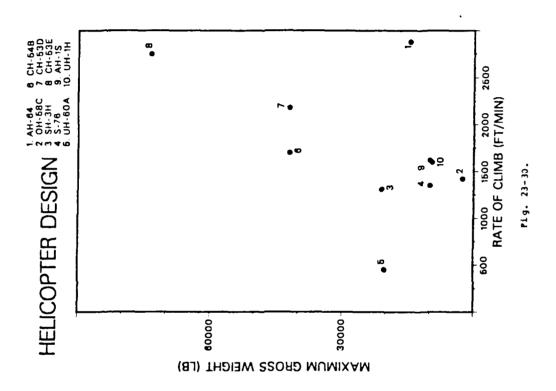


Fig. 23-30.

Hover Ceiling (IGE) Pairings.

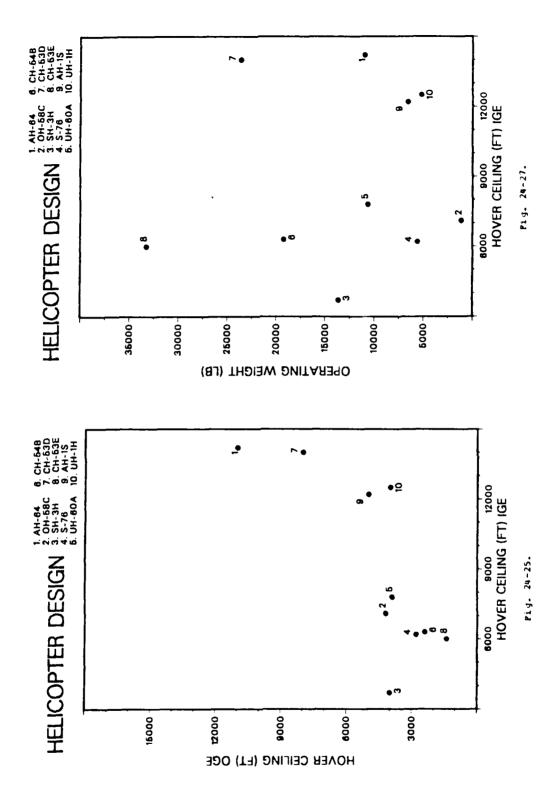
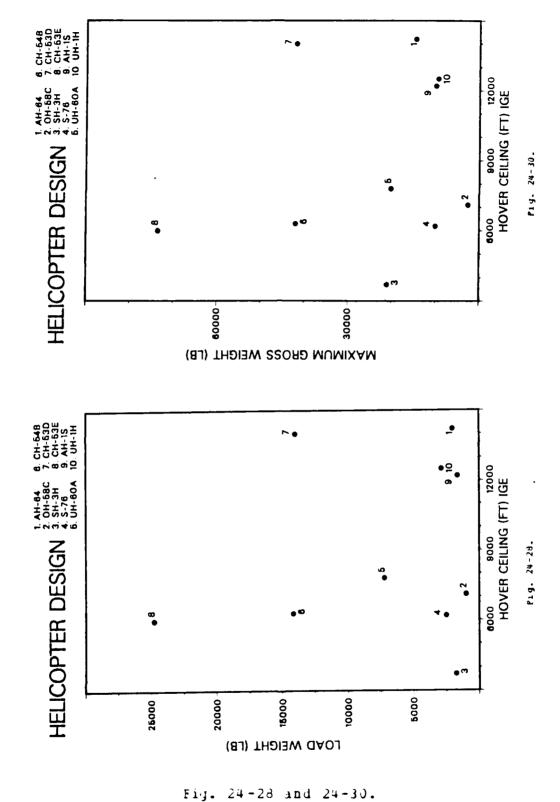


Fig. 24-25 and 24-27.



Hover Ceiling (OGE) Pairings.

a

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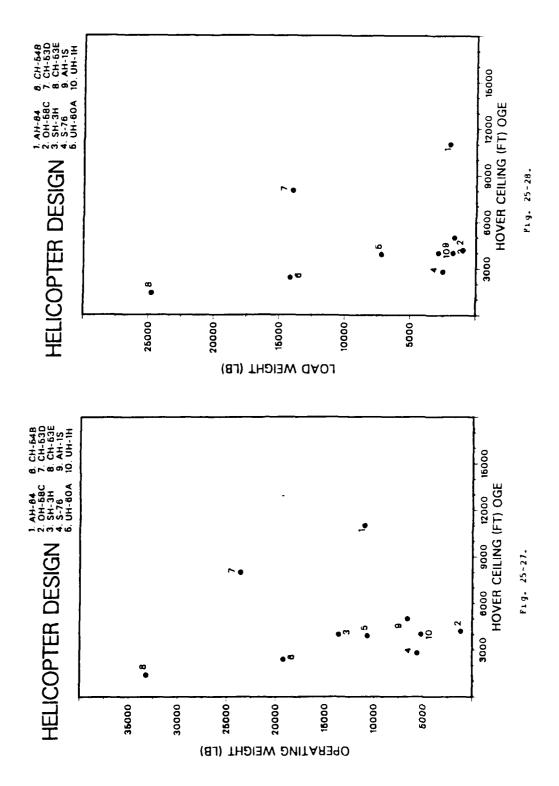
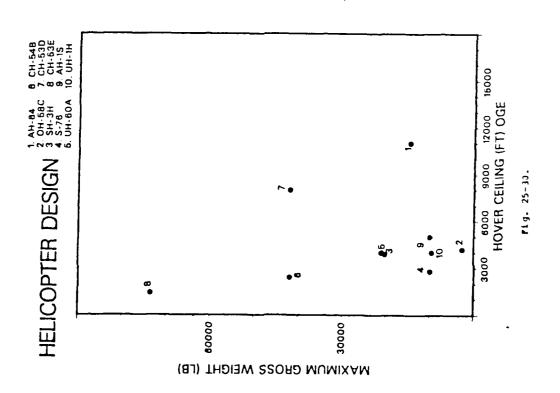
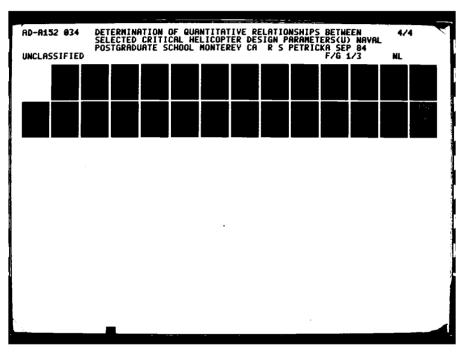


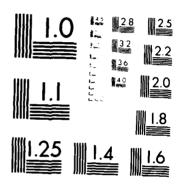
Fig. 25-27 and 25-28.



Pig. 25-30.

Length of Tail Pairings.





MICROCOPY RESOLUTION TEST CHART

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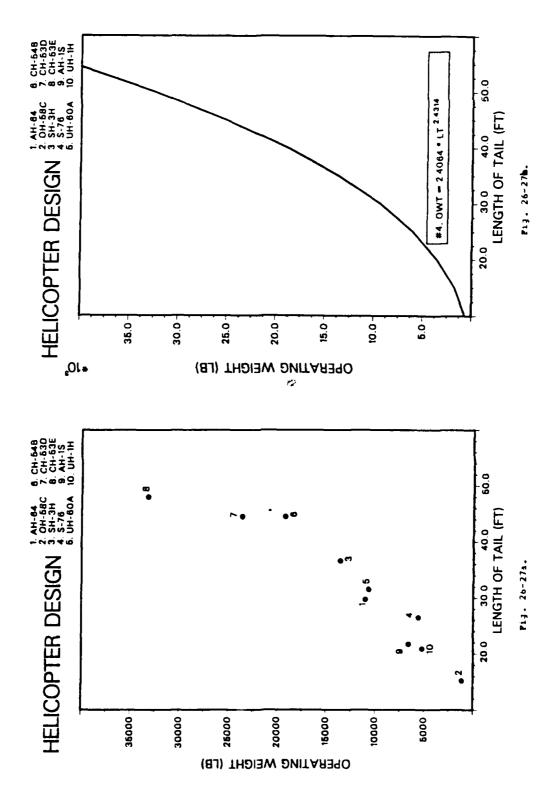


Fig. 20-27a and 26-27b.

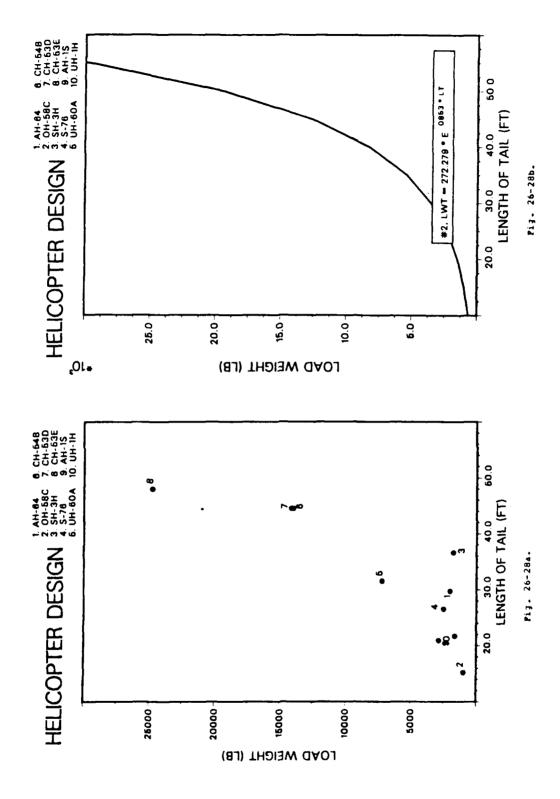


Fig. 20-28a and 26-28b.

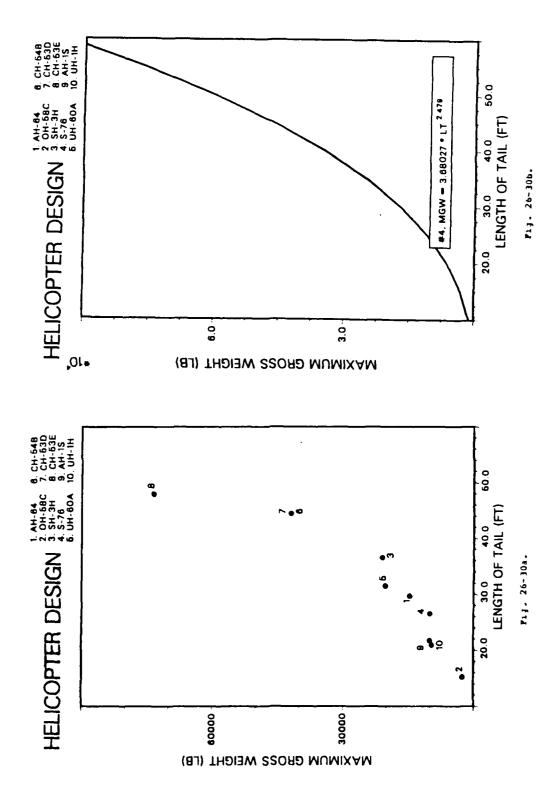


Fig. 20-30a and 26-30b.

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Operating Weight Pairings.

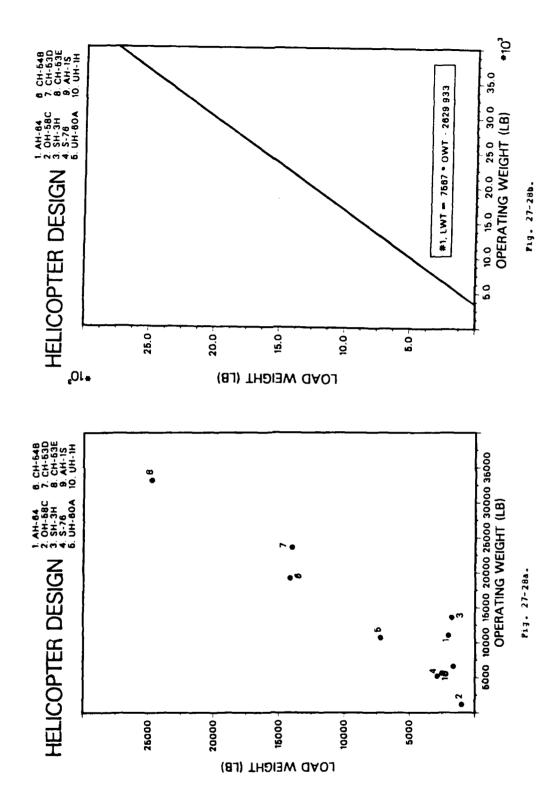


Fig. 27-28a and 27-28b.

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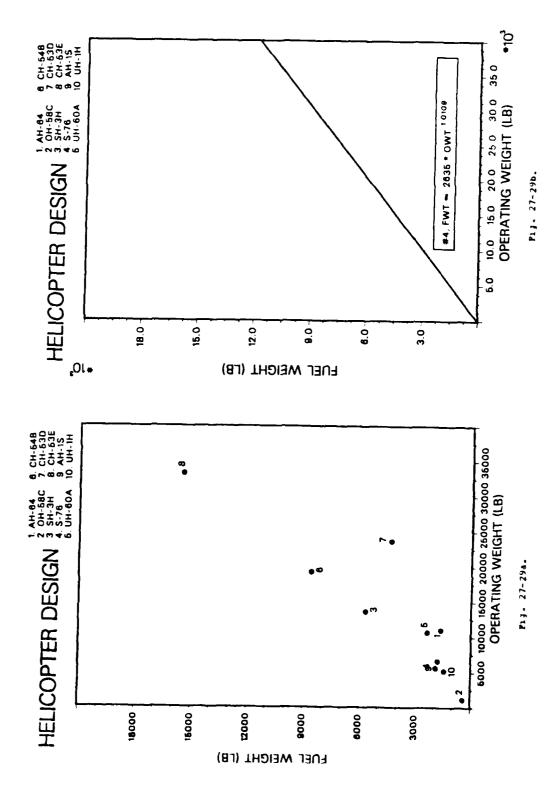
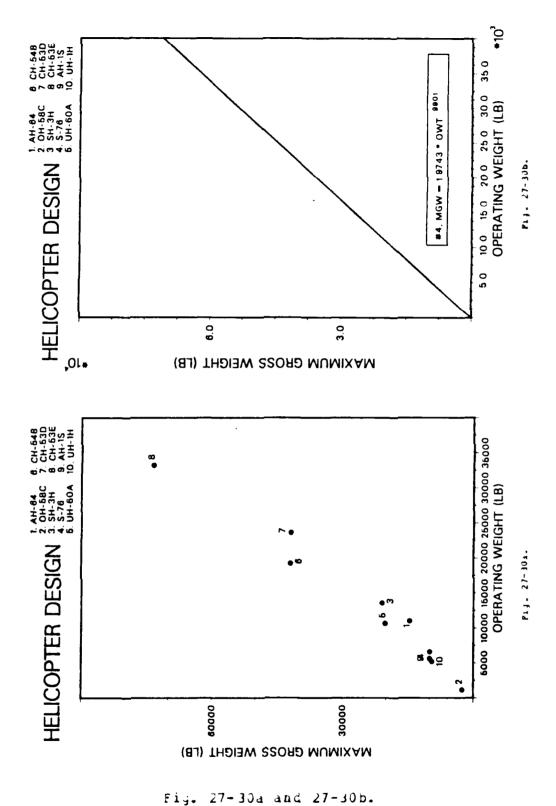


Fig. 27-29a and 27-29b.



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Load Weight Pairings.

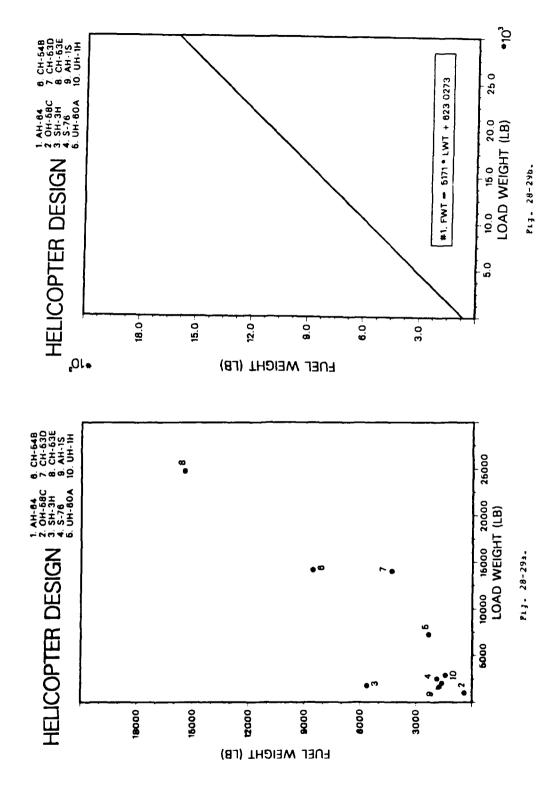


Fig. 28-29a and 28-29b.

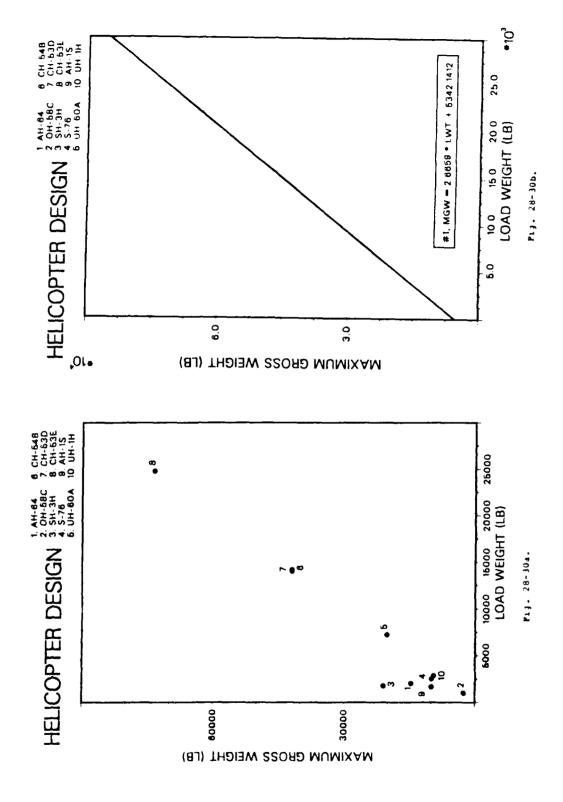
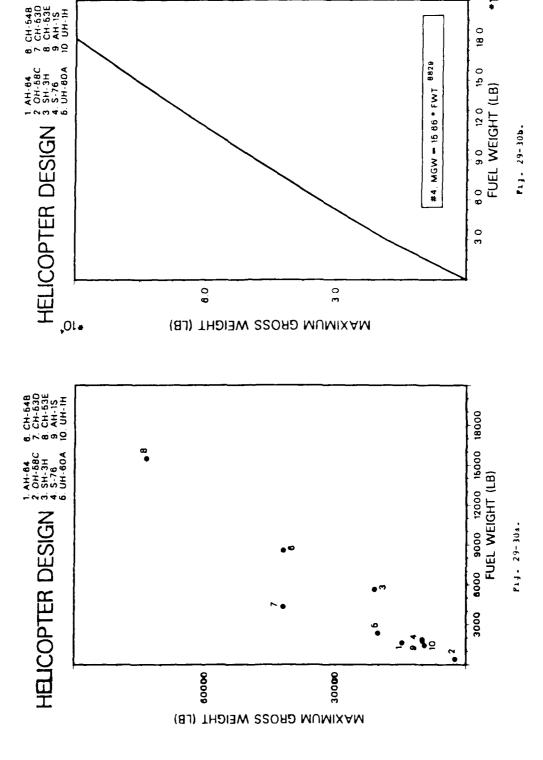


Fig. 28-30a and 28-30b.

Fuel Weight Pairings.

Fig. 29-30a and 29-30b.



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APPENDIX D

PORTRAM AND HEWLETT PACKARD COMPUTER PROGRAMS

A. 'CRVFIT' (DETERMINATION OF CURVE PIT EQUATIONS) HP PROGRAM

This program will determine a curve of best fit to a set of data points. The four standard curve types the program handles are:

1. Linear $y = b^*x + a$

2. Exponential $y = a^*e^{DX}$ (a>0)

3. Logarithmic $y = b^a Ln(x) + a$

4. Power $y = a^{a}x^{b}$ (a>0)

The program will compute the coefficients a and b in the equation of one of the above four curve types $% \left(1\right) =\left\{ 1\right\} =\left\{$

as well as compute a value $\,r^2\,$ called the coefficient of determination which is a measure of the goodness of filt. Once a set of data has been filt to a given curve type, a prediction may be made for the y-value given a new x-value, or a prediction may be made for the x-value given a new y-value. The functions available on the top row of keys on the keyboard are indicated in the following diagram.

These same functions are referenced in the examples and instructions by enclosing the name of the function on the key in square brackets [].

Example 1: Find the straight line which best fits the tollowing data: (1.1, 5.2), (4.5, 12.6), (8.0, 20.0), (10.0, 23.0), (15.6, 34.0) Then predict y when x=20 and predict x when y=25.

LOAD "CVF" PROS. Into the 41C and SIZE 027. GTO "CVF" and go into USER mode. This puts the program counter in ROM and makes the curve fit functions available on the top row of keys. Pressing [INITIALIZE] will initialize the program. This clears registers R11 thru R24 so that a new set of data may be entered. In this example the 5 data points will be entered using the [Σ +) key. Key in each pair as x ENTER! y and push [Σ +).

Do:		See:
[INITIALIZE] 1.1 ENTER 5.2 4.5 ENTER 12.6 8.0 ENTER 20.0	[[[[[[[[[[[[[[[[[[[1.0000 2.0000 3.0000 4.0000
10.0 ENTERT 23.0 15.6 ENTERT 34.0	[[]	5.0000 6.0000

All the data has now been entered and the parameters for the curve will be computed next. Since in this example we are interested in a straight line we key 1 (j=1) and push [SOLVE TYPE j]. When execution stops the values a, b, and r are available in the stack as:

Z:	r	and	ar e	8150	stored	85	RO8:	b	
Yı	8						R09:	8	
X:	b						R10:	r	

For this example:

Z: r=0.999035140. Y: a=3.499147270 X: b=1.972047542

The value r ranges between -1 and +1 and is a measure of how well the data fits the given curve type. The sign of r indicates whether the data is positively or negatively skewed. The closer r is to one of the extremes ± 1 the better the fit. For this example the line has positive slope and the fit is extremely good (all sample problems seem to work well).

Having computed the values b and a (these remain stored in R08 & R09 until new data is input) we can determine new points along the line. Key in 20 and push [\dot{y}] for the predicted y-value. \dot{y} =42.94009811 when x=20. Key in 25 and push [\dot{x}] for the predicted x-value, \dot{x} =10.90280649 when \dot{y} =25.

COMPLETE INSTRUCTIONS FOR "CVF"

(Keyboard Operation)

- 1) Key GTO $^{\rm H}$, SIZE 027 and go into USER mode. The keyboard functions should now be now available on the top row of keys.
- 2) Press [INITIALIZE] to initialize the program. This step clears data registers RI1 thru R24 inclusive. These registers will be used to accumulate the data for all tour curve types. The display will show 1.

- 3) Key in the next data pair (x,y) as $x \in NTER^{\frac{1}{2}} y$ and push $[\Sigma+]$. Repeat this step for all data pairs. The display will stop with a count of the number of the next data pair to be entered. This feature makes it possible to enter only the y-values when the x-values are consecutive integers which start counting from 1. In this case the display provides the x-values which need not be entered. If an improper data pair has just been input with the $[\Sigma+]$ key, then immediately pressing R/S will delete the pair. Otherwise an improper or undesired data pair can be deleted by re-entering both x and y and pressing $[\Sigma+]$.
- 4) As data pairs are entered it is possible that some x or y value is negative or zero. In these cases only one or two of the four curve types may be applied to the data. The four curve types and their respective equations are as follows:

Type J	Name		Equation		
1	Linear	•	- b*x + a		
2	Exponential	y	- a*e ^{bx}	(a>0)	
3	Logarithmic	y	= b*Ln(x)	+ a	
4	Power -	Y	- a-x ^b	(a>0)	

If any x-values are negative or zero then only types 1 & 2 are teasible curves. If any y-values are negative or zero then only types 1 & 3 are teasible curves. If in any data pair both x and y are negative or zero then type 1 is the only teasible curve. The a coefficient must be positive for curve types 2 and 4.

- 5) After all data pairs have been input the next step is to select the desired curve type. This step can be accomplished in one of two ways. Under either option, the 41C should not be interrupted or else there is a possibility that the data registers will not be returned with their normal contents.
- a) To fit a particular curve type, key in the number 1-4 for that type and press [SOLYE TYPE j]. The stack returns with:
- Z: r and these parameters R07: J=curve type
 Y: a remain stored in R08: b
 X: b R09: a
 R10: r

Step a) may be repeated at any time for any of the four curve types.

b) If all data input is positive then pressing [SOLVE BEST] will automatically choose the curve of best fit according to the curve type with largest absolute value of r. In this case the stack returns with:

T: r and these parameters
Z: a remain stored in R08: b
Y: b R09: a
X: j=best curve type R10: r

6) Predictions for new x or y values may be made only after step 5) has been completed. Predictions for new values are based on the settings of flags F08 and F09 which are automatically set during the fit process in step 5). The status of flags 8 and 9 for the four curve types are as follows.

		riag a	F183 9
1	Linear	clear	clear
2	Exponential	set	clear
3	Logarithmic	clear	set
4	Power	set	set

in general the user need not be concerned with these flag settings, and FOB and FOB are not available for other use and must not be disturbed. To predict y given x, key in x and press [\hat{y}]. To predict x given y, key in y and press [\hat{x}]. In both cases the predicted value is left in the X-register.

7) New data may be added or deleted at any time via the [Σ +] or [Σ -] keys. However, step 5) must be performed after updating the data before any new predictions can be made using step 6). The parameters e and b are automatically destroyed after input of new data.

01+LBL *CVF*	51 GTO 0 6	101 ST- 07	151 EtX
03 XEQ e	52◆LBL B	102 RCL 10	152 RTN
03 GTO IND 06	53•LBL 02	103 RCL 09	153+LBL D
A4+LBL A	54 CF 08	194 FS? 08	154+LBL 04
95+LBL 91	55 CF 0 9	105 EtX	155 FS? 08
86 CF 18	56 STO 07	106 STO 09	156 LN
07+LBL 06	57 2	197 RCL 98	157 RCL 09
08 STO 09	58 X(Y?	108 RTN	158 FS? 98
09 X(>Y	59 SF 09	109+LBL 10	159 LN
10 STO 08	60 /	110 RCL 11	160 -
11 EREG 13	61 FRC	111 X(> 17	161 RCL 08
12 FC2 18	62 X=0?	112 STO 11	162 /
13 Σ+	63 SF 08	113+LBL 13	163 FS2 89
14 FS? 10	64 8	114 RCL 21	164 EtX
15 Σ-	65 ST+ 0 7	115 X(> 15	165 RTN
16 RDN	66 XEQ IND 07	116 STO 21	166+LBL e
17 RCL 88	67 RCL 17	117 RCL 22	167+LBL 00
18 ENTERT	68 RCL 13	118 X(> 16	168 CLRG
19 X>0?	69 RCL 15	119 STO 22	169 SF 27
20 LN	70 STO 09	120+LBL 09	170 E
21 ST+ Z	71 *	121 RTN	171 RTN
22 RCL 09	72 RCL 18	122+LBL 11	172+LBL E
23 X>8?	73 /	123 RCL 12	173+LBL 05
24 LN	74 -	124 X(> 17	174 .
25 ST+ Z	75 STO 10	125 STO 12	175 STO 25
26 X()Y	76 RCL 14	126+LBL 14	176 4
27 ZREG 19	77 RCL 13	127 RCL 19	177 STO 97
28 FC? 10	78 X 1 2	128 X(> 13	178+LBL 97
29 Σ+	79 RCL 18	129 STO 19	179 RCL 07
30 FS? 10	80 /	130 RCL 20	189 XEQ B
31 Σ-	81 -	131 X() 14	
32 Rt	82 STO Z	132 STO 20	181 RCL 25
33 FS2 18	83 /	133 RTH	182 RCL 18
34 CHS	84 STO 0 8	134+LBL 12	183 ABS
35 ST+ 12	85 RCL 13	135 RCL 23	184 X<=Y?
36 Rt	86 ◆	136 X() 17	185 GTO 15
37 FS2 19	87 ST- 0 9	137 STO 23	186 STO 25
38 CHS	88 X<>Y	138 XEQ 14	187 RCL 07
39 ST+ 11	89 RCL 16	139 GTO 13	188 STO 26
49 X<> Z	90 RCL 15	140+LBL C	189+LBL 15
41 SIGN	91 X†2	141+LBL 83	190 BSE 07
42 ST+ L	92 RCL 18	142 FS? 09	191 GTO 0 7
43 RCL 08	93 ST/ 89	143 LH	192 RCL 26
44 RCL 09	94 /	144 RCL 08	193 XEQ 02
45 X() L	95 -	145 *	194 RCL 26
46 RTN	96 *	146 RCL 89	195 .END.
47 RCL 08	97 SQRT	147 FS? 68	
48 RCL 09	98 ST/ 10	148 LN	
49+LBL a	99 XEQ IND 07	149 +	
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B. 'CBVFIT' (GRAPHING OF CURVE FITS) FORTRAN PROGRAM

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7. CH-5308
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